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# **py-pde Documentation**

***Release 0.18.0***

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The *py-pde* python package provides methods and classes useful for solving partial differential equations (PDEs) of the form

$$\partial_t u(\mathbf{x}, t) = \mathcal{D}[u(\mathbf{x}, t)] + \eta(u, \mathbf{x}, t) ,$$

where  $\mathcal{D}$  is a (non-linear) differential operator that defines the time evolution of a (set of) physical fields  $u$  with possibly tensorial character, which depend on spatial coordinates  $\mathbf{x}$  and time  $t$ . The framework also supports stochastic differential equations in the Itô representation, where the noise is represented by  $\eta$  above.

The main audience for the package are researchers and students who want to investigate the behavior of a PDE and get an intuitive understanding of the role of the different terms and the boundary conditions. To support this, *py-pde* evaluates PDEs using the methods of lines with a finite-difference approximation of the differential operators. Consequently, the mathematical operator  $\mathcal{D}$  can be naturally translated to a function evaluating the evolution rate of the PDE.

## Contents



## GETTING STARTED

This *py-pde* package is developed for python 3.7+ and should run on all common platforms. The code is tested under Linux, Windows, and macOS.

### 1.1 Install using pip

The package is available on [pypi](#), so you should be able to install it by running

```
pip install py-pde
```

In order to have all features of the package available, you might also want to install the following optional packages:

```
pip install h5py pandas pyfftw tqdm
```

Moreover, **ffmpeg** needs to be installed and for creating movies.

### 1.2 Install using conda

The *py-pde* package is also available on [conda](#) using the *conda-forge* channel. You can thus install it using

```
conda install -c conda-forge py-pde
```

This installation includes all required dependencies to have all features of *py-pde*.

### 1.3 Install from source

Installing from source can be necessary if the pypi installation does not work or if the latest source code should be installed from [github](#).

### 1.3.1 Required prerequisites

The code builds on other python packages, which need to be installed for *py-pde* to function properly. The required packages are listed in the table below:

Package	Minimal version	Usage
matplotlib	3.1	Visualizing results
numba	0.50	Just-in-time compilation to accelerate numerics
numpy	1.18	Handling numerical data
scipy	1.4	Miscellaneous scientific functions
sympy	1.5	Dealing with user-defined mathematical expressions

The simplest way to install these packages is to use the `requirements.txt` in the base folder:

```
pip install -r requirements.txt
```

Alternatively, these package can be installed via your operating system's package manager, e.g. using **macports**, **homebrew**, or **conda**. The package versions given above are minimal requirements, although this is not tested systematically. Generally, it should help to install the latest version of the package.

### 1.3.2 Optional packages

The following packages should be installed to use some miscellaneous features:

Package	Usage
h5py	Storing data in the hierarchical file format
ipywidgets	Jupyter notebook support
napari	Displaying images interactively
pandas	Handling tabular data
pyfftw	Faster Fourier transforms
tqdm	Display progress bars during calculations

For making movies, the **ffmpeg** should be available. Additional packages might be required for running the tests in the folder `tests` and to build the documentation in the folder `docs`. These packages are listed in the files `requirements.txt` in the respective folders.

### 1.3.3 Downloading *py-pde*

The package can be simply checked out from [github.com/zwicker-group/py-pde](https://github.com/zwicker-group/py-pde). To import the package from any python session, it might be convenient to include the root folder of the package into the `PYTHONPATH` environment variable.

This documentation can be built by calling the **make html** in the `docs` folder. The final documentation will be available in `docs/build/html`. Note that a LaTeX documentation can be build using **make latexpdf**.

## 1.4 Package overview

The main aim of the *pde* package is to simulate partial differential equations in simple geometries. Here, the time evolution of a PDE is determined using the method of lines by explicitly discretizing space using fixed grids. The differential operators are implemented using the *finite difference method*. For simplicity, we consider only regular, orthogonal grids, where each axis has a uniform discretization and all axes are (locally) orthogonal. Currently, we support simulations on *CartesianGrid*, *PolarSymGrid*, *SphericalSymGrid*, and *CylindricalSymGrid*, with and without periodic boundaries where applicable.

Fields are defined by specifying values at the grid points using the classes *ScalarField*, *VectorField*, and *Tensor2Field*. These classes provide methods for applying differential operators to the fields, e.g., the result of applying the Laplacian to a scalar field is returned by calling the method *laplace()*, which returns another instance of *ScalarField*, whereas *gradient()* returns a *VectorField*. Combining these functions with ordinary arithmetics on fields allows to represent the right hand side of many partial differential equations that appear in physics. Importantly, the differential operators work with flexible boundary conditions.

The PDEs to solve are represented as a separate class inheriting from *PDEBase*. One example defined in this package is the diffusion equation implemented as *DiffusionPDE*, but more specific situations need to be implemented by the user. Most notably, PDEs can be specified by their expression using the convenient *PDE* class.

The PDEs are solved using solver classes, where a simple explicit solver is implemented by *ExplicitSolver*, but more advanced implementations can be done. To obtain more details during the simulation, trackers can be attached to the solver instance, which analyze intermediate states periodically. Typical trackers include *ProgressTracker* (display simulation progress), *PlotTracker* (display images of the simulation), and *SteadyStateTracker* (aborting simulation when a stationary state is reached). Others can be found in the *trackers* module. Moreover, we provide *MemoryStorage* and *FileStorage*, which can be used as trackers to store the intermediate state to memory and to a file, respectively.

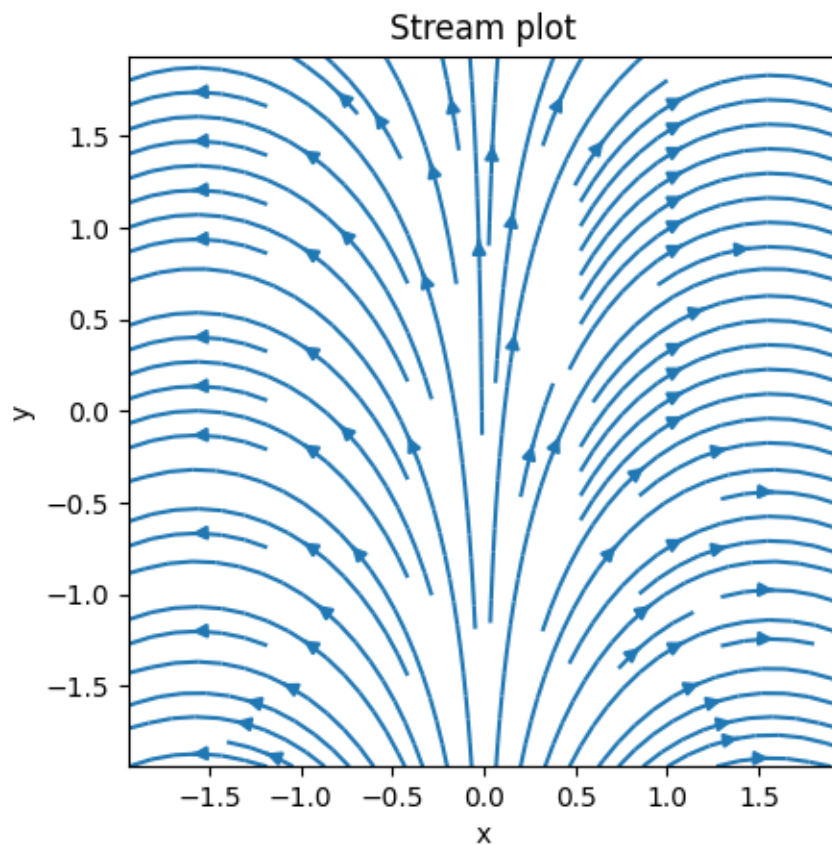


## EXAMPLES

These are example scripts using the *py-pde* package, which illustrates some of the most important features of the package.

## 2.1 Plotting a vector field

This example shows how to initialize and visualize the vector field  $\mathbf{u} = (\sin(x), \cos(x))$ .



```
from pde import CartesianGrid, VectorField  
grid = CartesianGrid([[-2, 2], [-2, 2]], 32)
```

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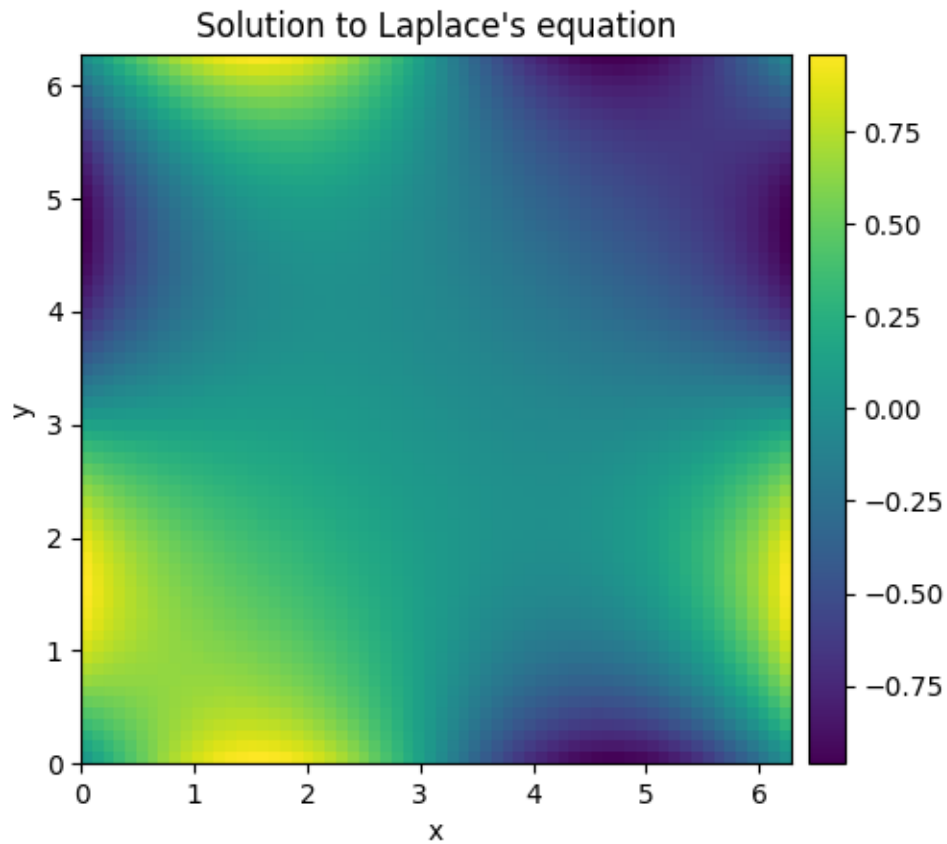
(continued from previous page)

```
field = VectorField.from_expression(grid, ["sin(x)", "cos(x)"])
field.plot(method="streamplot", title="Stream plot")
```

**Total running time of the script:** ( 0 minutes 0.823 seconds)

## 2.2 Solving Laplace's equation in 2d

This example shows how to solve a 2d Laplace equation with spatially varying boundary conditions.



```
import numpy as np

from pde import CartesianGrid, solve_laplace_equation

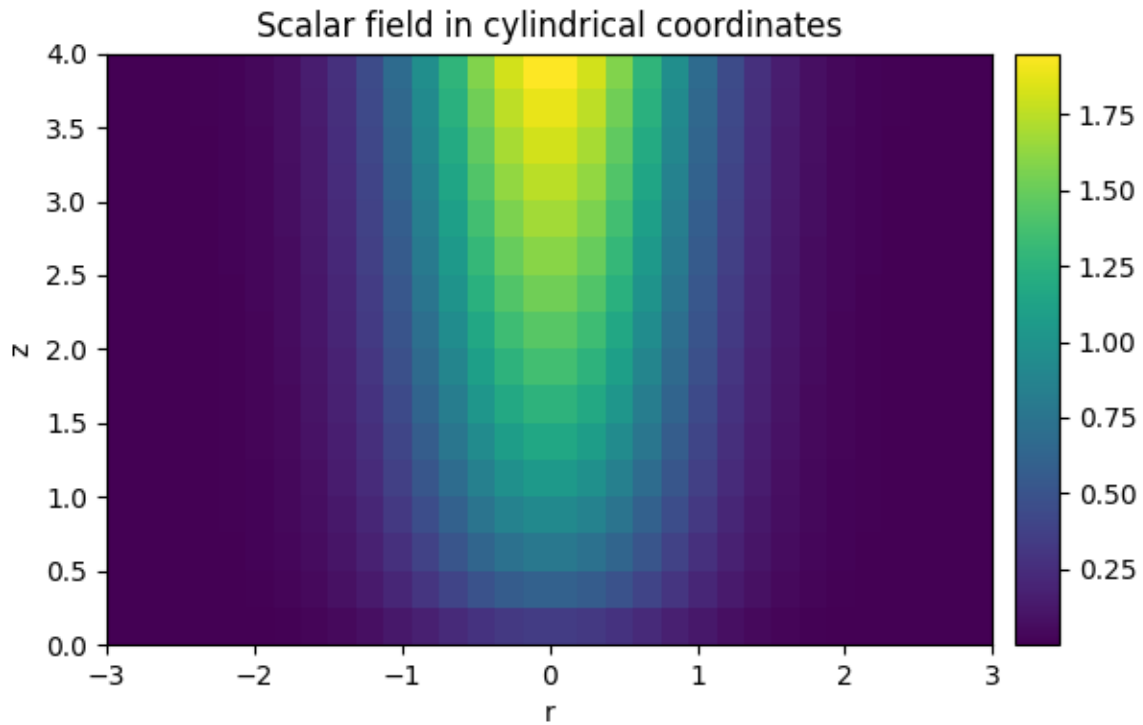
grid = CartesianGrid([0, 2 * np.pi] * 2, 64)
bcs = [{"value": "sin(y)"}, {"value": "sin(x)"}]

res = solve_laplace_equation(grid, bcs)
res.plot()
```

**Total running time of the script:** ( 0 minutes 1.416 seconds)

## 2.3 Plotting a scalar field in cylindrical coordinates

This example shows how to initialize and visualize the scalar field  $u = \sqrt{z} \exp(-r^2)$  in cylindrical coordinates.



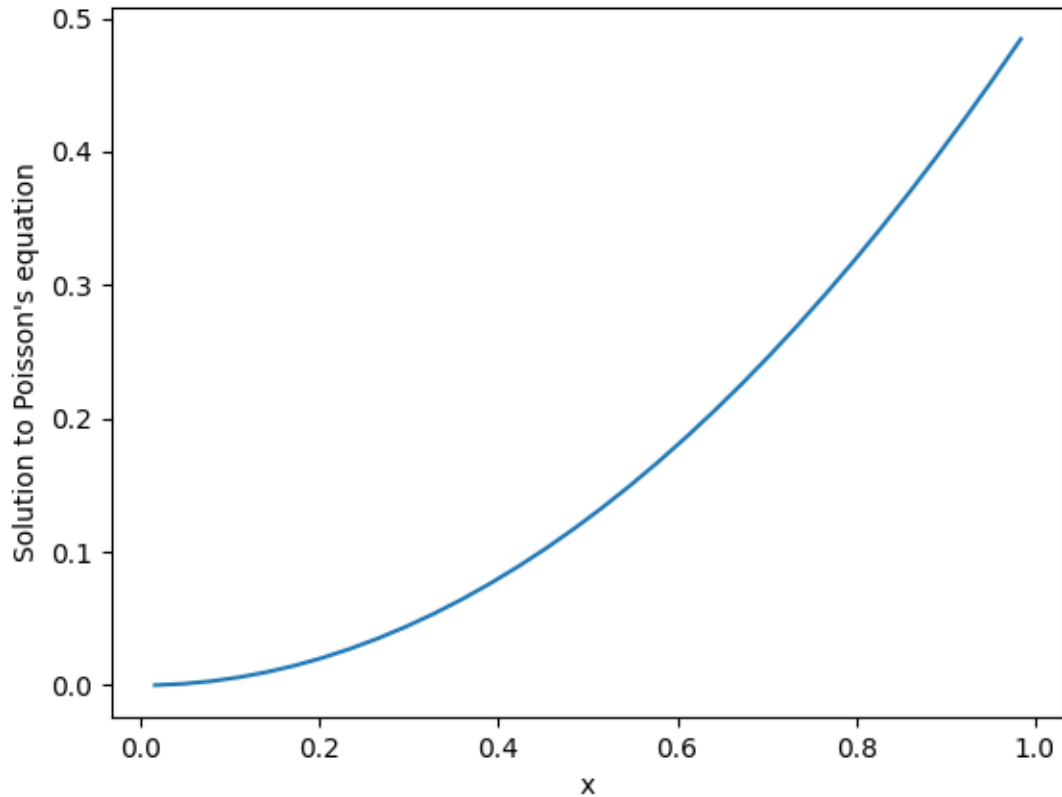
```
from pde import CylindricalSymGrid, ScalarField

grid = CylindricalSymGrid(radius=3, bounds_z=[0, 4], shape=16)
field = ScalarField.from_expression(grid, "sqrt(z) * exp(-r**2)")
field.plot(title="Scalar field in cylindrical coordinates")
```

**Total running time of the script:** ( 0 minutes 0.446 seconds)

## 2.4 Solving Poisson's equation in 1d

This example shows how to solve a 1d Poisson equation with boundary conditions.



```
from pde import CartesianGrid, ScalarField, solve_poisson_equation

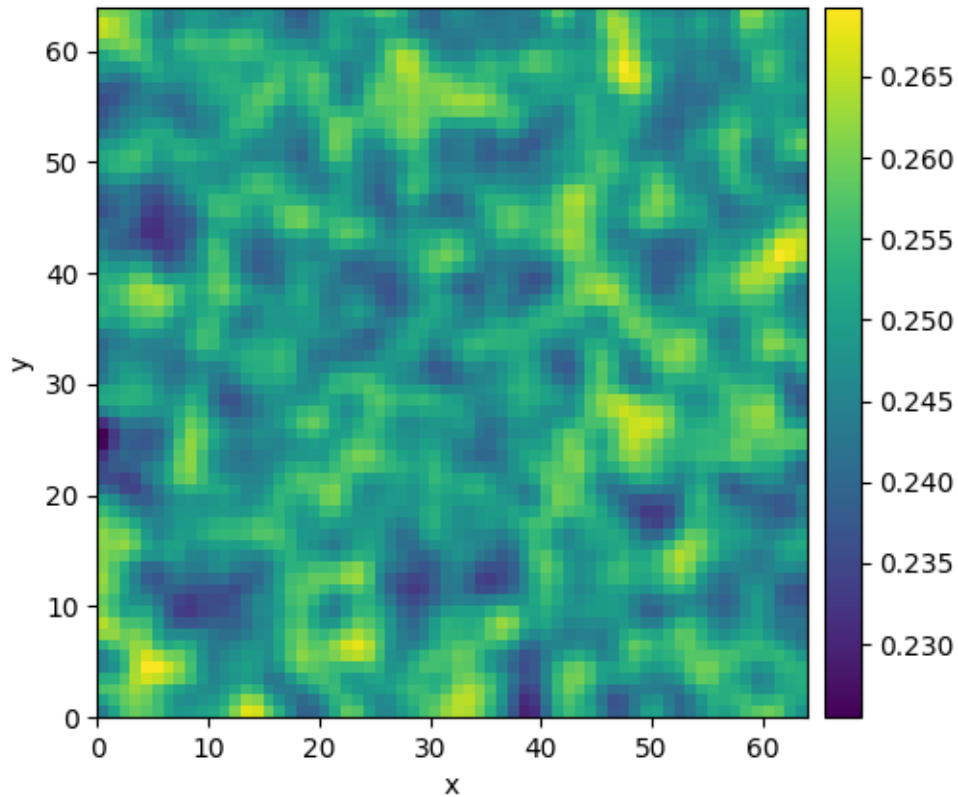
grid = CartesianGrid([[0, 1]], 32, periodic=False)
field = ScalarField(grid, 1)
result = solve_poisson_equation(field, bc=[{"value": 0}, {"derivative": 1}])

result.plot()
```

**Total running time of the script:** ( 0 minutes 0.101 seconds)

## 2.5 Simple diffusion equation

This example solves a simple diffusion equation in two dimensions.



Out:

```

0%|          | 0/10.0 [00:00<?, ?it/s]
Initializing: 0%|          | 0/10.0 [00:00<?, ?it/s]
0%|          | 0/10.0 [00:12<?, ?it/s]
0%|          | 0.00316/10.0 [00:12<10:56:16, 3938.93s/it]
1%|          | 0.05328/10.0 [00:12<38:44, 233.72s/it]
7%|7        | 0.73076/10.0 [00:12<02:38, 17.05s/it]
7%|7        | 0.73076/10.0 [00:12<02:38, 17.06s/it]
100%|#####| 10.0/10.0 [00:12<00:00, 1.25s/it]
100%|#####| 10.0/10.0 [00:12<00:00, 1.25s/it]

```

```

from pde import DiffusionPDE, ScalarField, UnitGrid

grid = UnitGrid([64, 64]) # generate grid
state = ScalarField.random_uniform(grid, 0.2, 0.3) # generate initial condition

```

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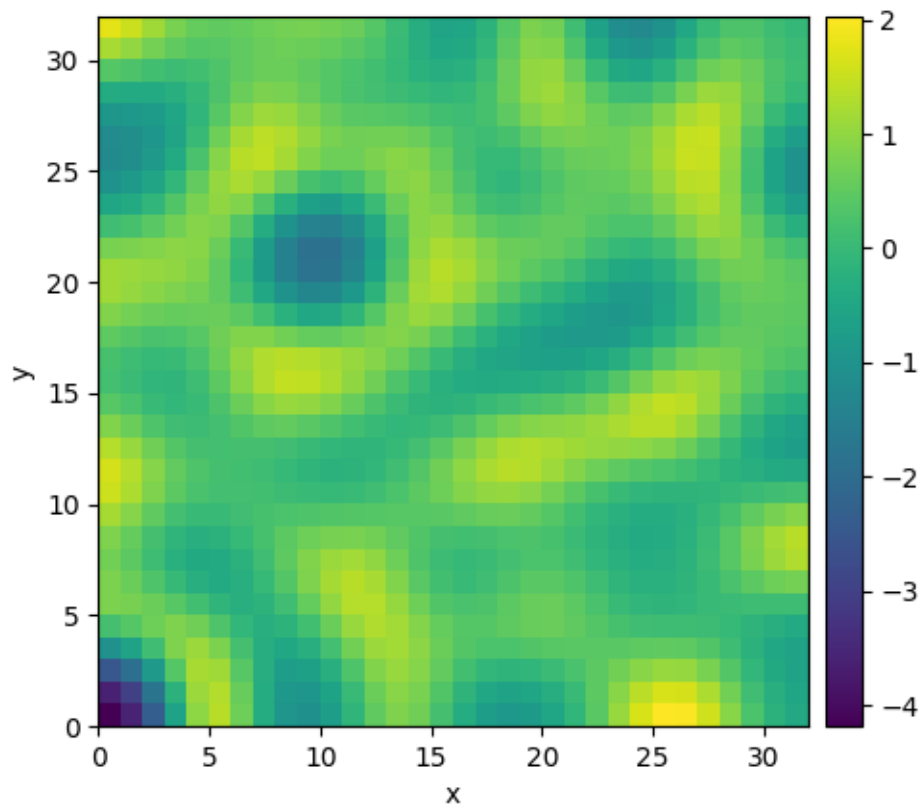
```
eq = DiffusionPDE(diffusivity=0.1) # define the pde
result = eq.solve(state, t_range=10)
result.plot()
```

**Total running time of the script:** ( 0 minutes 12.682 seconds)

## 2.6 Kuramoto-Sivashinsky - Using *PDE* class

This example implements a scalar PDE using the *PDE*. We here consider the Kuramoto–Sivashinsky equation, which for instance describes the dynamics of flame fronts:

$$\partial_t u = -\frac{1}{2}|\nabla u|^2 - \nabla^2 u - \nabla^4 u$$



Out:

```
0%|          | 0/10.0 [00:00<?, ?it/s]
Initializing: 0%|          | 0/10.0 [00:00<?, ?it/s]
0%|          | 0/10.0 [00:12<?, ?it/s]
0%|          | 0.01/10.0 [00:25<7:02:28, 2537.42s/it]
0%|          | 0.02/10.0 [00:28<3:54:09, 1407.80s/it]
```

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```

0%|          | 0.03/10.0 [00:28<2:35:57, 938.55s/it]
1%|1         | 0.1/10.0 [00:28<46:27, 281.57s/it]
44%|#####4  | 4.43/10.0 [00:28<00:35, 6.36s/it]
44%|#####4  | 4.43/10.0 [00:28<00:35, 6.36s/it]
100%|#####  | 10.0/10.0 [00:28<00:00, 2.82s/it]
100%|#####  | 10.0/10.0 [00:28<00:00, 2.82s/it]

```

```

from pde import PDE, ScalarField, UnitGrid

grid = UnitGrid([32, 32]) # generate grid
state = ScalarField.random_uniform(grid) # generate initial condition

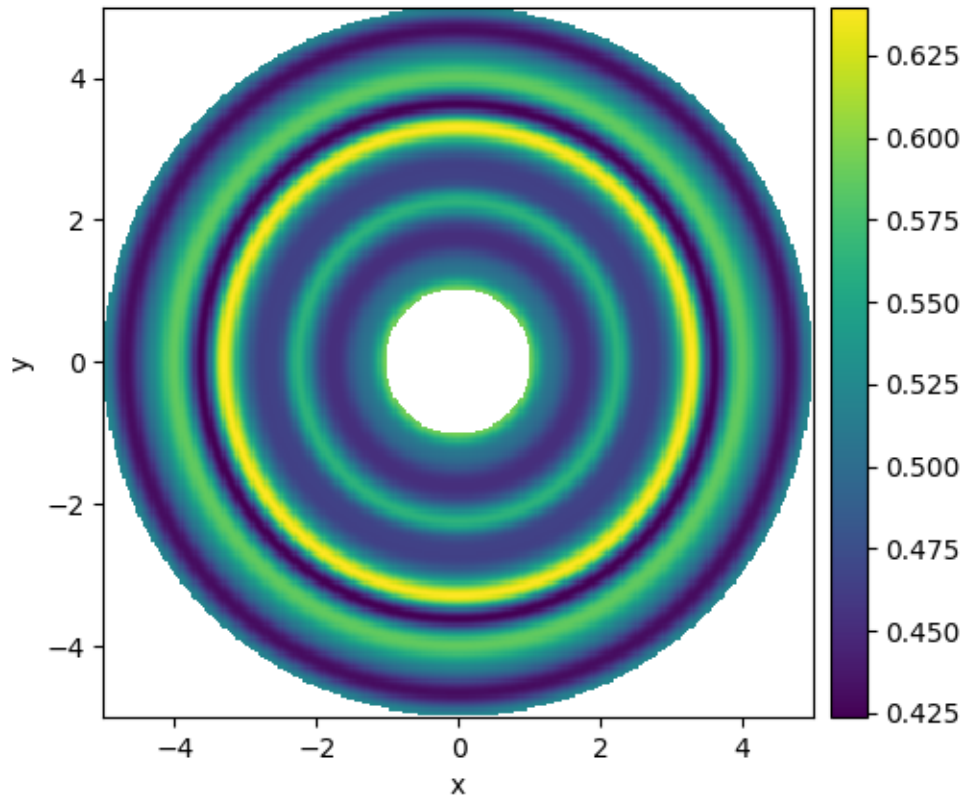
eq = PDE({"u": "-gradient_squared(u) / 2 - laplace(u + laplace(u))"}) # define the
↪pde
result = eq.solve(state, t_range=10, dt=0.01)
result.plot()

```

**Total running time of the script:** ( 0 minutes 28.369 seconds)

## 2.7 Spherically symmetric PDE

This example illustrates how to solve a PDE in a spherically symmetric geometry.



Out:

```

 0%|          | 0/0.1 [00:00<?, ?it/s]
Initializing: 0%|          | 0/0.1 [00:00<?, ?it/s]
 0%|          | 0/0.1 [00:02<?, ?it/s]
 6%|6         | 0.006/0.1 [00:03<00:52, 556.63s/it]
15%|#5        | 0.015/0.1 [00:03<00:21, 250.84s/it]
28%|##8       | 0.028/0.1 [00:03<00:09, 134.39s/it]
28%|##8       | 0.028/0.1 [00:03<00:09, 134.41s/it]
100%|#####| 0.1/0.1 [00:03<00:00, 37.64s/it]
100%|#####| 0.1/0.1 [00:03<00:00, 37.64s/it]

```

```

from pde import DiffusionPDE, ScalarField, SphericalSymGrid

grid = SphericalSymGrid(radius=[1, 5], shape=128) # generate grid
state = ScalarField.random_uniform(grid) # generate initial condition

eq = DiffusionPDE(0.1) # define the PDE
result = eq.solve(state, t_range=0.1, dt=0.001)

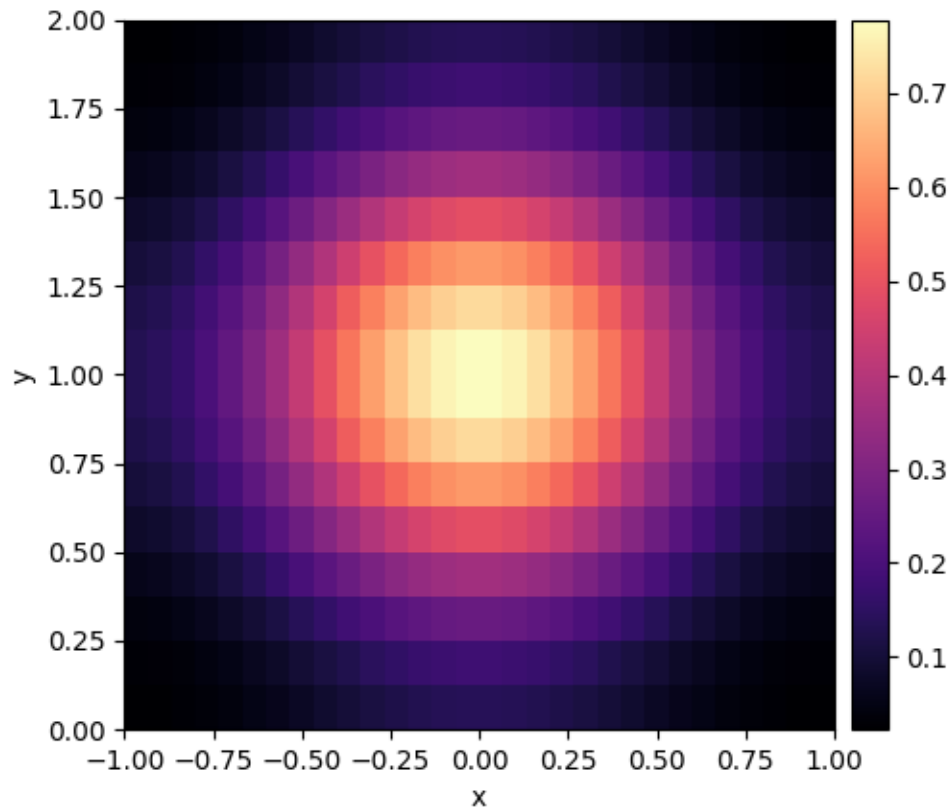
result.plot(kind="image")

```

Total running time of the script: ( 0 minutes 4.340 seconds)

## 2.8 Diffusion on a Cartesian grid

This example shows how to solve the diffusion equation on a Cartesian grid.



Out:

```

 0%|          | 0/1.0 [00:00<?, ?it/s]
Initializing: 0%|          | 0/1.0 [00:00<?, ?it/s]
 0%|          | 0/1.0 [00:06<?, ?it/s]
 1%|1         | 0.01/1.0 [00:07<12:45, 773.20s/it]
 2%|2         | 0.02/1.0 [00:08<07:12, 441.26s/it]
 3%|3         | 0.03/1.0 [00:08<04:45, 294.18s/it]
27%|##7       | 0.27/1.0 [00:08<00:23, 32.69s/it]
27%|##7       | 0.27/1.0 [00:08<00:23, 32.69s/it]
100%|#####| 1.0/1.0 [00:08<00:00, 8.83s/it]
100%|#####| 1.0/1.0 [00:08<00:00, 8.83s/it]

```

```

from pde import CartesianGrid, DiffusionPDE, ScalarField

grid = CartesianGrid([[-1, 1], [0, 2]], [30, 16]) # generate grid
state = ScalarField(grid) # generate initial condition
state.insert([0, 1], 1)

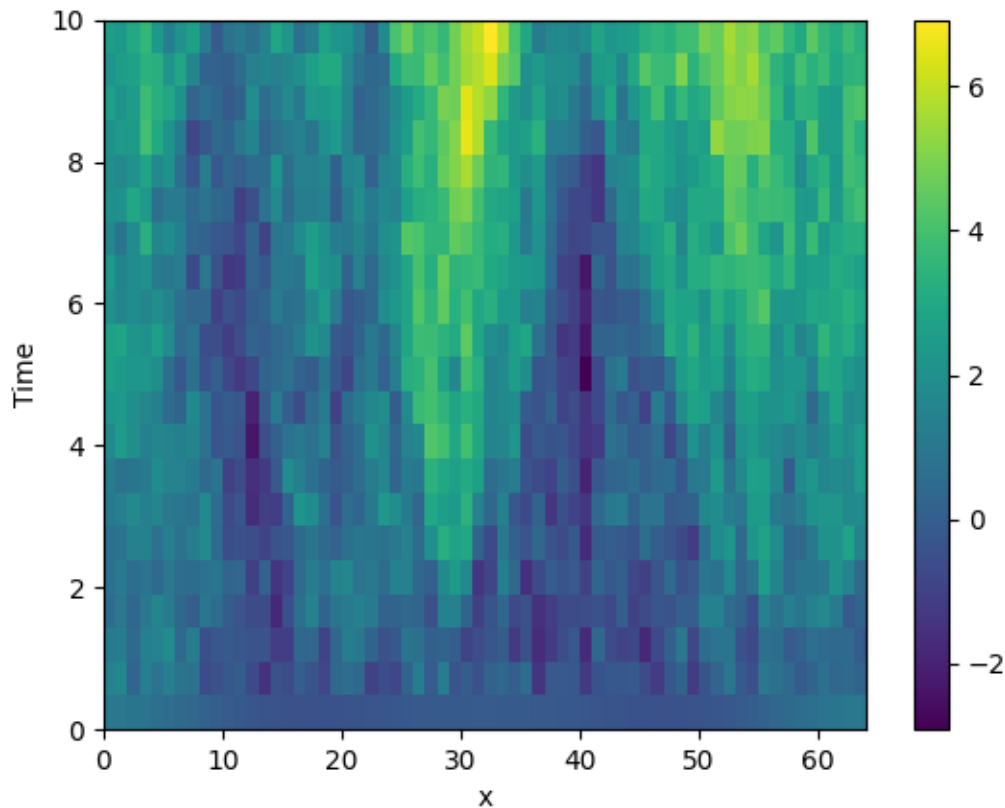
eq = DiffusionPDE(0.1) # define the pde
result = eq.solve(state, t_range=1, dt=0.01)
result.plot(cmap="magma")

```

**Total running time of the script:** ( 0 minutes 8.993 seconds)

## 2.9 Stochastic simulation

This example illustrates how a stochastic simulation can be done.



```

from pde import KPZInterfacePDE, MemoryStorage, ScalarField, UnitGrid, plot_kymograph

grid = UnitGrid([64]) # generate grid
state = ScalarField.random_harmonic(grid) # generate initial condition

eq = KPZInterfacePDE(noise=1) # define the SDE
storage = MemoryStorage()

```

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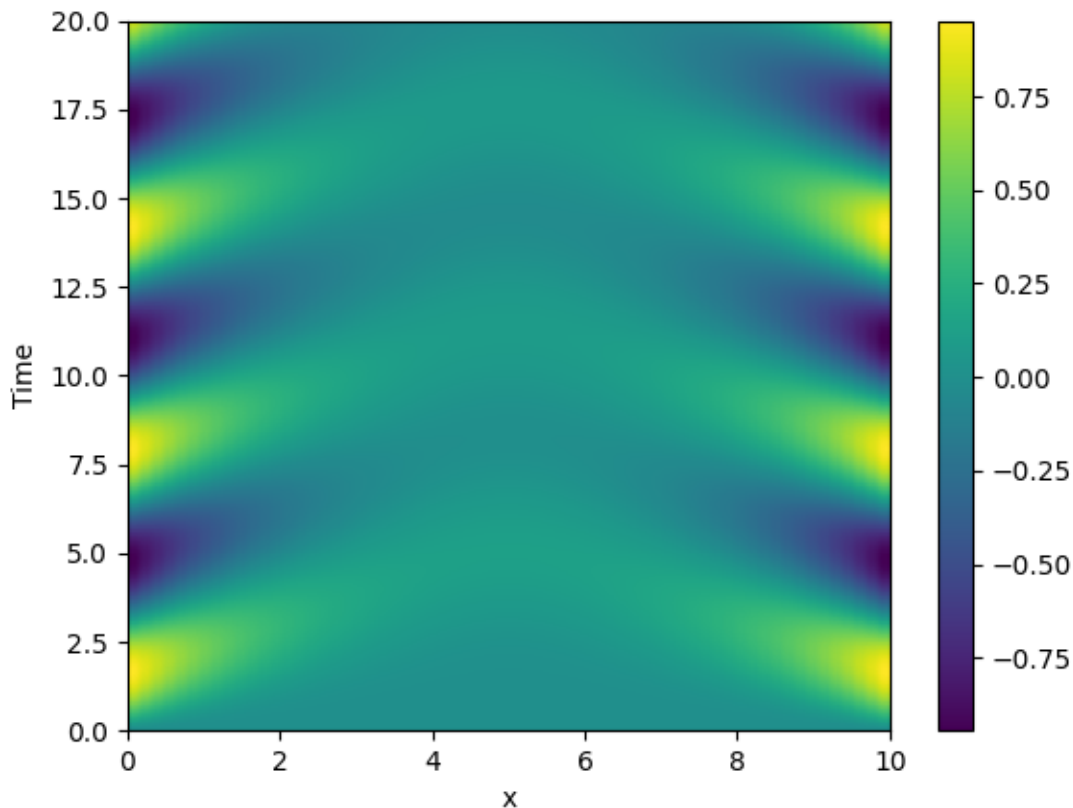
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```
eq.solve(state, t_range=10, dt=0.01, tracker=storage.tracker(0.5))
plot_kymograph(storage)
```

**Total running time of the script:** ( 0 minutes 8.275 seconds)

## 2.10 Time-dependent boundary conditions

This example solves a simple diffusion equation in one dimensions with time-dependent boundary conditions.



```
from pde import PDE, CartesianGrid, MemoryStorage, ScalarField, plot_kymograph

grid = CartesianGrid([[0, 10]], [64]) # generate grid
state = ScalarField(grid) # generate initial condition

eq = PDE({"c": "laplace(c)"}, bc={"value_expression": "sin(t)"})

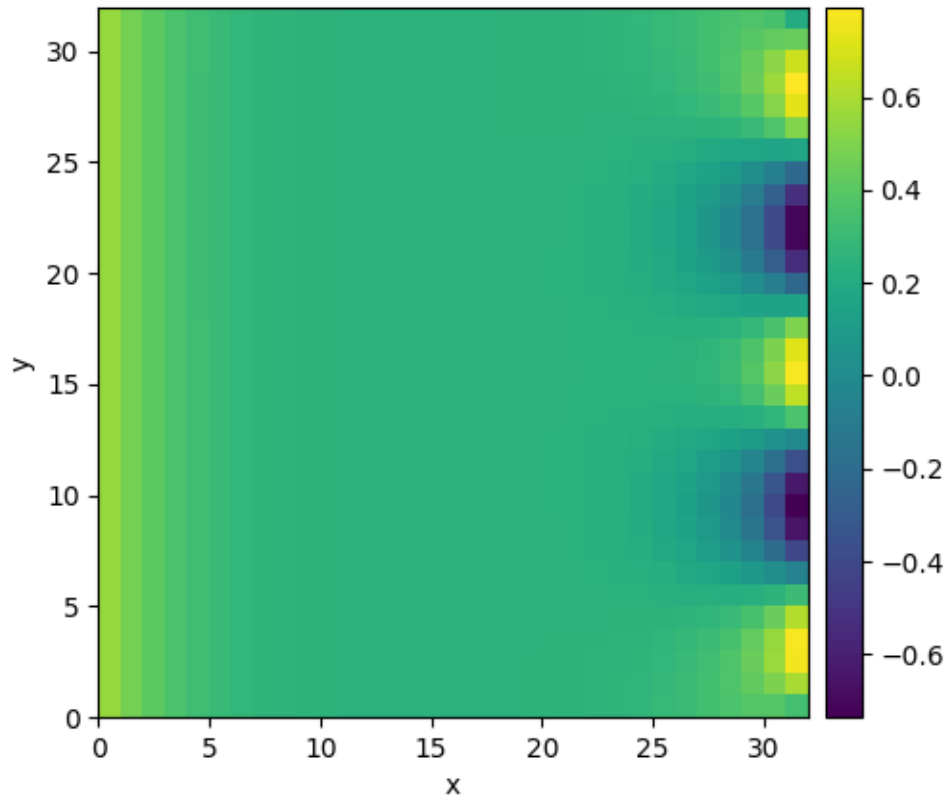
storage = MemoryStorage()
eq.solve(state, t_range=20, dt=1e-4, tracker=storage.tracker(0.1))

# plot the trajectory as a space-time plot
plot_kymograph(storage)
```

**Total running time of the script:** ( 0 minutes 5.958 seconds)

## 2.11 Setting boundary conditions

This example shows how different boundary conditions can be specified.



Out:

```

 0%|          | 0/10.0 [00:00<?, ?it/s]
Initializing: 0%|          | 0/10.0 [00:00<?, ?it/s]
 0%|          | 0/10.0 [00:07<?, ?it/s]
 0%|          | 0.005/10.0 [00:08<4:31:39, 1630.76s/it]
 0%|          | 0.01/10.0 [00:09<2:31:54, 912.35s/it]
 0%|          | 0.015/10.0 [00:09<1:41:13, 608.26s/it]
 2%|2        | 0.25/10.0 [00:09<05:55, 36.50s/it]
 2%|2        | 0.25/10.0 [00:09<05:56, 36.55s/it]
100%|#####| 10.0/10.0 [00:09<00:00, 1.09it/s]
100%|#####| 10.0/10.0 [00:09<00:00, 1.09it/s]

```

```

from pde import DiffusionPDE, ScalarField, UnitGrid

grid = UnitGrid([32, 32], periodic=[False, True]) # generate grid

```

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```

state = ScalarField.random_uniform(grid, 0.2, 0.3) # generate initial condition

# set boundary conditions `bc` for all axes
bc_x_left = {"derivative": 0.1}
bc_x_right = {"value": "sin(y / 2)"}
bc_x = [bc_x_left, bc_x_right]
bc_y = "periodic"
eq = DiffusionPDE(bc=[bc_x, bc_y])

result = eq.solve(state, t_range=10, dt=0.005)
result.plot()

```

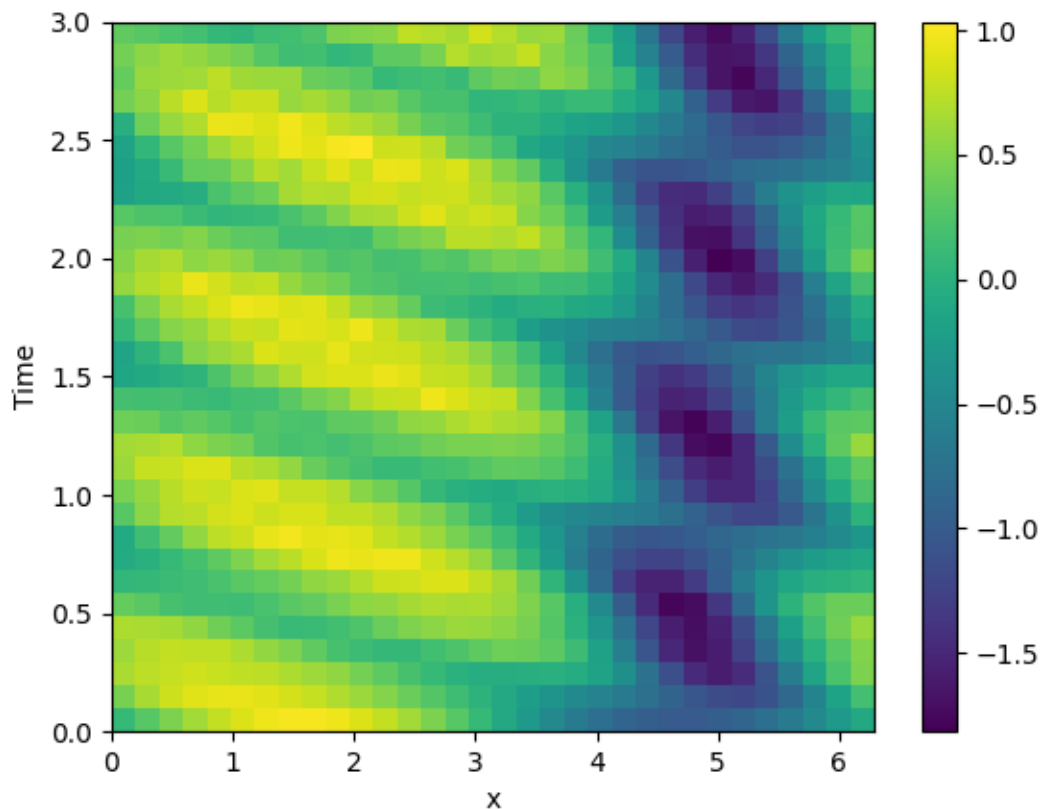
**Total running time of the script:** ( 0 minutes 9.293 seconds)

## 2.12 1D problem - Using *PDE* class

This example implements a PDE that is only defined in one dimension. Here, we chose the Korteweg-de Vries equation, given by

$$\partial_t \phi = 6\phi \partial_x \phi - \partial_x^3 \phi$$

which we implement using the *PDE*.



```

from math import pi

from pde import PDE, CartesianGrid, MemoryStorage, ScalarField, plot_kymograph

# initialize the equation and the space
eq = PDE({"ψ": "6 * ψ * d_dx(ψ) - laplace(d_dx(ψ))"})
grid = CartesianGrid([[0, 2 * pi]], [32], periodic=True)
state = ScalarField.from_expression(grid, "sin(x)")

# solve the equation and store the trajectory
storage = MemoryStorage()
eq.solve(state, t_range=3, tracker=storage.tracker(0.1))

# plot the trajectory as a space-time plot
plot_kymograph(storage)

```

Total running time of the script: ( 0 minutes 7.110 seconds)

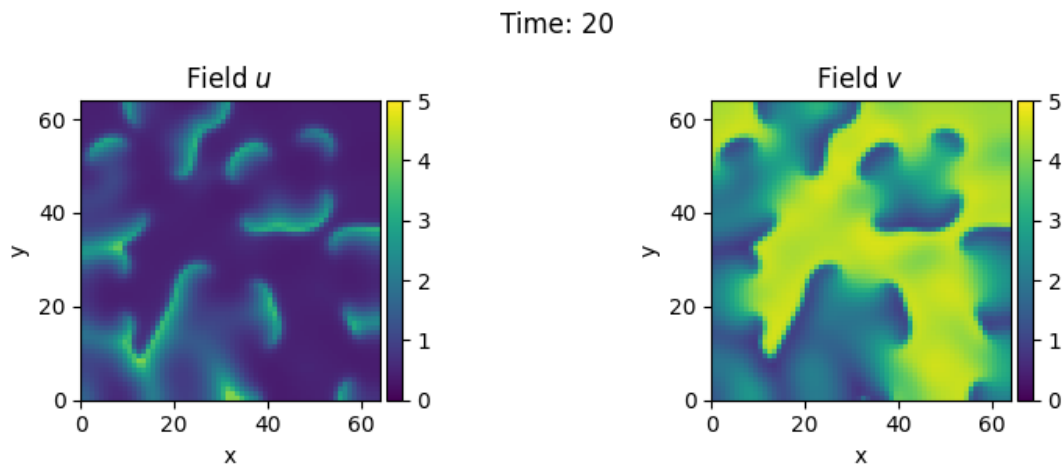
## 2.13 Brusselator - Using the *PDE* class

This example uses the *PDE* class to implement the *Brusselator* with spatial coupling,

$$\begin{aligned}\partial_t u &= D_0 \nabla^2 u + a - (1 + b)u + vu^2 \\ \partial_t v &= D_1 \nabla^2 v + bu - vu^2\end{aligned}$$

Here,  $D_0$  and  $D_1$  are the respective diffusivity and the parameters  $a$  and  $b$  are related to reaction rates.

Note that the same result can also be achieved with a *full implementation of a custom class*, which allows for more flexibility at the cost of code complexity.



```

from pde import PDE, FieldCollection, PlotTracker, ScalarField, UnitGrid

# define the PDE
a, b = 1, 3
d0, d1 = 1, 0.1
eq = PDE(
    {
        "u": f"{d0} * laplace(u) + {a} - ({b} + 1) * u + u**2 * v",

```

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```

        "v": f"{d1} * laplace(v) + {b} * u - u**2 * v",
    }
)

# initialize state
grid = UnitGrid([64, 64])
u = ScalarField(grid, a, label="Field $u$")
v = b / a + 0.1 * ScalarField.random_normal(grid, label="Field $v$")
state = FieldCollection([u, v])

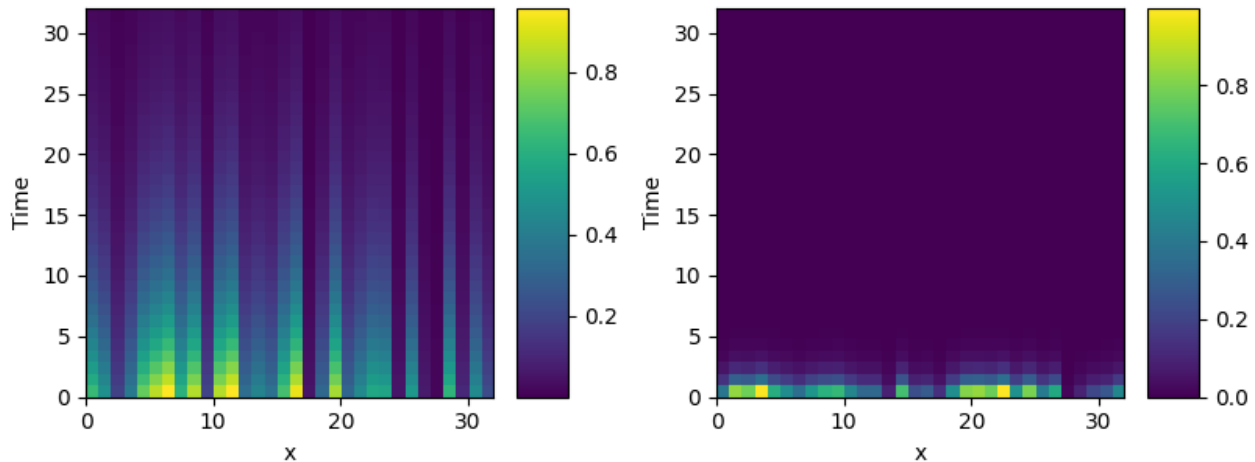
# simulate the pde
tracker = PlotTracker(interval=1, plot_args={"vmin": 0, "vmax": 5})
sol = eq.solve(state, t_range=20, dt=1e-3, tracker=tracker)

```

Total running time of the script: ( 0 minutes 26.703 seconds)

## 2.14 Writing and reading trajectory data

This example illustrates how to store intermediate data to a file for later post-processing. The storage frequency is an argument to the tracker.



```

from tempfile import NamedTemporaryFile

import pde

# define grid, state and pde
grid = pde.UnitGrid([32])
state = pde.FieldCollection(
    [pde.ScalarField.random_uniform(grid), pde.VectorField.random_uniform(grid)]
)
eq = pde.PDE({"s": "-0.1 * s", "v": "-v"})

# get a temporary file to write data to
path = NamedTemporaryFile(suffix=".hdf5")

# run a simulation and write the results
writer = pde.FileStorage(path.name, write_mode="truncate")

```

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```
eq.solve(state, t_range=32, dt=0.01, tracker=writer.tracker(1))

# read the simulation back in again
reader = pde.FileStorage(path.name, write_mode="read_only")
pde.plot_kymographs(reader)
```

**Total running time of the script:** ( 0 minutes 5.588 seconds)

## 2.15 Diffusion equation with spatial dependence

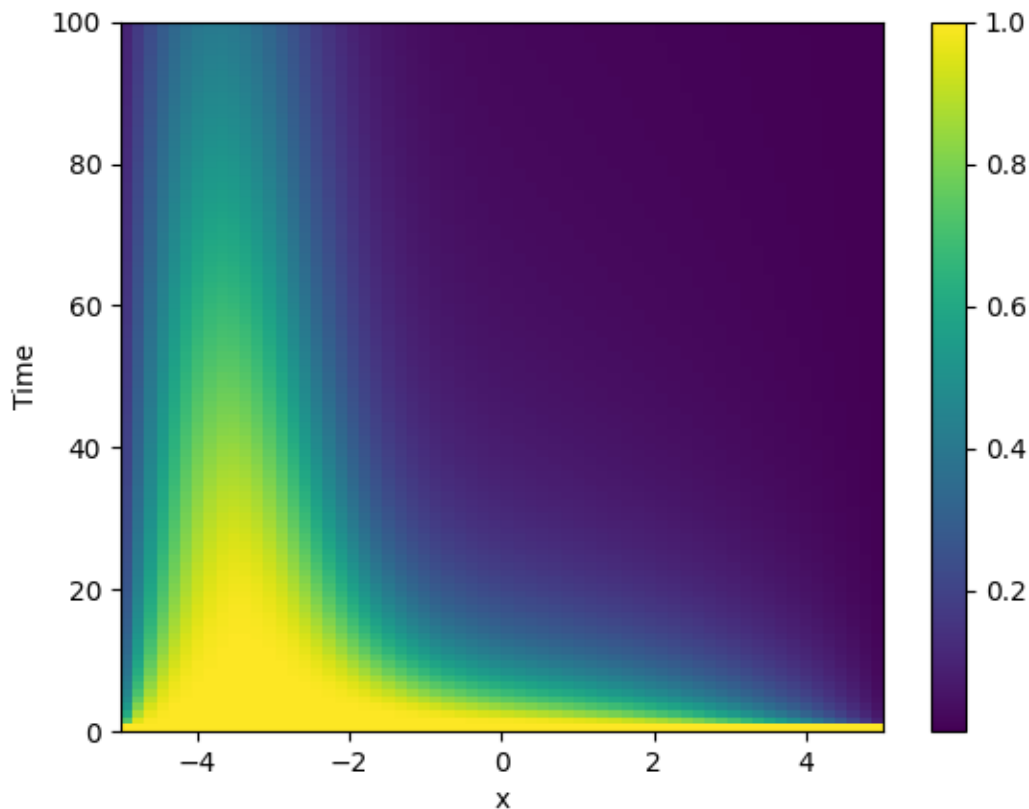
This example solve the [Diffusion equation](#) with a heterogeneous diffusivity:

$$\partial_t c = \nabla (D(\mathbf{r}) \nabla c)$$

using the [PDE](#) class. In particular, we consider  $D(x) = 1.01 + \tanh(x)$ , which gives a low diffusivity on the left side of the domain.

Note that the naive implementation, `PDE({"c": "divergence((1.01 + tanh(x)) * gradient(c))"})`, has numerical instabilities. This is because two finite difference approximations are nested. To arrive at a more stable numerical scheme, it is advisable to expand the divergence,

$$\partial_t c = D \nabla^2 c + \nabla D \cdot \nabla c$$



```

from pde import PDE, CartesianGrid, MemoryStorage, ScalarField, plot_kymograph

# Expanded definition of the PDE
diffusivity = "1.01 + tanh(x)"
term_1 = f"({diffusivity}) * laplace(c)"
term_2 = f"dot(gradient({diffusivity}), gradient(c))"
eq = PDE({"c": f"{term_1} + {term_2}"}, bc={"value": 0})

grid = CartesianGrid([-5, 5], 64) # generate grid
field = ScalarField(grid, 1) # generate initial condition

storage = MemoryStorage() # store intermediate information of the simulation
res = eq.solve(field, 100, dt=1e-3, tracker=storage.tracker(1)) # solve the PDE

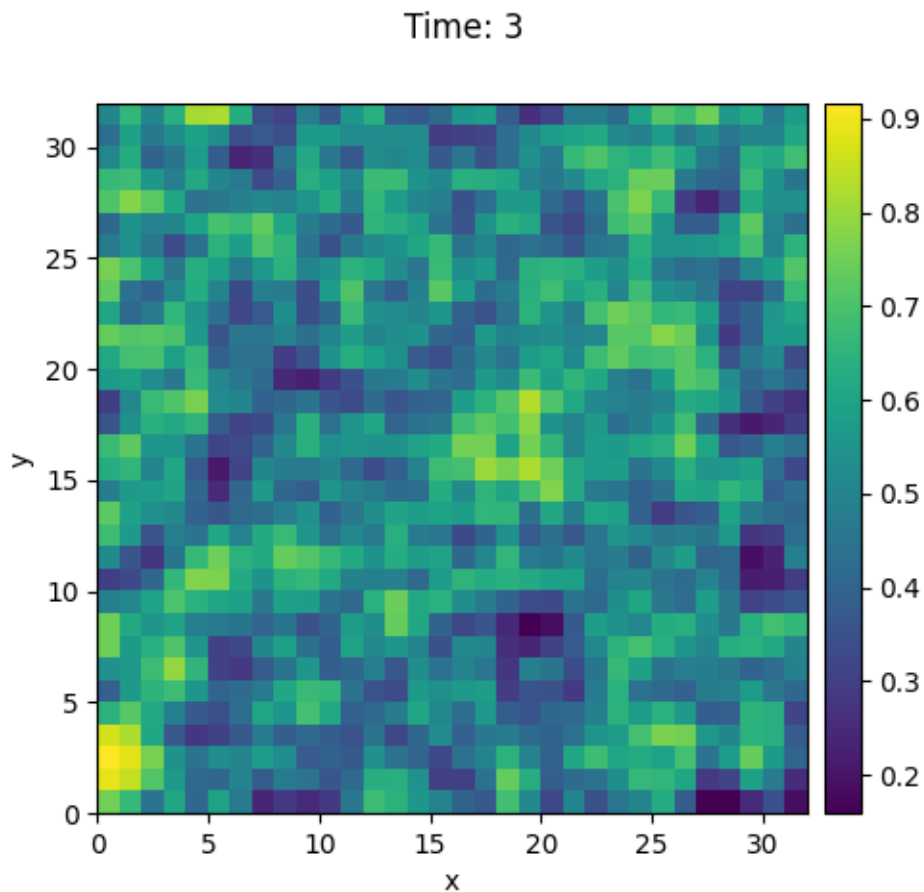
plot_kymograph(storage) # visualize the result in a space-time plot

```

Total running time of the script: ( 0 minutes 11.372 seconds)

## 2.16 Using simulation trackers

This example illustrates how trackers can be used to analyze simulations.



Out:

```

0%|          | 0/3.0 [00:00<?, ?it/s]
Initializing: 0%|          | 0/3.0 [00:00<?, ?it/s]
0%|          | 0/3.0 [00:07<?, ?it/s]
3%|3        | 0.1/3.0 [00:08<03:59, 82.49s/it]
7%|6        | 0.2/3.0 [00:09<02:08, 45.73s/it]
10%|9       | 0.3/3.0 [00:09<01:22, 30.49s/it]
13%|#3      | 0.4/3.0 [00:09<00:59, 22.87s/it]
13%|#3      | 0.4/3.0 [00:09<01:00, 23.34s/it]
100%|#####| 3.0/3.0 [00:09<00:00, 3.11s/it]
100%|#####| 3.0/3.0 [00:09<00:00, 3.11s/it]
528.5685691951896
528.5685691951895
528.5685691951894
528.5685691951894

```

```

import pde

grid = pde.UnitGrid([32, 32]) # generate grid
state = pde.ScalarField.random_uniform(grid) # generate initial condition

storage = pde.MemoryStorage()

trackers = [
    "progress", # show progress bar during simulation
    "steady_state", # abort when steady state is reached
    storage.tracker(interval=1), # store data every simulation time unit
    pde.PlotTracker(show=True), # show images during simulation
    # print some output every 5 real seconds:
    pde.PrintTracker(interval=pde.RealtimeIntervals(duration=5)),
]

eq = pde.DiffusionPDE(0.1) # define the PDE
eq.solve(state, 3, dt=0.1, tracker=trackers)

for field in storage:
    print(field.integral)

```

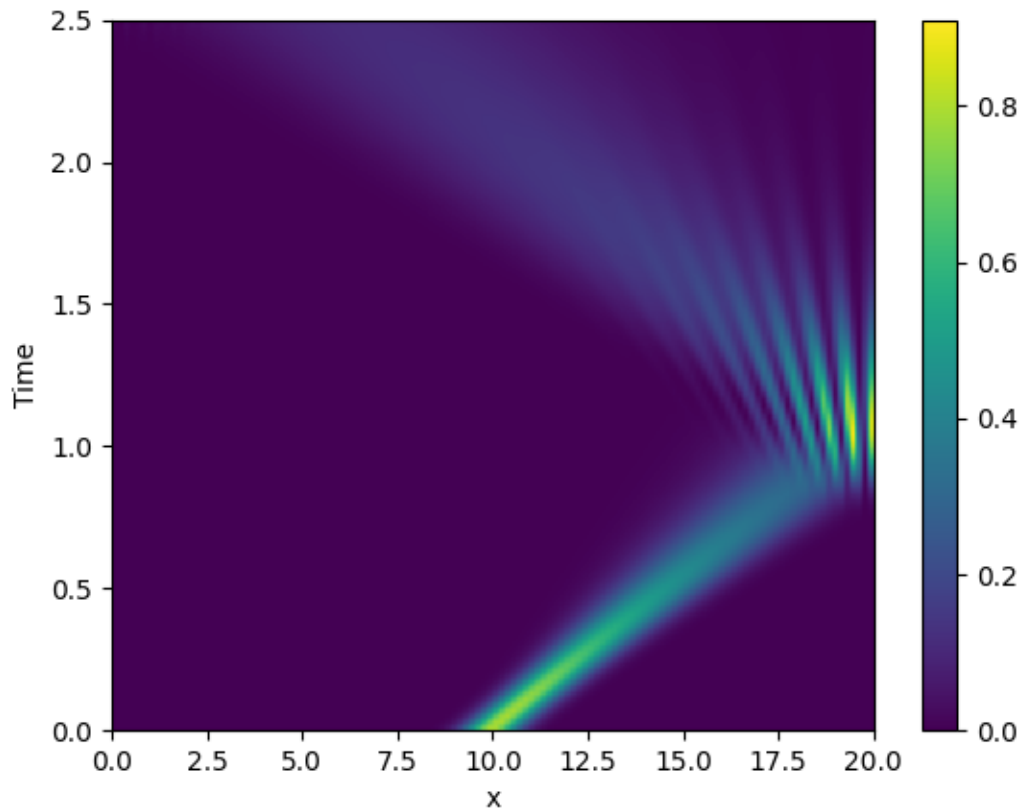
Total running time of the script: ( 0 minutes 9.416 seconds)

## 2.17 Schrödinger's Equation

This example implements a complex PDE using the *PDE*. We here chose the Schrödinger equation without a spatial potential in non-dimensional form:

$$i\partial_t\psi = -\nabla^2\psi$$

Note that the example imposes Neumann conditions at the wall, so the wave packet is expected to reflect off the wall.



```

from math import sqrt

from pde import PDE, CartesianGrid, MemoryStorage, ScalarField, plot_kymograph

grid = CartesianGrid([[0, 20]], 128, periodic=False) # generate grid

# create a (normalized) wave packet with a certain form as an initial condition
initial_state = ScalarField.from_expression(grid, "exp(I * 5 * x) * exp(-(x - 10)**2)
↪")
initial_state /= sqrt(initial_state.to_scalar("norm_squared").integral.real)

eq = PDE({"ψ": f"I * laplace(ψ)"}) # define the pde

# solve the pde and store intermediate data
storage = MemoryStorage()
eq.solve(initial_state, t_range=2.5, dt=1e-5, tracker=[storage.tracker(0.02)])

# visualize the results as a space-time plot
plot_kymograph(storage, scalar="norm_squared")

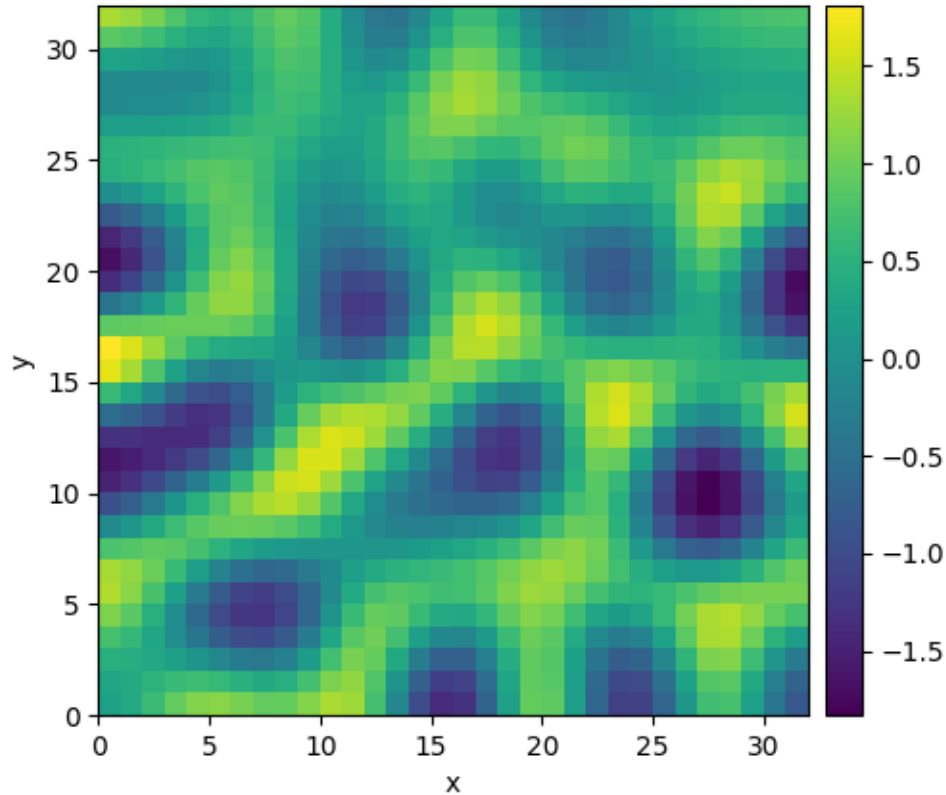
```

**Total running time of the script:** ( 0 minutes 5.217 seconds)

## 2.18 Kuramoto-Sivashinsky - Using custom class

This example implements a scalar PDE using a custom class. We here consider the Kuramoto–Sivashinsky equation, which for instance describes the dynamics of flame fronts:

$$\partial_t u = -\frac{1}{2}|\nabla u|^2 - \nabla^2 u - \nabla^4 u$$



Out:

```

0%|          | 0/10.0 [00:00<?, ?it/s]
Initializing: 0%|          | 0/10.0 [00:00<?, ?it/s]
0%|          | 0/10.0 [00:00<?, ?it/s]
2%|2        | 0.24/10.0 [00:06<04:21, 26.78s/it]
3%|3        | 0.34/10.0 [00:06<03:02, 18.91s/it]
17%|#6      | 1.7/10.0 [00:06<00:31, 3.82s/it]
73%|#####3 | 7.34/10.0 [00:06<00:02, 1.09it/s]
73%|#####3 | 7.34/10.0 [00:06<00:02, 1.07it/s]
100%|##### | 10.0/10.0 [00:06<00:00, 1.46it/s]
100%|##### | 10.0/10.0 [00:06<00:00, 1.46it/s]
```

```

from pde import PDEBase, ScalarField, UnitGrid

class KuramotoSivashinskyPDE(PDEBase):
    """Implementation of the normalized Kuramoto-Sivashinsky equation"""

    def evolution_rate(self, state, t=0):
        """implement the python version of the evolution equation"""
        state_lap = state.laplace(bc="auto_periodic_neumann")
        state_lap2 = state_lap.laplace(bc="auto_periodic_neumann")
        state_grad = state.gradient(bc="auto_periodic_neumann")
        return -state_grad.to_scalar("squared_sum") / 2 - state_lap - state_lap2

grid = UnitGrid([32, 32]) # generate grid
state = ScalarField.random_uniform(grid) # generate initial condition

eq = KuramotoSivashinskyPDE() # define the pde
result = eq.solve(state, t_range=10, dt=0.01)
result.plot()

```

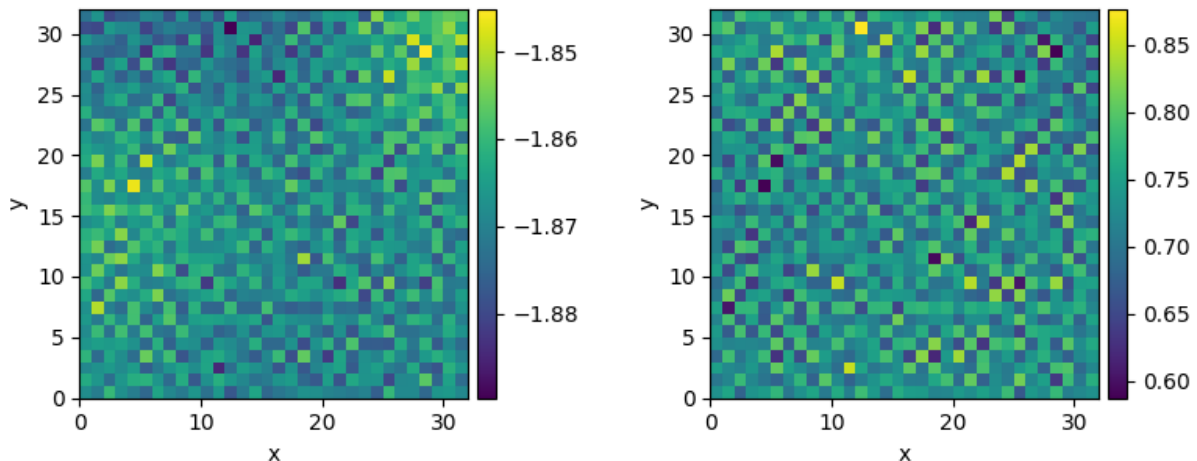
Total running time of the script: ( 0 minutes 6.993 seconds)

## 2.19 Custom Class for coupled PDEs

This example shows how to solve a set of coupled PDEs, the spatially coupled [FitzHugh–Nagumo model](#), which is a simple model for the excitable dynamics of coupled Neurons:

$$\begin{aligned}\partial_t u &= \nabla^2 u + u(u - \alpha)(1 - u) + w \\ \partial_t w &= \epsilon u\end{aligned}$$

Here,  $\alpha$  denotes the external stimulus and  $\epsilon$  defines the recovery time scale. We implement this as a custom PDE class below.



Out:

```

0%|          | 0/100.0 [00:00<?, ?it/s]
Initializing: 0%|          | 0/100.0 [00:00<?, ?it/s]

```

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```

0%|          | 0/100.0 [00:00<?, ?it/s]
0%|          | 0.25/100.0 [00:03<20:35, 12.39s/it]
0%|          | 0.38/100.0 [00:03<13:33, 8.17s/it]
2%|1         | 1.96/100.0 [00:03<02:39, 1.63s/it]
7%|7         | 7.29/100.0 [00:03<00:44, 2.10it/s]
17%|#7        | 17.29/100.0 [00:04<00:19, 4.30it/s]
31%|###       | 30.84/100.0 [00:04<00:10, 6.49it/s]
47%|#####6    | 46.71/100.0 [00:05<00:06, 8.33it/s]
64%|#####3    | 63.86/100.0 [00:06<00:03, 9.79it/s]
82%|#####1    | 81.77/100.0 [00:07<00:01, 10.91it/s]
100%|#####9   | 99.91/100.0 [00:08<00:00, 11.80it/s]
100%|#####9   | 99.91/100.0 [00:08<00:00, 11.80it/s]
100%|#####    | 100.0/100.0 [00:08<00:00, 11.81it/s]
100%|#####    | 100.0/100.0 [00:08<00:00, 11.81it/s]

```

```

from pde import FieldCollection, PDEBase, UnitGrid

class FitzhughNagumoPDE(PDEBase):
    """FitzHugh-Nagumo model with diffusive coupling"""

    def __init__(self, stimulus=0.5, tau=10, a=0, b=0, bc="auto_periodic_neumann"):
        self.bc = bc
        self.stimulus = stimulus
        self.tau = tau
        self.a = a
        self.b = b

    def evolution_rate(self, state, t=0):
        v, w = state # membrane potential and recovery variable

        v_t = v.laplace(bc=self.bc) + v - v**3 / 3 - w + self.stimulus
        w_t = (v + self.a - self.b * w) / self.tau

        return FieldCollection([v_t, w_t])

grid = UnitGrid([32, 32])
state = FieldCollection.scalar_random_uniform(2, grid)

eq = FitzhughNagumoPDE()
result = eq.solve(state, t_range=100, dt=0.01)
result.plot()

```

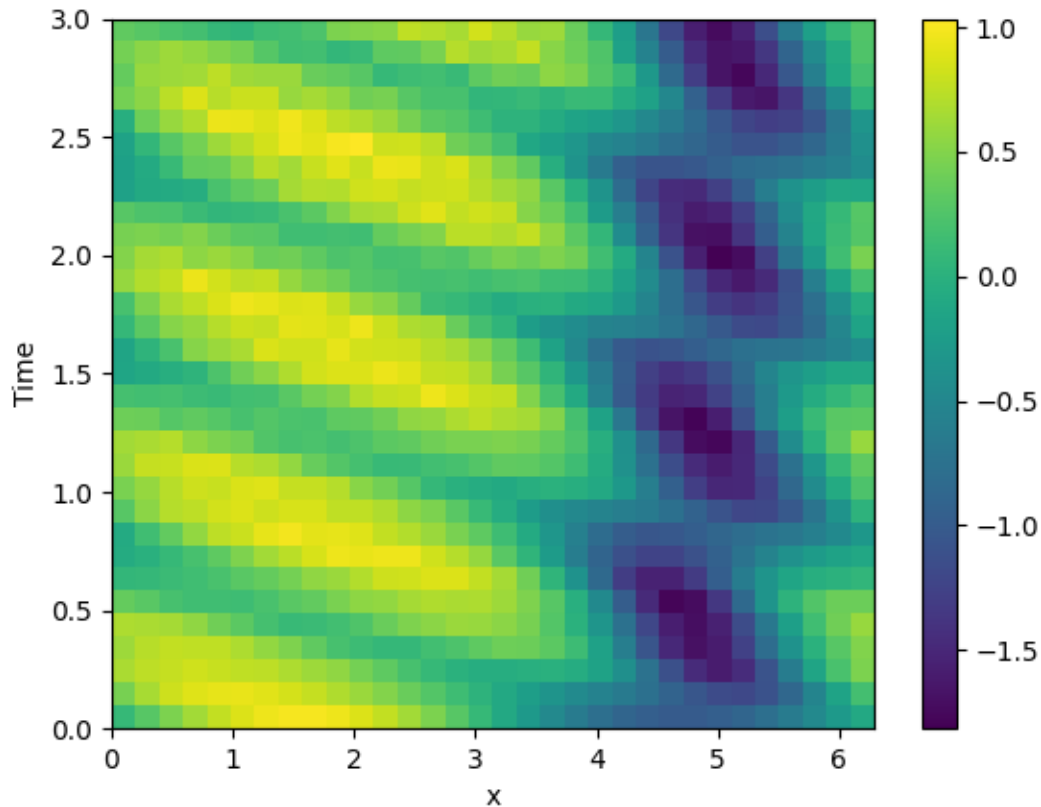
**Total running time of the script:** ( 0 minutes 8.775 seconds)

## 2.20 1D problem - Using custom class

This example implements a PDE that is only defined in one dimension. Here, we chose the [Korteweg-de Vries equation](#), given by

$$\partial_t \phi = 6\phi \partial_x \phi - \partial_x^3 \phi$$

which we implement using a custom PDE class below.



```
from math import pi

from pde import CartesianGrid, MemoryStorage, PDEBase, ScalarField, plot_kymograph

class KortewegDeVriesPDE(PDEBase):
    """Korteweg-de Vries equation"""

    def evolution_rate(self, state, t=0):
        """implement the python version of the evolution equation"""
        assert state.grid.dim == 1 # ensure the state is one-dimensional
        grad_x = state.gradient("auto_periodic_neumann")[0]
        return 6 * state * grad_x - grad_x.laplace("auto_periodic_neumann")

# initialize the equation and the space
```

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```

grid = CartesianGrid([[0, 2 * pi]], [32], periodic=True)
state = ScalarField.from_expression(grid, "sin(x)")

# solve the equation and store the trajectory
storage = MemoryStorage()
eq = KortewegDeVriesPDE()
eq.solve(state, t_range=3, tracker=storage.tracker(0.1))

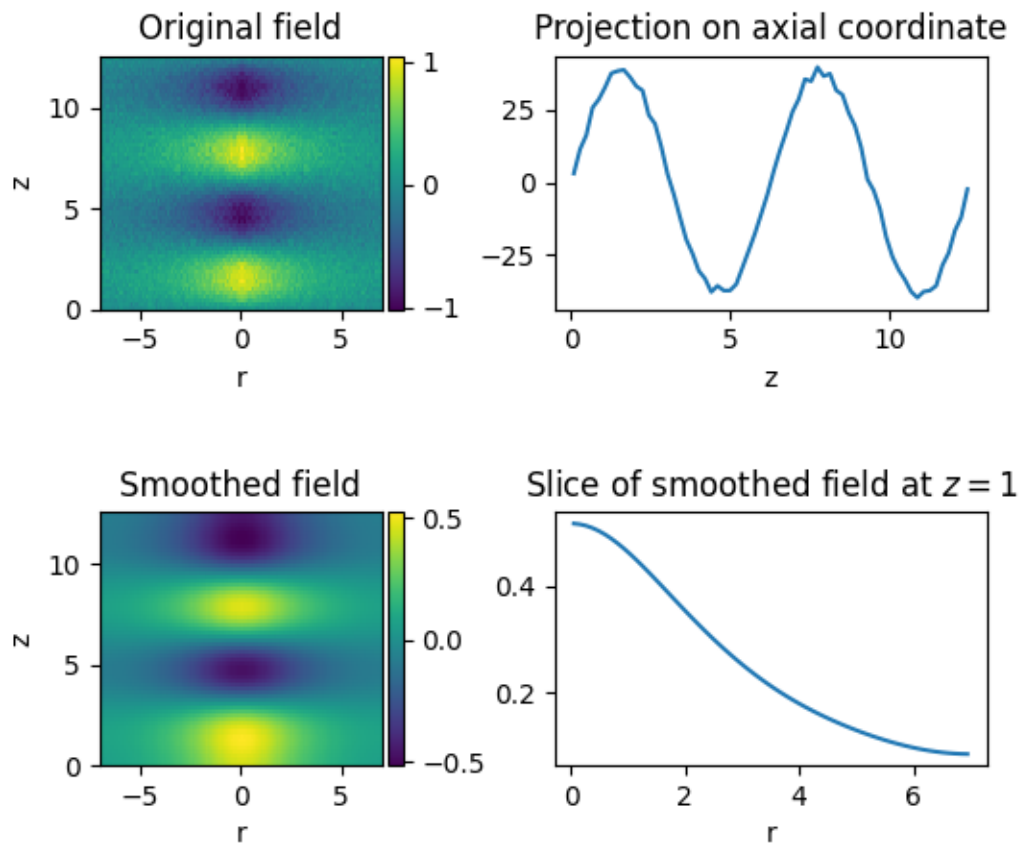
# plot the trajectory as a space-time plot
plot_kymograph(storage)

```

**Total running time of the script:** ( 0 minutes 4.249 seconds)

## 2.21 Visualizing a scalar field

This example displays methods for visualizing scalar fields.



```

import matplotlib.pyplot as plt
import numpy as np

from pde import CylindricalSymGrid, ScalarField

```

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```

# create a scalar field with some noise
grid = CylindricalSymGrid(7, [0, 4 * np.pi], 64)
data = ScalarField.from_expression(grid, "sin(z) * exp(-r / 3)")
data += 0.05 * ScalarField.random_normal(grid)

# manipulate the field
smoothed = data.smooth() # Gaussian smoothing to get rid of the noise
projected = data.project("r") # integrate along the radial direction
sliced = smoothed.slice({"z": 1}) # slice the smoothed data

# create four plots of the field and the modifications
fig, axes = plt.subplots(nrows=2, ncols=2)
data.plot(ax=axes[0, 0], title="Original field")
smoothed.plot(ax=axes[1, 0], title="Smoothed field")
projected.plot(ax=axes[0, 1], title="Projection on axial coordinate")
sliced.plot(ax=axes[1, 1], title="Slice of smoothed field at $z=1$")
plt.subplots_adjust(hspace=0.8)
plt.show()

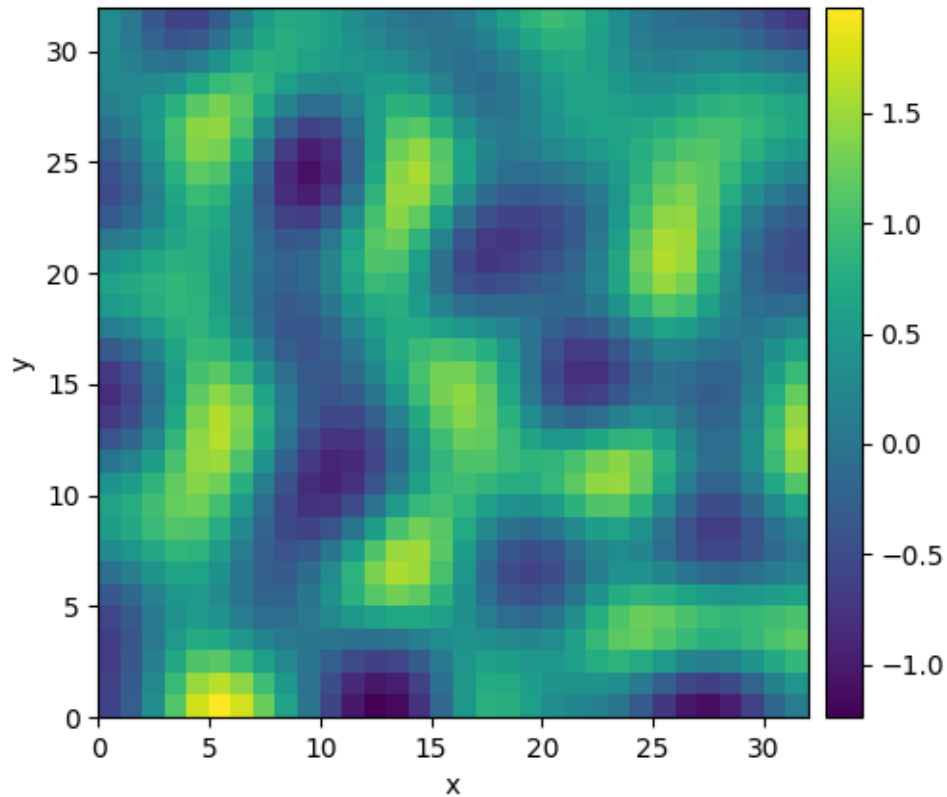
```

**Total running time of the script:** ( 0 minutes 0.509 seconds)

## 2.22 Kuramoto-Sivashinsky - Compiled methods

This example implements a scalar PDE using a custom class with a numba-compiled method for accelerated calculations. We here consider the [Kuramoto–Sivashinsky equation](#), which for instance describes the dynamics of flame fronts:

$$\partial_t u = -\frac{1}{2}|\nabla u|^2 - \nabla^2 u - \nabla^4 u$$



Out:

```

 0%|          | 0/10.0 [00:00<?, ?it/s]
Initializing: 0%|          | 0/10.0 [00:00<?, ?it/s]
 0%|          | 0/10.0 [00:15<?, ?it/s]
 0%|          | 0.01/10.0 [00:19<5:17:11, 1905.01s/it]
 0%|          | 0.02/10.0 [00:21<2:55:30, 1055.17s/it]
 0%|          | 0.03/10.0 [00:21<1:56:53, 703.46s/it]
 1%|1         | 0.1/10.0 [00:21<34:49, 211.04s/it]
45%|#####5   | 4.52/10.0 [00:21<00:25, 4.67s/it]
45%|#####5   | 4.52/10.0 [00:21<00:25, 4.67s/it]
100%|#####| 10.0/10.0 [00:21<00:00, 2.11s/it]
100%|#####| 10.0/10.0 [00:21<00:00, 2.11s/it]

```

```

import numba as nb

from pde import PDEBase, ScalarField, UnitGrid

class KuramotoSivashinskyPDE(PDEBase):

```

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(continued from previous page)

```

"""Implementation of the normalized Kuramoto-Sivashinsky equation"""

def __init__(self, bc="auto_periodic_neumann"):
    self.bc = bc

def evolution_rate(self, state, t=0):
    """implement the python version of the evolution equation"""
    state_lap = state.laplace(bc=self.bc)
    state_lap2 = state_lap.laplace(bc=self.bc)
    state_grad_sq = state.gradient_squared(bc=self.bc)
    return -state_grad_sq / 2 - state_lap - state_lap2

def _make_pde_rhs_numba(self, state):
    """numba-compiled implementation of the PDE"""
    gradient_squared = state.grid.make_operator("gradient_squared", bc=self.bc)
    laplace = state.grid.make_operator("laplace", bc=self.bc)

    @nb.jit
    def pde_rhs(data, t):
        return -0.5 * gradient_squared(data) - laplace(data + laplace(data))

    return pde_rhs

grid = UnitGrid([32, 32]) # generate grid
state = ScalarField.random_uniform(grid) # generate initial condition

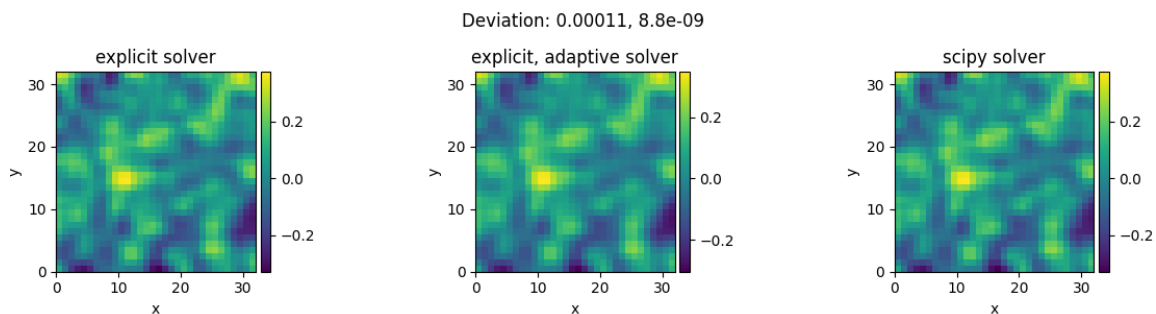
eq = KuramotoSivashinskyPDE() # define the pde
result = eq.solve(state, t_range=10, dt=0.01)
result.plot()

```

Total running time of the script: ( 0 minutes 21.279 seconds)

## 2.23 Solver comparison

This example shows how to set up solvers explicitly and how to extract diagnostic information.



Out:

```

Diagnostic information from first run:
{'controller': {'t_start': 0, 't_end': 1.0, 'solver_class': 'ExplicitSolver', 'solver_
→start': '2022-03-15 14:40:28.713444', 'profiler': {'solver': 1.448718250000013,
→'tracker': 4.7672999983205955e-05}, 'successful': True, 'stop_reason': 'Reached_
→final time', 'solver_duration': '0:00:01.448858', 't_final': 1.0}, 'package version
→': '0.18.0', 'solver': {'class': 'ExplicitSolver', 'pde_class': 'DiffusionPDE', 'dt
→': 0.001, 'steps': 1000, 'scheme': 'euler', 'state_modifications': 0.0, 'dt_adaptive
→': False, 'backend': 'numba', 'stochastic': False, 'adaptive': False}, 'jit_count': 33
→{'make_stepper': 7, 'simulation': 0}}

```

(continued from previous page)

```

Diagnostic information from second run:
{'controller': {'t_start': 0, 't_end': 1.0, 'solver_class': 'ExplicitSolver', 'solver_
→start': '2022-03-15 14:40:30.924224', 'profiler': {'solver': 2.6291207099999995,
→'tracker': 4.0753000007498486e-05}, 'successful': True, 'stop_reason': 'Reached_
→final time', 'solver_duration': '0:00:02.629222', 't_final': 1.1286979382091924},
→'package_version': '0.18.0', 'solver': {'class': 'ExplicitSolver', 'pde_class':
→'DiffusionPDE', 'dt': 0.001, 'steps': 12, 'scheme': 'runge-kutta', 'state_
→modifications': 0.0, 'dt_adaptive': True, 'backend': 'numba', 'stochastic': False,
→'adaptive': True, 'dt_last': 0.24901510892640738}, 'jit_count': {'make_stepper': 3,
→'simulation': 0}}

Diagnostic information from third run:
{'controller': {'t_start': 0, 't_end': 1.0, 'solver_class': 'ScipySolver', 'solver_
→start': '2022-03-15 14:40:34.306809', 'profiler': {'solver': 0.003942405000003646,
→'tracker': 3.832899997746608e-05}, 'successful': True, 'stop_reason': 'Reached_
→final time', 'solver_duration': '0:00:00.004009', 't_final': 1.0}, 'package_version
→': '0.18.0', 'solver': {'class': 'ScipySolver', 'pde_class': 'DiffusionPDE', 'dt':_
→None, 'steps': 50, 'stochastic': False, 'backend': 'numba'}, 'jit_count': {'make_
→stepper': 1, 'simulation': 0}}

```

```

import pde

# initialize the grid, an initial condition, and the PDE
grid = pde.UnitGrid([32, 32])
field = pde.ScalarField.random_uniform(grid, -1, 1)
eq = pde.DiffusionPDE()

# try the explicit solver
solver1 = pde.ExplicitSolver(eq)
controller1 = pde.Controller(solver1, t_range=1, tracker=None)
sol1 = controller1.run(field, dt=1e-3)
sol1.label = "explicit solver"
print("Diagnostic information from first run:")
print(controller1.diagnostics)
print()

# try an explicit solver with adaptive time steps
solver2 = pde.ExplicitSolver(eq, scheme="runge-kutta", adaptive=True)
controller2 = pde.Controller(solver2, t_range=1, tracker=None)
sol2 = controller2.run(field, dt=1e-3)
sol2.label = "explicit, adaptive solver"
print("Diagnostic information from second run:")
print(controller2.diagnostics)
print()

# try the standard scipy solver
solver3 = pde.ScipySolver(eq)
controller3 = pde.Controller(solver3, t_range=1, tracker=None)
sol3 = controller3.run(field)
sol3.label = "scipy solver"

```

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(continued from previous page)

```

print("Diagnostic information from third run:")
print(controller3.diagnostics)
print()

# plot both fields and give the deviation as the title
title = f"Deviation: {((sol1 - sol2)**2).average:.2g}, {((sol1 - sol3)**2).average:.2g}"
pde.FieldCollection([sol1, sol2, sol3]).plot(title=title)

```

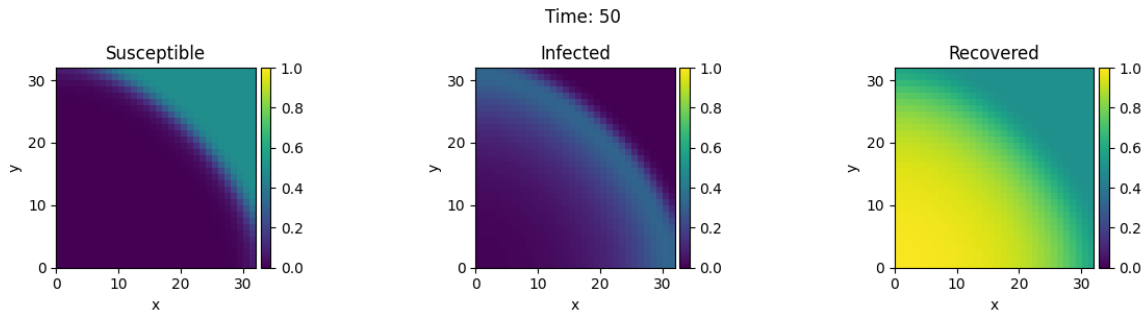
Total running time of the script: ( 0 minutes 12.911 seconds)

## 2.24 Custom PDE class: SIR model

This example implements a [spatially coupled SIR model](#) with the following dynamics for the density of susceptible, infected, and recovered individuals:

$$\begin{aligned}\partial_t s &= D \nabla^2 s - \beta i s \\ \partial_t i &= D \nabla^2 i + \beta i s - \gamma i \\ \partial_t r &= D \nabla^2 r + \gamma i\end{aligned}$$

Here,  $D$  is the diffusivity,  $\beta$  the infection rate, and  $\gamma$  the recovery rate.



Out:

```

0%|          | 0/50.0 [00:00<?, ?it/s]
Initializing: 0%|          | 0/50.0 [00:00<?, ?it/s]
0%|          | 0/50.0 [00:00<?, ?it/s]
0%|          | 0.02/50.0 [00:03<2:30:24, 180.55s/it]
0%|          | 0.03/50.0 [00:03<1:40:16, 120.41s/it]
1%|          | 0.3/50.0 [00:03<10:01, 12.10s/it]
5%|4        | 2.26/50.0 [00:03<01:19, 1.67s/it]
15%|4       | 7.47/50.0 [00:04<00:23, 1.80it/s]
32%|###2    | 16.02/50.0 [00:04<00:10, 3.26it/s]
52%|#####1 | 25.78/50.0 [00:05<00:05, 4.48it/s]
73%|#####2 | 36.39/50.0 [00:06<00:02, 5.46it/s]
95%|#####5 | 47.5/50.0 [00:07<00:00, 6.24it/s]
95%|#####5 | 47.5/50.0 [00:07<00:00, 5.98it/s]
100%|##### | 50.0/50.0 [00:07<00:00, 6.29it/s]
100%|##### | 50.0/50.0 [00:07<00:00, 6.29it/s]

```

```

from pde import FieldCollection, PDEBase, PlotTracker, ScalarField, UnitGrid

class SIRPDE(PDEBase):
    """SIR-model with diffusive mobility"""

    def __init__(
        self, beta=0.3, gamma=0.9, diffusivity=0.1, bc="auto_periodic_neumann"
    ):
        self.beta = beta # transmission rate
        self.gamma = gamma # recovery rate
        self.diffusivity = diffusivity # spatial mobility
        self.bc = bc # boundary condition

    def get_state(self, s, i):
        """generate a suitable initial state"""
        norm = (s + i).data.max() # maximal density
        if norm > 1:
            s /= norm
            i /= norm
        s.label = "Susceptible"
        i.label = "Infected"

        # create recovered field
        r = ScalarField(s.grid, data=1 - s - i, label="Recovered")
        return FieldCollection([s, i, r])

    def evolution_rate(self, state, t=0):
        s, i, r = state
        diff = self.diffusivity
        ds_dt = diff * s.laplace(self.bc) - self.beta * i * s
        di_dt = diff * i.laplace(self.bc) + self.beta * i * s - self.gamma * i
        dr_dt = diff * r.laplace(self.bc) + self.gamma * i
        return FieldCollection([ds_dt, di_dt, dr_dt])

eq = SIRPDE(beta=2, gamma=0.1)

# initialize state
grid = UnitGrid([32, 32])
s = ScalarField(grid, 1)
i = ScalarField(grid, 0)
i.data[0, 0] = 1
state = eq.get_state(s, i)

# simulate the pde
tracker = PlotTracker(interval=10, plot_args={"vmin": 0, "vmax": 1})
sol = eq.solve(state, t_range=50, dt=1e-2, tracker=["progress", tracker])

```

Total running time of the script: ( 0 minutes 8.122 seconds)

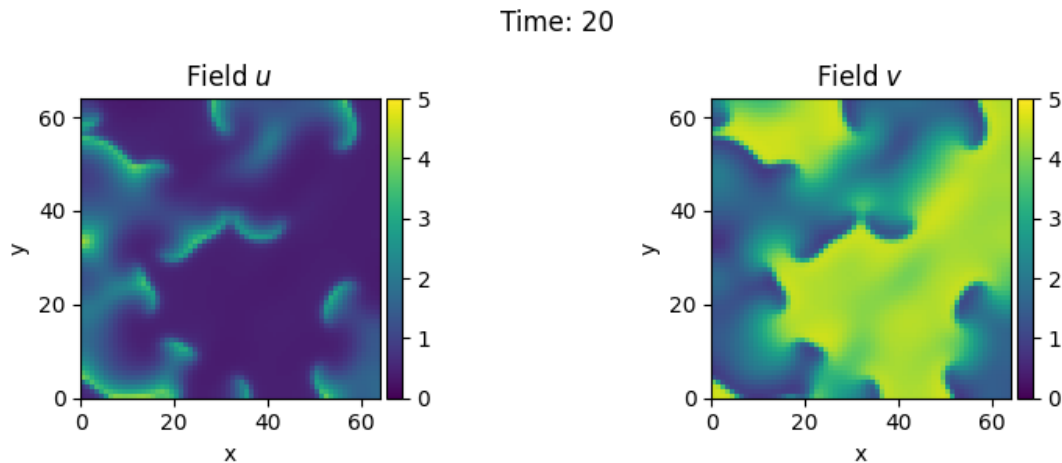
## 2.25 Brusselator - Using custom class

This example implements the [Brusselator](#) with spatial coupling,

$$\begin{aligned}\partial_t u &= D_0 \nabla^2 u + a - (1 + b)u + vu^2 \\ \partial_t v &= D_1 \nabla^2 v + bu - vu^2\end{aligned}$$

Here,  $D_0$  and  $D_1$  are the respective diffusivity and the parameters  $a$  and  $b$  are related to reaction rates.

Note that the PDE can also be implemented using the [PDE](#) class; see [the example](#). However, that implementation is less flexible and might be more difficult to extend later.



```
import numba as nb
import numpy as np

from pde import FieldCollection, PDEBase, PlotTracker, ScalarField, UnitGrid

class BrusselatorPDE(PDEBase):
    """Brusselator with diffusive mobility"""

    def __init__(self, a=1, b=3, diffusivity=[1, 0.1], bc="auto_periodic_neumann"):
        self.a = a
        self.b = b
        self.diffusivity = diffusivity # spatial mobility
        self.bc = bc # boundary condition

    def get_initial_state(self, grid):
        """prepare a useful initial state"""
        u = ScalarField(grid, self.a, label="Field $u$")
        v = self.b / self.a + 0.1 * ScalarField.random_normal(grid, label="Field $v$")
        return FieldCollection([u, v])

    def evolution_rate(self, state, t=0):
        """pure python implementation of the PDE"""
        u, v = state
        rhs = state.copy()
        d0, d1 = self.diffusivity
        rhs[0] = d0 * u.laplace(self.bc) + self.a - (self.b + 1) * u + u**2 * v
        rhs[1] = d1 * v.laplace(self.bc) + self.b * u - u**2 * v
```

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```

    return rhs

    def _make_pde_rhs_numba(self, state):
        """numba-compiled implementation of the PDE"""
        d0, d1 = self.diffusivity
        a, b = self.a, self.b
        laplace = state.grid.make_operator("laplace", bc=self.bc)

        @nb.jit
        def pde_rhs(state_data, t):
            u = state_data[0]
            v = state_data[1]

            rate = np.empty_like(state_data)
            rate[0] = d0 * laplace(u) + a - (1 + b) * u + v * u**2
            rate[1] = d1 * laplace(v) + b * u - v * u**2
            return rate

        return pde_rhs

# initialize state
grid = UnitGrid([64, 64])
eq = BrusselatorPDE(diffusivity=[1, 0.1])
state = eq.get_initial_state(grid)

# simulate the pde
tracker = PlotTracker(interval=1, plot_args={"vmin": 0, "vmax": 5})
sol = eq.solve(state, t_range=20, dt=1e-3, tracker=tracker)

```

**Total running time of the script:** ( 0 minutes 16.107 seconds)

## 3.1 Mathematical basics

To solve partial differential equations (PDEs), the *py-pde* package provides differential operators to express spatial derivatives. These operators are implemented using the [finite difference method](#) to support various boundary conditions. The time evolution of the PDE is then calculated using the method of lines by explicitly discretizing space using the grid classes. This reduces the PDEs to a set of ordinary differential equations, which can be solved using standard methods as described below.

### 3.1.1 Curvilinear coordinates

The package supports multiple curvilinear coordinate systems. They allow to exploit symmetries present in physical systems. Consequently, many grids implemented in *py-pde* inherently assume symmetry of the described fields. However, a drawback of curvilinear coordinates are the fact that the basis vectors now depend on position, which makes tensor fields less intuitive and complicates the expression of differential operators. To avoid confusion, we here specify the used coordinate systems explicitly:

#### Polar coordinates

Polar coordinates describe points by a radius  $r$  and an angle  $\phi$  in a two-dimensional coordinates system. They are defined by the transformation

$$\begin{cases} x = r \cos(\phi) \\ y = r \sin(\phi) \end{cases} \quad \text{for } r \in [0, \infty] \text{ and } \phi \in [0, 2\pi)$$

The associated symmetric grid [PolarSymGrid](#) assumes that fields only depend on the radial coordinate  $r$ . Note that vector and tensor fields can still have components in the polar direction. In particular, vector fields still have two components:  $\vec{v}(r) = v_r(r)\vec{e}_r + v_\phi(r)\vec{e}_\phi$ .

#### Spherical coordinates

Spherical coordinates describe points by a radius  $r$ , an azimuthal angle  $\theta$ , and a polar angle  $\phi$ . The conversion to ordinary Cartesian coordinates reads

$$\begin{cases} x = r \sin(\theta) \cos(\phi) \\ y = r \sin(\theta) \sin(\phi) \\ z = r \cos(\theta) \end{cases} \quad \text{for } r \in [0, \infty], \theta \in [0, \pi], \text{ and } \phi \in [0, 2\pi)$$

The associated symmetric grid *SphericalSymGrid* assumes that fields only depend on the radial coordinate  $r$ . Note that vector and tensor fields can still have components in the two angular direction.

**Warning:** Not all results of differential operators on vectorial and tensorial fields can be expressed in terms of fields that only depend on the radial coordinate  $r$ . In particular, the gradient of a vector field can only be calculated if the azimuthal component of the vector field vanishes. Similarly, the divergence of a tensor field can only be taken in special situations.

## Cylindrical coordinates

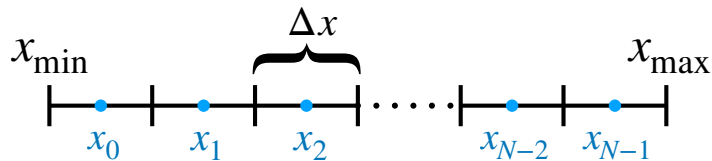
Cylindrical coordinates describe points by a radius  $r$ , an axial coordinate  $z$ , and a polar angle  $\phi$ . The conversion to ordinary Cartesian coordinates reads

$$\begin{cases} x = r \cos(\phi) \\ y = r \sin(\phi) \\ z = z \end{cases} \quad \text{for } r \in [0, \infty], z \in \mathbb{R}, \text{ and } \phi \in [0, 2\pi)$$

The associated symmetric grid *CylindricalSymGrid* assumes that fields only depend on the coordinates  $r$  and  $z$ . Vector and tensor fields still specify all components in the three-dimensional space.

**Warning:** The order of components in the vector and tensor fields defined on cylindrical grids is different than in ordinary math. While it is common to use  $(r, \phi, z)$ , we here use the order  $(r, z, \phi)$ . It might thus be best to access components by name instead of index.

### 3.1.2 Spatial discretization



The finite differences scheme used by *py-pde* is currently restricted to orthogonal coordinate systems with uniform discretization. Because of the orthogonality, each axis of the grid can be discretized independently. For simplicity, we only consider uniform grids, where the support points are spaced equidistantly along a given axis, i.e., the discretization  $\Delta x$  is constant. If a given axis covers values in a range  $[x_{\min}, x_{\max}]$ , a discretization with  $N$  support points can then be thought of as covering the axis with  $N$  equal-sized boxes; see inset. Field values are then specified for each box, i.e., the support points lie at the centers of the box:

$$x_i = x_{\min} + \left(i + \frac{1}{2}\right) \Delta x \quad \text{for } i = 0, \dots, N-1$$

$$\Delta x = \frac{x_{\max} - x_{\min}}{N}$$

which is also indicated in the inset. Differential operators are implemented using the usual second-order central difference. This requires the introducing of virtual support points at  $x_{-1}$  and  $x_N$ , which can be determined from the boundary conditions at  $x = x_{\min}$  and  $x = x_{\max}$ , respectively.

### 3.1.3 Temporal evolution

Once the fields have been discretized, the PDE reduces to a set of coupled ordinary differential equations (ODEs), which can be solved using standard methods. This reduction is also known as the method of lines. The *py-pde* package implements the simple Euler scheme and a more advanced *Runge-Kutta scheme* in the *ExplicitSolver* class. For the simple implementations of these explicit methods, the user needs to specify a time step, which will be kept fixed. One problem with explicit solvers is that they require small time steps for some PDEs, which are then often called ‘stiff PDEs’. Stiff PDEs can sometimes be solved more efficiently by using implicit methods. This package provides a simple implementation of the *Backward Euler method* in the *ImplicitSolver* class. Finally, more advanced methods are available by wrapping the `scipy.integrate.solve_ivp()` in the *ScipySolver* class.

## 3.2 Basic usage

We here describe the typical workflow to solve a PDE using *py-pde*. Throughout this section, we assume that the package has been imported using `import pde`.

### 3.2.1 Defining the geometry

The state of the system is described in a discretized geometry, also known as a *grid*. The package focuses on simple geometries, which work well for the employed finite difference scheme. Grids are defined by instance of various classes that capture the symmetries of the underlying space. In particular, the package offers Cartesian grids of 1 to 3 dimensions via *CartesianGrid*, as well as curvilinear coordinate for spherically symmetric systems in two dimension (*PolarSymGrid*) and three dimensions (*SphericalSymGrid*), as well as the special class *CylindricalSymGrid* for a cylindrical geometry which is symmetric in the angle.

All grids allow to set the size of the underlying geometry and the number of support points along each axis, which determines the spatial resolution. Moreover, most grids support periodic boundary conditions. For example, a rectangular grid with one periodic boundary condition can be specified as

```
grid = pde.CartesianGrid([[0, 10], [0, 5]], [20, 10], periodic=[True, False])
```

This grid will have a rectangular shape of 10x5 with square unit cells of side length 0.5. Note that the grid will only be periodic in the *x*-direction.

### 3.2.2 Initializing a field

Fields specifying the values at the discrete points of the grid defined in the previous section. Most PDEs discussed in the package describe a scalar variable, which can be encoded th class *ScalarField*. However, tensors with rank 1 (vectors) and rank 2 are also supported using *VectorField* and *Tensor2Field*, respectively. In any case, a field is initialized using a pre-defined grid, e.g., `field = pde.ScalarField(grid)`. Optional values allow to set the value of the grid, as well as a label that is later used in plotting, e.g., `field1 = pde.ScalarField(grid, data=1, label="Ones")`. Moreover, fields can be initialized randomly (`field2 = pde.ScalarField.random_normal(grid, mean=0.5)`) or from a mathematical expression, which may depend on the coordinates of the grid (`field3 = pde.ScalarField.from_expression(grid, "x * y")`).

All field classes support basic arithmetic operations and can be used much like numpy arrays. Moreover, they have methods for applying differential operators, e.g., the result of applying the Laplacian to a scalar field is returned by calling the method `laplace()`, which returns another instance of *ScalarField*, whereas `gradient()` returns a *VectorField*. Combining these functions with ordinary arithmetics on fields allows to represent the right hand side of many partial differential equations that appear in physics. Importantly, the differential operators work with flexible boundary conditions.

### 3.2.3 Specifying the PDE

PDEs are also instances of special classes and a number of classical PDEs are already pre-defined in the module `pde.pdes`. Moreover, the special class `PDE` allows defining PDEs by simply specifying the expression on their right hand side. To see how this works in practice, let us consider the Kuramoto–Sivashinsky equation,  $\partial_t u = -\nabla^4 u - \nabla^2 u - \frac{1}{2}|\nabla u|^2$ , which describes the time evolution of a scalar field  $u$ . A simple implementation of this equation reads

```
eq = pde.PDE({"u": "-gradient_squared(u) / 2 - laplace(u + laplace(u))"})
```

Here, the argument defines the evolution rate for all fields (in this case only  $u$ ). The expression on the right hand side can contain typical mathematical functions and the operators defined by the package.

### 3.2.4 Running the simulation

To solve the PDE, we first need to generate an initial condition, i.e., the initial values of the fields that are evolved forward in time by the PDE. This field also defined the geometry on which the PDE is solved. In the simplest case, the solution is then obtain by running

```
result = eq.solve(field, t_range=10, dt=1e-2)
```

Here, `t_range` specifies the duration over which the PDE is considered and `dt` specifies the time step. The `result` field will be defined on the same grid as the initial condition `field`, but instead contain the data value at the final time. Note that all intermediate states are discarded in the simulation above and no information about the dynamical evolution is retained. To study the dynamics, one can either analyze the evolution on the fly or store its state for subsequent analysis. Both these tasks are achieved using `trackers`, which analyze the simulation periodically. For instance, to store the state for some time points in memory, one uses

```
storage = pde.MemoryStorage()
result = eq.solve(field, t_range=10, dt=1e-3, tracker=["progress", storage.
    ↪ tracker(1)])
```

Note that we also included the special identifier "progress" in the list of trackers, which shows a progress bar during the simulation. Another useful tracker is "plot" which displays the state on the fly.

### 3.2.5 Analyzing the results

Sometimes it suffices to plot the final result, which can be done using `result.plot()`. The final result can of course also be analyzed quantitatively, e.g., using `result.average` to obtain its mean value. If the intermediate states have been saved as indicated above, they can be analyzed subsequently:

```
for time, field in storage.items():
    print(f"t={time}, field={field.magnitude}")
```

Moreover, a movie of the simulation can be created using `pde.movie(storage, filename=FILE)`, where `FILE` determines where the movie is written.

## 3.3 Advanced usage

### 3.3.1 Boundary conditions

A crucial aspect of partial differential equations are boundary conditions, which need to be specified at the domain boundaries. For the simple domains contained in *py-pde*, all boundaries are orthogonal to one of the axes in the domain, so boundary conditions need to be applied to both sides of each axis. Here, the lower side of an axis can have a different condition than the upper side. For instance, one can enforce the value of a field to be 4 at the lower side and its derivative (in the outward direction) to be 2 on the upper side using the following code:

```
bc_lower = {"value": 4}
bc_upper = {"derivative": 2}
bc = [bc_lower, bc_upper]

grid = pde.UnitGrid([16])
field = pde.ScalarField(grid)
field.laplace(bc)
```

Here, the Laplace operator applied to the field in the last line will respect the boundary conditions. Note that it suffices to give one condition if both sides of the axis require the same condition. For instance, to enforce a value of 3 on both sides, one could simply use `bc = {'value': 3}`. Vectorial boundary conditions, e.g., to calculate the vector gradient or tensor divergence, can have vectorial values for the boundary condition.

Boundary values that depend on space can be set by specifying a mathematical expression, which may depend on the coordinates of all axes:

```
# two different conditions for lower and upper end of x-axis
bc_x = [{"derivative": 0.1}, {"value": "sin(y / 2)"}]
# the same condition on the lower and upper end of the y-axis
bc_y = {"value": "sqrt(1 + cos(x))"}

grid = UnitGrid([32, 32])
field = pde.ScalarField(grid)
field.laplace(bc=[bc_x, bc_y])
```

**Warning:** To interpret arbitrary expressions, the package uses `exec()`. It should therefore not be used in a context where malicious input could occur.

Inhomogeneous values can also be specified by directly supplying an array, whose shape needs to be compatible with the boundary, i.e., it needs to have the same shape as the grid but with the dimension of the axis along which the boundary is specified removed.

There exist also special boundary conditions that impose a time-dependent value (`bc='value_expression'`) of the field or its derivative (`bc='derivative_expression'`). Beyond the spatial coordinates that are already supported for the constant conditions above, the expressions of these boundary conditions can depend on the time variable `t`. Note that PDEs need to supply the current time when setting the boundary conditions, e.g., when applying the differential operators. The pre-defined PDEs and the general class *PDE* already support time-dependent boundary conditions.

One important aspect about boundary conditions is that they need to respect the periodicity of the underlying grid. For instance, in a 2d grid with one periodic axis, the following boundary condition can be used:

```
grid = pde.UnitGrid([16, 16], periodic=[True, False])
field = pde.ScalarField(grid)
```

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```
bc = ["periodic", {"derivative": 0}]
field.laplace(bc)
```

For convenience, this typical situation can be described with the special boundary condition *natural*, e.g., calling the Laplace operator using `field.laplace("natural")` is identical to the example above. Alternatively, this condition can be called *auto\_periodic\_neumann* to stress that this chooses between periodic and Neumann boundary conditions automatically. Similarly, the special condition *auto\_periodic\_dirichlet* enforces periodic boundary conditions or Dirichlet boundary condition (vanishing value), depending on the periodicity of the underlying grid.

### 3.3.2 Custom PDE classes

To implement a new PDE in a way that all of the machinery of *py-pde* can be used, one needs to subclass *PDEBase* and overwrite at least the *evolution\_rate()* method. A simple implementation for the Kuramoto–Sivashinsky equation could read

```
class KuramotoSivashinskyPDE(PDEBase):

    def evolution_rate(self, state, t=0):
        """ numpy implementation of the evolution equation """
        state_lapacian = state.laplace(bc="auto_periodic_neumann")
        state_gradient = state.gradient(bc="auto_periodic_neumann")
        return (- state_lapacian.laplace(bc="auto_periodic_neumann")
                - state_lapacian
                - 0.5 * state_gradient.to_scalar("squared_sum"))
```

A slightly more advanced example would allow for attributes that for instance define the boundary conditions and the diffusivity:

```
class KuramotoSivashinskyPDE(PDEBase):

    def __init__(self, diffusivity=1, bc="auto_periodic_neumann", bc_laplace="auto_
↳ periodic_neumann"):
        """ initialize the class with a diffusivity and boundary conditions
        for the actual field and its second derivative """
        self.diffusivity = diffusivity
        self.bc = bc
        self.bc_laplace = bc_laplace

    def evolution_rate(self, state, t=0):
        """ numpy implementation of the evolution equation """
        state_lapacian = state.laplace(bc=self.bc)
        state_gradient = state.gradient(bc=self.bc)
        return (- state_lapacian.laplace(bc=self.bc_laplace)
                - state_lapacian
                - 0.5 * self.diffusivity * (state_gradient @ state_gradient))
```

We here replaced the call to `to_scalar('squared_sum')` by a dot product with itself (using the `@` notation), which is equivalent. Note that the numpy implementation of the right hand side of the PDE is rather slow since it runs mostly in pure python and constructs a lot of intermediate field classes. While such an implementation is helpful for testing initial ideas, actual computations should be performed with compiled PDEs as described below.

### 3.3.3 Low-level operators

This section explains how to use the low-level version of the field operators. This is necessary for the numba-accelerated implementations described above and it might be necessary to use parts of the *py-pde* package in other packages.

#### Differential operators

Applying a differential operator to an instance of *ScalarField* is as simple as calling `field.laplace(bc)`, where *bc* denotes the boundary conditions. Calling this method returns another *ScalarField*, which in this case contains the discretized Laplacian of the original field. The equivalent call using the low-level interface is

```
apply_laplace = field.grid.make_operator("laplace", bc)
laplace_data = apply_laplace(field.data)
```

Here, the first line creates a function `apply_laplace` for the given grid `field.grid` and the boundary conditions *bc*. This function can be applied to `numpy.ndarray` instances, e.g. `field.data`. Note that the result of this call is again a `numpy.ndarray`.

Similarly, a gradient operator can be defined

```
grid = UnitGrid([6, 8])
apply_gradient = grid.make_operator("gradient", bc="auto_periodic_neumann")

data = np.random.random((6, 8))
gradient_data = apply_gradient(data)
assert gradient_data.shape == (2, 6, 8)
```

Note that this example does not even use the field classes. Instead, it directly defines a *grid* and the respective gradient operator. This operator is then applied to a random field and the resulting `numpy.ndarray` represents the 2-dimensional vector field.

The `make_operator` method of the grids generally supports the following differential operators: 'laplacian', 'gradient', 'gradient\_squared', 'divergence', 'vector\_gradient', 'vector\_laplace', and 'tensor\_divergence'. However, a complete list of operators supported by a certain grid class can be obtained from the class property `GridClass.operators`. New operators can be added using the class method `GridClass.register_operator()`.

#### Field integration

The integral of an instance of *ScalarField* is usually determined by accessing the property `field.integral`. Since the integral of a discretized field is basically a sum weighted by the cell volumes, calculating the integral using only `numpy` is easy:

```
cell_volumes = field.grid.cell_volumes
integral = (field.data * cell_volumes).sum()
```

Note that `cell_volumes` is a simple number for Cartesian grids, but is an array for more complicated grids, where the cell volume is not uniform.

## Field interpolation

The fields defined in the *py-pde* package also support linear interpolation by calling `field.interpolate(point)`. Similarly to the differential operators discussed above, this call can also be translated to code that does not use the full package:

```
grid = UnitGrid([6, 8])
interpolate = grid.make_interpolator_compiled(bc="auto_periodic_neumann")

data = np.random.random((6, 8))
value = interpolate(data, np.array([3.5, 7.9]))
```

We first create a function `interpolate`, which is then used to interpolate the field data at a certain point. Note that the coordinates of the point need to be supplied as a `numpy.ndarray` and that only the interpolation at single points is supported. However, iteration over multiple points can be fast when the loop is compiled with `numba`.

## Inner products

For vector and tensor fields, *py-pde* defines inner products that can be accessed conveniently using the `@`-syntax: `field1 @ field2` determines the scalar product between the two fields. The package also provides an implementation for an `dot`-operator:

```
grid = UnitGrid([6, 8])
field1 = VectorField.random_normal(grid)
field2 = VectorField.random_normal(grid)

dot_operator = field1.make_dot_operator()

result = dot_operator(field1.data, field2.data)
assert result.shape == (6, 8)
```

Here, `result` is the data of the scalar field resulting from the dot product.

## 3.3.4 Numba-accelerated PDEs

The compiled operators introduced in the previous section can be used to implement a compiled method for the evolution rate of PDEs. As an example, we now extend the class `KuramotoSivashinskyPDE` introduced above:

```
from pde.tools.numba import jit

class KuramotoSivashinskyPDE(PDEBase):

    def __init__(self, diffusivity=1, bc="auto_periodic_neumann", bc_laplace="auto_
↳ periodic_neumann"):
        """ initialize the class with a diffusivity and boundary conditions
        for the actual field and its second derivative """
        self.diffusivity = diffusivity
        self.bc = bc
        self.bc_laplace = bc_laplace

    def evolution_rate(self, state, t=0):
        """ numpy implementation of the evolution equation """
```

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```

state_lapacian = state.laplace(bc=self.bc)
state_gradient = state.gradient(bc="auto_periodic_neumann")
return (- state_lapacian.laplace(bc=self.bc_laplace)
        - state_lapacian
        - 0.5 * self.diffusivity * (state_gradient @ state_gradient))

def _make_pde_rhs_numba(self, state):
    """ the numba-accelerated evolution equation """
    # make attributes locally available
    diffusivity = self.diffusivity

    # create operators
    laplace_u = state.grid.make_operator("laplace", bc=self.bc)
    gradient_u = state.grid.make_operator("gradient", bc=self.bc)
    laplace2_u = state.grid.make_operator("laplace", bc=self.bc_laplace)
    dot = VectorField(state.grid).make_dot_operator()

    @jit
    def pde_rhs(state_data, t=0):
        """ compiled helper function evaluating right hand side """
        state_lapacian = laplace_u(state_data)
        state_grad = gradient_u(state_data)
        return (- laplace2_u(state_lapacian)
                - state_lapacian
                - diffusivity / 2 * dot(state_grad, state_grad))

    return pde_rhs

```

To activate the compiled implementation of the evolution rate, we simply have to overwrite the `_make_pde_rhs_numba()` method. This method expects an example of the state class (e.g., an instance of `ScalarField`) and returns a function that calculates the evolution rate. The `state` argument is necessary to define the grid and the dimensionality of the data that the returned function is supposed to be handling. The implementation of the compiled function is split in several parts, where we first copy the attributes that are required by the implementation. This is necessary, since numba freezes the values when compiling the function, so that in the example above the diffusivity cannot be altered without recompiling. In the next step, we create all operators that we need subsequently. Here, we use the boundary conditions defined by the attributes, which requires two different laplace operators, since their boundary conditions might differ. In the last step, we define the actual implementation of the evolution rate as a local function that is compiled using the `jit` decorator. Here, we use the implementation shipped with *py-pde*, which sets some default values. However, we could have also used the usual numba implementation. It is important that the implementation of the evolution rate only uses python constructs that numba can compile.

One advantage of the numba compiled implementation is that we can now use loops, which will be much faster than their python equivalents. For instance, we could have written the dot product in the last line as an explicit loop:

```

[...]

def _make_pde_rhs_numba(self, state):
    """ the numba-accelerated evolution equation """
    # make attributes locally available
    diffusivity = self.diffusivity

    # create operators
    laplace_u = state.grid.make_operator("laplace", bc=self.bc)
    gradient_u = state.grid.make_operator("gradient", bc=self.bc)
    laplace2_u = state.grid.make_operator("laplace", bc=self.bc_laplace)

```

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```
dot = VectorField(state.grid).make_dot_operator()
dim = state.grid.dim

@jit
def pde_rhs(state_data, t=0):
    """ compiled helper function evaluating right hand side """
    state_lapacian = laplace_u(state_data)
    state_grad = gradient_u(state_data)
    result = - laplace2_u(state_lapacian) - state_lapacian

    for i in range(state_data.size):
        for j in range(dim):
            result.flat[i] -= diffusivity / 2 * state_grad[j].flat[i]**2

    return result

return pde_rhs
```

Here, we extract the total number of elements in the state using its `size` attribute and we obtain the dimensionality of the space from the grid attribute `dim`. Note that we access numpy arrays using their `flat` attribute to provide an implementation that works for all dimensions.

### 3.3.5 Configuration parameters

Configuration parameters affect how the package behaves. They can be set using a dictionary-like interface of the configuration `config`, which can be imported from the base package. Here is a list of all configuration options that can be adjusted in the package:

**numba.debug** Determines whether numba used the debug mode for compilation. If enabled, this emits extra information that might be useful for debugging. **(Default value: False)**

**numba.fastmath** Determines whether the fastmath flag is set during compilation. This affects the precision of the mathematical calculations. **(Default value: True)**

**numba.parallel** Determines whether multiple cores are used in numba-compiled code. **(Default value: True)**

**numba.parallel\_threshold** Minimal number of support points before multithreading or multiprocessing is enabled in the numba compilations. **(Default value: 65536)**

---

**Tip:** To disable parallel computing in the package, the following code could be added to the start of the script:

```
from pde import config
config['numba.parallel'] = False

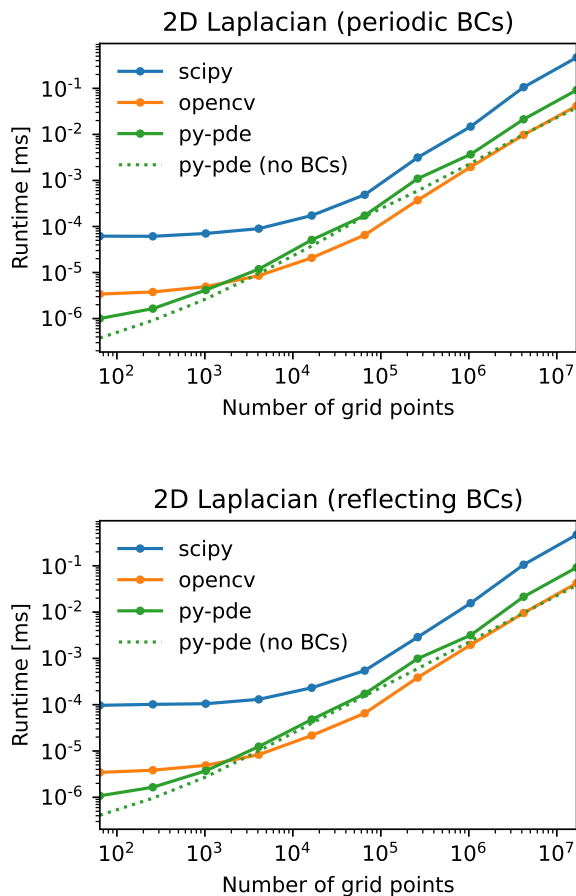
# actual code using py-pde
```

---

## 3.4 Performance

### 3.4.1 Measuring performance

The performance of the *py-pde* package depends on many details and general statements are thus difficult to make. However, since the core operators are just-in-time compiled using *numba*, many operations of the package proceed at performances close to most compiled languages. For instance, a simple Laplace operator applied to fields defined on a Cartesian grid has performance that is similar to the operators supplied by the popular *OpenCV* package. The following figures illustrate this by showing the duration of evaluating the Laplacian on grids of increasing number of support points for two different boundary conditions (lower duration is better):



Note that the call overhead is lower in the *py-pde* package, so that the performance on small grids is particularly good. However, realistic use-cases probably need more complicated operations and it is thus always necessary to profile the respective code. This can be done using the function `estimate_computation_speed()` or the traditional `timeit`, `profile`, or even more sophisticated profilers like *pyinstrument*.

### 3.4.2 Improving performance

Factors influencing the performance of the package include the compiler used for `numpy`, `scipy`, and of course `numba`. Moreover, the BLAS and LAPACK libraries might make a difference. The package has some basic support for multi-threading, which can be accelerated using the *Threading Building Blocks* library. Finally, it can help to install the intel short vector math library (SVML). However, this is not distributed with **macports** and might thus be more difficult to enable.

Using **macports**, one could for instance install the following variants of typical packages

```
port install py37-numpy +gcc8+openblas
port install py37-scipy +gcc8+openblas
port install py37-numba +tbb
```

## 3.5 Contributing code

### 3.5.1 Structure of the package

The functionality of the `pde` package is split into multiple sub-package. The domain, together with its symmetries, periodicities, and discretizations, is described by classes defined in `grids`. Discretized fields are represented by classes in `fields`, which have methods for differential operators with various boundary conditions collected in `boundaries`. The actual pdes are collected in `pdes` and the respective solvers are defined in `solvers`.

### 3.5.2 Extending functionality

All code is build on a modular basis, making it easy to introduce new classes that integrate with the rest of the package. For instance, it is simple to define a new partial differential equation by subclassing `PDEBase`. Alternatively, PDEs can be defined by specifying their evolution rates using mathematical expressions by creating instances of the class `PDE`. Moreover, new grids can be introduced by subclassing `GridBase`. It is also possible to only use parts of the package, e.g., the discretized differential operators from `operators`.

New operators can be associated with grids by registering them using `register_operator()`. For instance, to create a new operator for the cylindrical grid one needs to define a factory function that creates the operator. This factory function takes an instance of `Boundaries` as an argument and returns a function that takes as an argument the actual data array for the grid. Note that the grid itself is an attribute of `Boundaries`. This operator would be registered with the grid by calling `CylindricalSymGrid.register_operator("operator", make_operator)`, where the first argument is the name of the operator and the second argument is the factory function.

### 3.5.3 Design choices

The data layout of field classes (subclasses of `FieldBase`) was chosen to allow for a simple decomposition of different fields and tensor components. Consequently, the data is laid out in memory such that spatial indices are last. For instance, the data of a vector field `field` defined on a 2d Cartesian grid will have three dimensions and can be accessed as `field.data[vector_component, x, y]`, where `vector_component` is either 0 or 1.

### 3.5.4 Coding style

The coding style is enforced using `isort` and `black`. Moreover, we use `Google Style docstrings`, which might be best [learned by example](#). The documentation, including the docstrings, are written using `reStructuredText`, with examples in the following [cheatsheet](#). To ensure the integrity of the code, we also try to provide many test functions, which are typically contained in separate modules in sub-packages called `tests`. These tests can be ran using scripts in the `tests` subfolder in the root folder. This folder also contain a script `tests_types.sh`, which uses `mypy` to check the consistency of the python type annotations. We use these type annotations for additional documentation and they have also already been useful for finding some bugs.

We also have some conventions that should make the package more consistent and thus easier to use. For instance, we try to use `properties` instead of getter and setter methods as often as possible. Because we use a lot of `numba` just-in-time compilation to speed up computations, we need to pass around (compiled) functions regularly. The names of the methods and functions that make such functions, i.e. that return callables, should start with `'make_*` where the wildcard should describe the purpose of the function being created.

### 3.5.5 Running unit tests

The `pde` package contains several unit tests, typically contained in sub-module `tests` in the folder of a given module. These tests ensure that basic functions work as expected, in particular when code is changed in future versions. To run all tests, there are a few convenience scripts in the root directory `tests`. The most basic script is `tests_run.sh`, which uses `pytest` to run the tests in the sub-modules of the `pde` package. Clearly, the python package `pytest` needs to be installed. There are also additional scripts that for instance run tests in parallel (need the python package `pytest-xdist` installed), measure test coverage (need package `pytest-cov` installed), and make simple performance measurements. Moreover, there is a script `test_types.sh`, which uses `mypy` to check the consistency of the python type annotations and there is a script `format_code.sh`, which formats the code automatically to adhere to our style.

Before committing a change to the code repository, it is good practice to run the tests, check the type annotations, and the coding style with the scripts described above.

## 3.6 Citing the package

To cite or reference *py-pde* in other work, please refer to the [publication in the Journal of Open Source Software](#). Here are the respective bibliographic records in Bibtex format:

```
@article{py-pde,
  Author = {David Zwicker},
  Doi = {10.21105/joss.02158},
  Journal = {Journal of Open Source Software},
  Number = {48},
  Pages = {2158},
  Publisher = {The Open Journal},
  Title = {py-pde: A Python package for solving partial differential equations},
  Url = {https://doi.org/10.21105/joss.02158},
  Volume = {5},
  Year = {2020}
}
```

and in RIS format:

```
TY  - JOUR
AU  - Zwicker, David
JO  - Journal of Open Source Software
```

(continues on next page)

(continued from previous page)

IS	-	48
SP	-	2158
PB	-	The Open Journal
T1	-	py-pde: A Python package for solving partial differential equations
UR	-	<a href="https://doi.org/10.21105/joss.02158">https://doi.org/10.21105/joss.02158</a>
VL	-	5
PY	-	2020

## 3.7 Code of Conduct

### 3.7.1 Our Pledge

In the interest of fostering an open and welcoming environment, we as contributors and maintainers pledge to making participation in our project and our community a harassment-free experience for everyone, regardless of age, body size, disability, ethnicity, sex characteristics, gender identity and expression, level of experience, education, socio-economic status, nationality, personal appearance, race, religion, or sexual identity and orientation.

### 3.7.2 Our Standards

Examples of behavior that contributes to creating a positive environment include:

- Using welcoming and inclusive language
- Being respectful of differing viewpoints and experiences
- Gracefully accepting constructive criticism
- Focusing on what is best for the community
- Showing empathy towards other community members

Examples of unacceptable behavior by participants include:

- The use of sexualized language or imagery and unwelcome sexual attention or advances
- Trolling, insulting/derogatory comments, and personal or political attacks
- Public or private harassment
- Publishing others' private information, such as a physical or electronic address, without explicit permission
- Other conduct which could reasonably be considered inappropriate in a professional setting

### 3.7.3 Our Responsibilities

Project maintainers are responsible for clarifying the standards of acceptable behavior and are expected to take appropriate and fair corrective action in response to any instances of unacceptable behavior.

Project maintainers have the right and responsibility to remove, edit, or reject comments, commits, code, wiki edits, issues, and other contributions that are not aligned to this Code of Conduct, or to ban temporarily or permanently any contributor for other behaviors that they deem inappropriate, threatening, offensive, or harmful.

### 3.7.4 Scope

This Code of Conduct applies both within project spaces and in public spaces when an individual is representing the project or its community. Examples of representing a project or community include using an official project e-mail address, posting via an official social media account, or acting as an appointed representative at an online or offline event. Representation of a project may be further defined and clarified by project maintainers.

### 3.7.5 Enforcement

Instances of abusive, harassing, or otherwise unacceptable behavior may be reported by contacting the project team at [david.zwicker@ds.mpg.de](mailto:david.zwicker@ds.mpg.de). All complaints will be reviewed and investigated and will result in a response that is deemed necessary and appropriate to the circumstances. The project team is obligated to maintain confidentiality with regard to the reporter of an incident. Further details of specific enforcement policies may be posted separately.

Project maintainers who do not follow or enforce the Code of Conduct in good faith may face temporary or permanent repercussions as determined by other members of the project's leadership.

### 3.7.6 Attribution

This Code of Conduct is adapted from the [Contributor Covenant](https://www.contributor-covenant.org/version/1/4/code-of-conduct.html), version 1.4, available at <https://www.contributor-covenant.org/version/1/4/code-of-conduct.html>

For answers to common questions about this code of conduct, see <https://www.contributor-covenant.org/faq>



## REFERENCE MANUAL

The py-pde package provides classes and methods for solving partial differential equations.

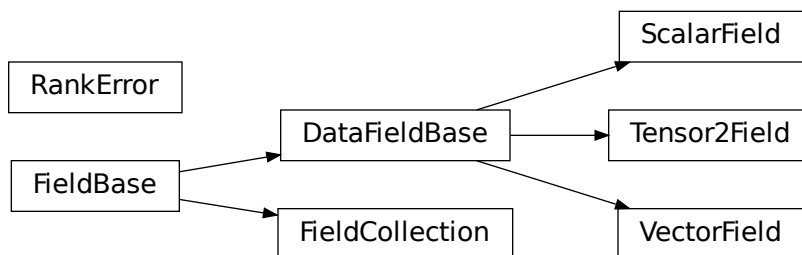
**Subpackages:**

### 4.1 `pde.fields` package

Defines fields, which contain the actual data stored on a discrete grid.

<i>ScalarField</i>	Scalar field discretized on a grid
<i>VectorField</i>	Vector field discretized on a grid
<i>Tensor2Field</i>	Tensor field of rank 2 discretized on a grid
<i>FieldCollection</i>	Collection of fields defined on the same grid

Inheritance structure of the classes:



The details of the classes are explained below:

### 4.1.1 `pde.fields.base` module

Defines base classes of fields, which are discretized on grids

```
class DataFieldBase (grid: GridBase, data: Optional[Union[int, float, complex, numpy.ndarray,  
Sequence[NumberOrArray], Sequence[Sequence[Any]], str]] = 'zeros', *, label: str =  
None, dtype=None, with_ghost_cells: bool = False)
```

Bases: `pde.fields.base.FieldBase`

abstract base class for describing fields of single entities

#### Parameters

- **grid** (*GridBase*) – Grid defining the space on which this field is defined.
- **data** (Number or `ndarray`, optional) – Field values at the support points of the grid. The flag `with_ghost_cells` determines whether this data array contains values for the ghost cells, too. The resulting field will contain real data unless the `data` argument contains complex values. Special values are “zeros” or `None`, initializing the field with zeros, and “empty”, just allocating memory with unspecified values.
- **label** (*str*, optional) – Name of the field
- **dtype** (*numpy dtype*) – The data type of the field. All the numpy dtypes are supported. If omitted, it will be determined from `data` automatically.
- **with\_ghost\_cells** (*bool*) – Indicates whether the ghost cells are included in data

```
add_interpolated (point: numpy.ndarray, amount: Union[int, float, complex, numpy.ndarray,  
Sequence[NumberOrArray], Sequence[Sequence[Any]]]) → None
```

deprecated alias of method `insert`

```
property average: Union[int, float, complex, numpy.ndarray]
```

determine the average of data

This is calculated by integrating each component of the field over space and dividing by the grid volume

```
copy (*, label: str = None, dtype=None) → TDataField
```

return a copy of the data, but not of the grid

#### Parameters

- **label** (*str*, optional) – Name of the returned field
- **dtype** (*numpy dtype*) – The data type of the field. If omitted, it will be determined from `data` automatically or the dtype of the current field is used.

```
property data_shape: Tuple[int, ...]
```

the shape of the data at each grid point

Type `tuple`

```
property fluctuations: Union[int, float, complex, numpy.ndarray]
```

fluctuations over the entire space.

The fluctuations are defined as the standard deviation of the data scaled by the cell volume. This definition makes the fluctuations independent of the discretization. It corresponds to the physical scaling available in the `random_normal()`.

**Returns** A tensor with the same rank of the field, specifying the fluctuations of each component of the tensor field individually. Consequently, a simple scalar is returned for a `ScalarField`.

**Return type** `ndarray`

Type `ndarray`

**classmethod from\_state** (*attributes: Dict[str, Any], data: numpy.ndarray = None*) → *DataFieldBase*  
create a field from given state.

#### Parameters

- **attributes** (*dict*) – The attributes that describe the current instance
- **data** (*ndarray*, optional) – Data values at the support points of the grid defining the field

**get\_boundary\_values** (*axis: int, upper: bool, bc: Optional[Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase, Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]], Sequence[Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase, Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]]]]] = None*) → *NumberOrArray*

get the field values directly on the specified boundary

#### Parameters

- **axis** (*int*) – The axis perpendicular to the boundary
- **upper** (*bool*) – Whether the boundary is at the upper side of the axis
- **bc** – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by ‘periodic’). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value NUM (specified by {‘value’: NUM}) and Neumann conditions enforcing the value DERIV for the derivative in the normal direction (specified by {‘derivative’: DERIV}) are supported. Note that the special value ‘natural’ imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#). If the special value *None* is given, no boundary conditions are enforced. The user then needs to ensure that the ghost cells are set accordingly.

**Returns** The discretized values on the boundary

**Return type** *ndarray*

**classmethod get\_class\_by\_rank** (*rank: int*) → *Type[DataFieldBase]*  
return a *DataFieldBase* subclass describing a field with a given rank

**Parameters** **rank** (*int*) – The rank of the tensor field

**get\_image\_data** (*scalar: str = 'auto', transpose: bool = False, \*\*kwargs*) → *Dict[str, Any]*  
return data for plotting an image of the field

#### Parameters

- **scalar** (*str or int*) – The method for extracting scalars as described in *DataFieldBase.to\_scalar()*.
- **transpose** (*bool*) – Determines whether the transpose of the data should be plotted
- **\*\*kwargs** – Additional parameters are forwarded to *grid.get\_image\_data*

**Returns** Information useful for plotting an image of the field

**Return type** *dict*

**get\_line\_data** (*scalar: str = 'auto', extract: str = 'auto'*) → *Dict[str, Any]*  
return data for a line plot of the field

#### Parameters

- **scalar** (*str or int*) – The method for extracting scalars as described in *DataFieldBase.to\_scalar()*.

- **extract** (*str*) – The method used for extracting the line data. See the docstring of the grid method *get\_line\_data* to find supported values.

**Returns** Information useful for performing a line plot of the field

**Return type** `dict`

**get\_vector\_data** (*\*\*kwargs*) → `Dict[str, Any]`

return data for a vector plot of the field

**Parameters** *\*\*kwargs* – Additional parameters are forwarded to *grid.get\_image\_data*

**Returns** Information useful for plotting an vector field

**Return type** `dict`

**insert** (*point*: `numpy.ndarray`, *amount*: `Union[int, float, complex, numpy.ndarray, Sequence[NumberOrArray], Sequence[Sequence[Any]]]`) → `None`

adds an (integrated) value to the field at an interpolated position

**Parameters**

- **point** (`ndarray`) – The point inside the grid where the value is added. This is given in grid coordinates.
- **amount** (`Number` or `ndarray`) – The amount that will be added to the field. The value describes an integrated quantity (given by the field value times the discretization volume). This is important for consistency with different discretizations and in particular grids with non-uniform discretizations.

**abstract property integral**: `Union[int, float, complex, numpy.ndarray]`

**interpolate** (*point*: `numpy.ndarray`, *\**, *backend*: *str* = 'numba', *method*: *str* = 'linear', *fill*: `Optional[Number]` = `None`, *\*\*kwargs*) → `NumberOrArray`

interpolate the field to points between support points

**Parameters**

- **point** (`ndarray`) – The points at which the values should be obtained. This is given in grid coordinates.
- **backend** (*str*) – The accepted values “scipy” and “numba” determine the backend that is used for the interpolation.
- **method** (*str*) – Determines the method being used for interpolation. Typical values that are “nearest” and “linear”, but the supported values depend on the chosen *backend*.
- **fill** (`Number`, *optional*) – Determines how values out of bounds are handled. If `None`, a `ValueError` is raised when out-of-bounds points are requested. Otherwise, the given value is returned.
- **\*\*kwargs** – Additional keyword arguments are forwarded to the method `DataFieldBase.make_interpolator()`.

**Returns** the values of the field

**Return type** `ndarray`

**interpolate\_to\_grid** (*grid*: `GridBase`, *\**, *backend*: *str* = 'numba', *method*: *str* = 'linear', *fill*: `Optional[Number]` = `None`, *label*: *str* = `None`) → `TDataField`

interpolate the data of this field to another grid.

**Parameters**

- **grid** (`GridBase`) – The grid of the new field onto which the current field is interpolated.

- **backend** (*str*) – The accepted values “scipy” and “numba” determine the backend that is used for the interpolation.
- **method** (*str*) – Determines the method being used for interpolation. Typical values that are “nearest” and “linear”, but the supported values depend on the chosen *backend*.
- **fill** (*Number*, *optional*) – Determines how values out of bounds are handled. If *None*, a *ValueError* is raised when out-of-bounds points are requested. Otherwise, the given value is returned.
- **label** (*str*, *optional*) – Name of the returned field

**Returns** Field of the same rank as the current one.

**property magnitude:** `float`

determine the magnitude of the field.

This is calculated by getting a scalar field using the default arguments of the `to_scalar()` method, averaging the result over the whole grid, and taking the absolute value.

**Type** `float`

**make\_interpolator** (*method: str = 'linear', \*, fill: Number = None, backend: str = 'numba', \*\*kwargs*) → `Callable[[numpy.ndarray, numpy.ndarray], NumberOrArray]`

returns a function that can be used to interpolate values.

#### Parameters

- **backend** (*str*) – The accepted values *scipy* and *numba* determine the backend that is used for the interpolation.
- **method** (*str*) – Determines the method being used for interpolation. Typical values that are “nearest” and “linear”, but the supported values depend on the chosen *backend*.
- **fill** (*Number*, *optional*) – Determines how values out of bounds are handled. If *None*, a *ValueError* is raised when out-of-bounds points are requested. Otherwise, the given value is returned.
- **\*\*kwargs** – Additional keyword arguments are passed to the individual interpolator methods and can be used to further affect the behavior.

The *scipy* implementations use `scipy.interpolate.RegularGridInterpolator` and thus do not respect boundary conditions. Additional keyword arguments are directly forwarded to the constructor of *RegularGridInterpolator*.

The *numba* implementation respect boundary conditions, which can be set using the *bc* keywords argument. Supported values are the same as for the operators, e.g., the Laplacian. If no boundary conditions are specified, natural boundary conditions are assumed, which are periodic conditions for periodic axes and Neumann conditions otherwise.

**Returns** A function which returns interpolated values when called with arbitrary positions within the space of the grid.

**plot** (*kind: str = 'auto', \*args, title: str = None, filename: str = None, action: str = 'auto', ax\_style: Optional[Dict[str, Any]] = None, fig\_style: Optional[Dict[str, Any]] = None, ax=None, \*\*kwargs*) → `PlotReference`

visualize the field

#### Parameters

- **kind** (*str*) – Determines the visualizations. Supported values are *image*, *line*, *vector*, or *interactive*. Alternatively, *auto* determines the best visualization based on the field itself.
- **title** (*str*) – Title of the plot. If omitted, the title might be chosen automatically.

- **filename** (*str*, *optional*) – If given, the plot is written to the specified file.
- **action** (*str*) – Decides what to do with the final figure. If the argument is set to *show*, `matplotlib.pyplot.show()` will be called to show the plot. If the value is *none*, the figure will be created, but not necessarily shown. The value *close* closes the figure, after saving it to a file when *filename* is given. The default value *auto* implies that the plot is shown if it is not a nested plot call.
- **ax\_style** (*dict*) – Dictionary with properties that will be changed on the axis after the plot has been drawn by calling `matplotlib.pyplot.setp()`. A special item in this dictionary is *use\_offset*, which is flag that can be used to control whether offset are shown along the axes of the plot.
- **fig\_style** (*dict*) – Dictionary with properties that will be changed on the figure after the plot has been drawn by calling `matplotlib.pyplot.setp()`. For instance, using `fig_style={'dpi': 200}` increases the resolution of the figure.
- **ax** (`matplotlib.axes.Axes`) – Figure axes to be used for plotting. The special value “create” creates a new figure, while “reuse” attempts to reuse an existing figure, which is the default.
- **\*\*kwargs** – All additional keyword arguments are forwarded to the actual plotting function.

**Returns** Instance that contains information to update the plot with new data later.

**Return type** `PlotReference`

**classmethod random\_colored** (*grid*: `GridBase`, *exponent*: *float* = 0, *scale*: *float* = 1, \*, *label*: *str* = None, *dtype*=None, *rng*: *Optional*[`numpy.random._generator.Generator`] = None) → `DataFieldBase`

create a field of random values with colored noise

The spatially correlated values obey

$$\langle c_i(\mathbf{k})c_j(\mathbf{k}') \rangle = \Gamma^2 |\mathbf{k}|^\nu \delta_{ij} \delta(\mathbf{k} - \mathbf{k}')$$

in spectral space. The special case  $\nu = 0$  corresponds to white noise. Note that the components of vector or tensor fields are uncorrelated.

#### Parameters

- **grid** (`GridBase`) – Grid defining the space on which this field is defined
- **exponent** (*float*) – Exponent  $\nu$  of the power spectrum
- **scale** (*float*) – Scaling factor  $\Gamma$  determining noise strength
- **label** (*str*, *optional*) – Name of the field
- **dtype** (*numpy dtype*) – The data type of the field. If omitted, it defaults to *double*.
- **rng** (`Generator`) – Random number generator (default: `default_rng()`)

**classmethod random\_harmonic** (*grid*: `GridBase`, *modes*: *int* = 3, *harmonic*=<ufunc 'cos'>, *axis\_combination*=<ufunc 'multiply'>, \*, *label*: *typing.str* = None, *dtype*=None, *rng*: *typing.Optional*[`numpy.random._generator.Generator`] = None) → `DataFieldBase`

create a random field build from harmonics

The resulting fields will be highly correlated in space and can thus serve for testing differential operators.

With the default settings, the resulting field  $c_i(\mathbf{x})$  is given by

$$c_i(\mathbf{x}) = \prod_{\alpha=1}^N \sum_{j=1}^M a_{ij\alpha} \cos\left(\frac{2\pi x_\alpha}{jL_\alpha}\right),$$

where  $N$  is the number of spatial dimensions, each with length  $L_\alpha$ ,  $M$  is the number of modes given by *modes*, and  $a_{ij\alpha}$  are random amplitudes, chosen from a uniform distribution over the interval  $[0, 1]$ .

Note that the product could be replaced by a sum when *axis\_combination* = *numpy.add* and the *cos()* could be any other function given by the parameter *harmonic*.

#### Parameters

- **grid** (*GridBase*) – Grid defining the space on which this field is defined
- **modes** (*int*) – Number  $M$  of harmonic modes
- **harmonic** (*callable*) – Determines which harmonic function is used. Typical values are *numpy.sin()* and *numpy.cos()*, which basically relate to different boundary conditions applied at the grid boundaries.
- **axis\_combination** (*callable*) – Determines how values from different axis are combined. Typical choices are *numpy.multiply()* and *numpy.add()* resulting in products and sums of the values along axes, respectively.
- **label** (*str*, *optional*) – Name of the field
- **dtype** (*numpy dtype*) – The data type of the field. If omitted, it defaults to *double*.
- **rng** (*Generator*) – Random number generator (default: *default\_rng()*)

**classmethod random\_normal** (*grid*: *GridBase*, *mean*: *float* = 0, *std*: *float* = 1, \*, *scaling*: *str* = 'none', *label*: *str* = None, *dtype*: None, *rng*: *Optional*[*numpy.random.\_generator.Generator*] = None) → *DataFieldBase*

create field with normal distributed random values

These values are uncorrelated in space. A complex field is returned when either *mean* or *std* is a complex number. In this case, the real and imaginary parts of these arguments are used to determine the distribution of the real and imaginary parts of the resulting field. Consequently, *ScalarField.random\_normal(grid, 0, 1 + 1j)* creates a complex field where the real and imaginary parts are chosen from a standard normal distribution.

#### Parameters

- **grid** (*GridBase*) – Grid defining the space on which this field is defined
- **mean** (*float*) – Mean of the Gaussian distribution
- **std** (*float*) – Standard deviation of the Gaussian distribution.
- **scaling** (*str*) – Determines how the values are scaled. Possible choices are 'none' (values are drawn from a normal distribution with given mean and standard deviation) or 'physical' (the variance of the random number is scaled by the inverse volume of the grid cell; this is for instance useful for concentration fields, which vary less in larger volumes).
- **label** (*str*, *optional*) – Name of the field
- **dtype** (*numpy dtype*) – The data type of the field. If omitted, it defaults to *double* if both *mean* and *std* are real, otherwise it is *complex*.
- **rng** (*Generator*) – Random number generator (default: *default\_rng()*)

**classmethod random\_uniform** (*grid*: [GridBase](#), *vmin*: *float* = 0, *vmax*: *float* = 1, \*, *label*: *str* = None, *dtype*: None, *rng*: *Optional*[[numpy.random.\\_generator.Generator](#)] = None) → [DataFieldBase](#)

create field with uniform distributed random values

These values are uncorrelated in space.

#### Parameters

- **grid** ([GridBase](#)) – Grid defining the space on which this field is defined
- **vmin** (*float*) – Smallest possible random value
- **vmax** (*float*) – Largest random value
- **label** (*str*, *optional*) – Name of the field
- **dtype** (*numpy dtype*) – The data type of the field. If omitted, it defaults to *double* if both *vmin* and *vmax* are real, otherwise it is *complex*.
- **rng** ([Generator](#)) – Random number generator (default: `default_rng()`)

**rank**: *int*

**set\_ghost\_cells** (*bc*: *Union*[*Dict*[*str*, *Union*[*Dict*, *str*, [BCBase](#)]], *Dict*, *str*, [BCBase](#), *Tuple*[*Union*[*Dict*, *str*, [BCBase](#)], *Union*[*Dict*, *str*, [BCBase](#)]], *Sequence*[*Union*[*Dict*[*str*, *Union*[*Dict*, *str*, [BCBase](#)]], *Dict*, *str*, [BCBase](#), *Tuple*[*Union*[*Dict*, *str*, [BCBase](#)], *Union*[*Dict*, *str*, [BCBase](#)]]]], \*, *args*: None) → None

set the boundary values on virtual points for all boundaries

#### Parameters

- **bc** (*str* or *list* or *tuple* or *dict*) – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by 'periodic'). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value NUM (specified by {'value': NUM}) and Neumann conditions enforcing the value DERIV for the derivative in the normal direction (specified by {'derivative': DERIV}) are supported. Note that the special value 'natural' imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#).
- **args** – Additional arguments that might be supported by special boundary conditions.

**smooth** (*sigma*: *float* = 1, \*, *out*: *Optional*[[TDataField](#)] = None, *label*: *str* = None) → [TDataField](#)  
applies Gaussian smoothing with the given standard deviation

This function respects periodic boundary conditions of the underlying grid, using reflection when no periodicity is specified.

**sigma** (*float*): Gives the standard deviation of the smoothing in real length units (default: 1)

**out** ([FieldBase](#), *optional*): Optional field into which the smoothed data is stored. Setting this to the input field enables in-place smoothing.

**label** (*str*, *optional*): Name of the returned field

**Returns** Field with smoothed data. This is stored at *out* if given.

**abstract to\_scalar** (*scalar*: *str* = 'auto', \*, *label*: *str* = None) → [ScalarField](#)

**classmethod unserialize\_attributes** (*attributes: Dict[str, str]*) → Dict[str, Any]  
 unserializes the given attributes

**Parameters** *attributes* (*dict*) – The serialized attributes

**Returns** The unserialized attributes

**Return type** *dict*

**class FieldBase** (*grid: GridBase, data: numpy.ndarray, \*, label: str = None*)

Bases: *object*

abstract base class for describing (discretized) fields

**Parameters**

- **grid** (*GridBase*) – Grid defining the space on which this field is defined
- **data** (*ndarray*, optional) – Field values at the support points of the grid and the ghost cells
- **label** (*str*, optional) – Name of the field

**apply** (*func: Callable, out: Optional[TField] = None, label: str = None*) → TField

applies a function to the data and returns it as a field

**Parameters**

- **func** (*callable or str*) – The (vectorized) function being applied to the data or the name of an operator that is defined for the grid of this field.
- **out** (*FieldBase*, optional) – Optional field into which the data is written
- **label** (*str*, optional) – Name of the returned field

**Returns** Field with new data. This is stored at *out* if given.

**assert\_field\_compatible** (*other: FieldBase, accept\_scalar: bool = False*)

checks whether *other* is compatible with the current field

**Parameters**

- **other** (*FieldBase*) – The other field this one is compared to
- **accept\_scalar** (*bool*, optional) – Determines whether it is acceptable that *other* is an instance of *ScalarField*.

**property attributes: Dict[str, Any]**

describes the state of the instance (without the data)

**Type** *dict*

**property attributes\_serialized: Dict[str, str]**

serialized version of the attributes

**Type** *dict*

**conjugate** () → TField

returns complex conjugate of the field

**abstract copy** (\*, *label: str = None, dtype=None*) → TField

**property data: numpy.ndarray**

discretized data at the support points

**Type** *ndarray*

**property dtype**

returns the numpy dtype of the underlying data

**classmethod** `from_file(filename: str) → FieldBase`

create field from data stored in a file

Field can be written to a file using `FieldBase.to_file()`.

---

### Example

Write a field to a file and then read it back:

```
field = pde.ScalarField(...)
field.write_to("test.hdf5")

field_copy = pde.FieldBase.from_file("test.hdf5")
```

---

**Parameters** `filename` (*str*) – Path to the file being read

**Returns** The field with the appropriate sub-class

**Return type** *FieldBase*

**classmethod** `from_state(attributes: Dict[str, Any], data: numpy.ndarray = None) → FieldBase`

create a field from given state.

### Parameters

- **attributes** (*dict*) – The attributes that describe the current instance
- **data** (*ndarray*, optional) – Data values at the support points of the grid defining the field

**abstract** `get_image_data()` → *Dict*[*str*, *Any*]

**abstract** `get_line_data(scalar: str = 'auto', extract: str = 'auto')` → *Dict*[*str*, *Any*]

**property** `grid: pde.grids.base.GridBase`

The grid on which the field is defined

Type *GridBase*

**property** `imag: pde.fields.base.TField`

Imaginary part of the field

Type *FieldBase*

**property** `is_complex: bool`

whether the field contains real or complex data

Type *bool*

**property** `label: Optional[str]`

the name of the field

Type *str*

**abstract** `plot(*args, **kwargs)`

**plot\_interactive** (*viewer\_args: Optional[Dict[str, Any]] = None, \*\*kwargs*)

create an interactive plot of the field using `napari`

For a detailed description of the launched program, see the [napari webpage](#).

### Parameters

- **viewer\_args** (*dict*) – Arguments passed to `napari.viewer.Viewer` to affect the viewer.
- **\*\*kwargs** – Extra arguments passed to the plotting function

**property** `real`: `pde.fields.base.TField`

Real part of the field

Type `FieldBase`

**to\_file** (*filename: str, \*\*kwargs*)

store field in a file

The extension of the filename determines what format is being used. If it ends in `.h5` or `.hdf`, the Hierarchical Data Format is used. The other supported format are images, where only the most typical formats are supported.

To load the field back from the file, you may use `FieldBase.from_file()`.

---

### Example

Write a field to a file and then read it back:

```
field = pde.ScalarField(...)
field.write_to("test.hdf5")

field_copy = pde.FieldBase.from_file("test.hdf5")
```

---

### Parameters

- **filename** (*str*) – Path where the data is stored
- **\*\*kwargs** – Additional parameters may be supported for some formats

**classmethod** `unserialize_attributes` (*attributes: Dict[str, str]*) → `Dict[str, Any]`

unserializes the given attributes

**Parameters** `attributes` (*dict*) – The serialized attributes

**Returns** The unserialized attributes

**Return type** `dict`

**property** `writeable`: `bool`

whether the field data can be changed or not

Type `bool`

**exception** `RankError`

Bases: `TypeError`

error indicating that the field has the wrong rank

### 4.1.2 `pde.fields.collection` module

Defines a collection of fields to represent multiple fields defined on a common grid.

**class** `FieldCollection` (*fields*: `Sequence[DataFieldBase]`, \*, *copy\_fields*: `bool` = `False`, *label*: `str` = `None`,  
*labels*: `Optional[List[str]]` = `None`, *dtype*=`None`)

Bases: `pde.fields.base.FieldBase`

Collection of fields defined on the same grid

Note that all fields in the same collection must have the same data type. This might lead to upcasting, where for instance a combination of a real-valued and a complex-valued field will be both stored as complex fields.

#### Parameters

- **fields** – Sequence of the individual fields
- **copy\_fields** (`bool`) – Flag determining whether the individual fields given in *fields* are copied. Note that fields are always copied if some of the supplied fields are identical.
- **label** (`str`) – Label of the field collection
- **labels** (*list of str*) – Labels of the individual fields. If omitted, the labels from the *fields* argument are used.
- **dtype** (`numpy dtype`) – The data type of the field. All the numpy dtypes are supported. If omitted, it will be determined from *data* automatically.

**assert\_field\_compatible** (*other*: `FieldBase`, *accept\_scalar*: `bool` = `False`)

checks whether *other* is compatible with the current field

#### Parameters

- **other** (`FieldBase`) – Other field this is compared to
- **accept\_scalar** (`bool`, *optional*) – Determines whether it is acceptable that *other* is an instance of `ScalarField`.

**property** `attributes`: `Dict[str, Any]`

describes the state of the instance (without the data)

Type `dict`

**property** `attributes_serialized`: `Dict[str, str]`

serialized version of the attributes

Type `dict`

**property** `averages`: `List`

averages of all fields

**copy** (\*, *label*: `str` = `None`, *dtype*=`None`) → `FieldCollection`

return a copy of the data, but not of the grid

#### Parameters

- **label** (`str`, *optional*) – Name of the returned field
- **dtype** (`numpy dtype`) – The data type of the field. If omitted, it will be determined from *data* automatically.

**property** `fields`: `List[pde.fields.base.DataFieldBase]`

the fields of this collection

Type `list`

**classmethod from\_scalar\_expressions** (*grid*: [GridBase](#), *expressions*: [Sequence\[str\]](#), \*, *label*: *str* = *None*, *labels*: [Optional\[Sequence\[str\]\]](#) = *None*, *dtype*=*None*) → [FieldCollection](#)

create a field collection on a grid from given expressions

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur.

#### Parameters

- **grid** ([GridBase](#)) – Grid defining the space on which this field is defined
- **expressions** (*list of str*) – A list of mathematical expression, one for each field in the collection. The expressions determine the values as a function of the position on the grid. The expressions may contain standard mathematical functions and they may depend on the axes labels of the grid.
- **label** (*str*, *optional*) – Name of the whole collection
- **labels** (*list of str*, *optional*) – Names of the individual fields
- **dtype** (*numpy dtype*) – The data type of the field. All the numpy dtypes are supported. If omitted, it will be determined from *data* automatically.

**classmethod from\_state** (*attributes*: [Dict\[str, Any\]](#), *data*: *numpy.ndarray* = *None*) → [FieldCollection](#)  
create a field collection from given state.

#### Parameters

- **attributes** (*dict*) – The attributes that describe the current instance
- **data** (*ndarray*, *optional*) – Data values at support points of the grid defining all fields

**get\_image\_data** (*index*: *int* = 0, *\*\*kwargs*) → [Dict\[str, Any\]](#)  
return data for plotting an image of the field

#### Parameters

- **index** (*int*) – Index of the field whose data is returned
- **\*\*kwargs** – Arguments forwarded to the *get\_image\_data* method

**Returns** Information useful for plotting an image of the field

**Return type** [dict](#)

**get\_line\_data** (*index*: *int* = 0, *scalar*: *str* = 'auto', *extract*: *str* = 'auto') → [Dict\[str, Any\]](#)  
return data for a line plot of the field

#### Parameters

- **index** (*int*) – Index of the field whose data is returned
- **scalar** (*str* or *int*) – The method for extracting scalars as described in [DataFieldBase.to\\_scalar\(\)](#).
- **extract** (*str*) – The method used for extracting the line data. See the docstring of the grid method *get\_line\_data* to find supported values.

**Returns** Information useful for performing a line plot of the field

**Return type** [dict](#)

**property integrals:** `List`

integrals of all fields

**interpolate\_to\_grid** (*grid*: `GridBase`, \*, *backend*: *str* = 'numba', *method*: *str* = 'linear', *fill*:

*Optional*[*Number*] = *None*, *label*: *str* = *None*) → *FieldCollection*

interpolate the data of this field collection to another grid.

#### Parameters

- **grid** (*GridBase*) – The grid of the new field onto which the current field is interpolated.
- **backend** (*str*) – The accepted values “scipy” and “numba” determine the backend that is used for the interpolation.
- **method** (*str*) – Determines the method being used for interpolation. Typical values that are “nearest” and “linear”, but the supported values depend on the chosen *backend*.
- **fill** (*Number*, *optional*) – Determines how values out of bounds are handled. If *None*, a *ValueError* is raised when out-of-bounds points are requested. Otherwise, the given value is returned.
- **label** (*str*, *optional*) – Name of the returned field collection

**Returns** Interpolated data

**Return type** `FieldCollection`

**property labels:** `_FieldLabels`

the labels of all fields

---

**Note:** The attribute returns a special class `_FieldLabels` to allow specific manipulations of the field labels. The returned object behaves much like a list, but assigning values will modify the labels of the fields in the collection.

---

**Type** `_FieldLabels`

**property magnitudes:** `numpy.ndarray`

scalar magnitudes of all fields

**Type** `ndarray`

**plot** (*kind*: *Union*[*str*, *Sequence*[*str*]] = 'auto', *resize\_fig*=*None*, *figsize*='auto', *arrangement*='horizontal', *subplot\_args*=*None*, \**args*, *title*: *str* = *None*, *constrained\_layout*: *bool* = *True*, *filename*: *str* = *None*, *action*: *str* = 'auto', *fig\_style*: *Optional*[*Dict*[*str*, *Any*]] = *None*, *fig*=*None*, \*\**kwargs*) → *List*[*PlotReference*]

visualize all the fields in the collection

#### Parameters

- **kind** (*str* or *list* of *str*) – Determines the kind of the visualizations. Supported values are *image*, *line*, *vector*, or *interactive*. Alternatively, *auto* determines the best visualization based on each field itself. Instead of a single value for all fields, a list with individual values can be given.
- **resize\_fig** (*bool*) – Whether to resize the figure to adjust to the number of panels
- **figsize** (*str* or *tuple* of *numbers*) – Determines the figure size. The figure size is unchanged if the string *default* is passed. Conversely, the size is adjusted automatically when *auto* is passed. Finally, a specific figure size can be specified using two values, using `matplotlib.figure.Figure.set_size_inches()`.

- **arrangement** (*str*) – Determines how the subpanels will be arranged. The default value *horizontal* places all subplots next to each other. The alternative value *vertical* puts them below each other.
- **title** (*str*) – Title of the plot. If omitted, the title might be chosen automatically. This is shown above all panels.
- **constrained\_layout** (*bool*) – Whether to use *constrained\_layout* in `matplotlib.pyplot.figure()` call to create a figure. This affects the layout of all plot elements. Generally, spacing might be better with this flag enabled, but it can also lead to problems when plotting multiple plots successively, e.g., when creating a movie.
- **filename** (*str*, *optional*) – If given, the figure is written to the specified file.
- **action** (*str*) – Decides what to do with the final figure. If the argument is set to *show*, `matplotlib.pyplot.show()` will be called to show the plot. If the value is *none*, the figure will be created, but not necessarily shown. The value *close* closes the figure, after saving it to a file when *filename* is given. The default value *auto* implies that the plot is shown if it is not a nested plot call.
- **fig\_style** (*dict*) – Dictionary with properties that will be changed on the figure after the plot has been drawn by calling `matplotlib.pyplot.setp()`. For instance, using `fig_style={'dpi': 200}` increases the resolution of the figure.
- **fig** (`matplotlib.figure.Figure`) – Figure that is used for plotting. If omitted, a new figure is created.
- **subplot\_args** (*list*) – Additional arguments for the specific subplots. Should be a list with a dictionary of arguments for each subplot. Supplying an empty dict allows to keep the default setting of specific subplots.
- **\*\*kwargs** – All additional keyword arguments are forwarded to the actual plotting function of all subplots.

**Returns** Instances that contain information to update all the plots with new data later.

**Return type** List of `PlotReference`

**classmethod** **scalar\_random\_uniform** (*num\_fields*: *int*, *grid*: `GridBase`, *vmin*: *float* = 0, *vmax*: *float* = 1, \*, *label*: *str* = None, *labels*: *Optional*[*Sequence*[*str*]] = None) → *FieldCollection*

create scalar fields with random values between *vmin* and *vmax*

#### Parameters

- **num\_fields** (*int*) – The number of fields to create
- **grid** (`GridBase`) – Grid defining the space on which the fields are defined
- **vmin** (*float*) – Lower bound. Can be complex to create complex fields
- **vmax** (*float*) – Upper bound. Can be complex to create complex fields
- **label** (*str*, *optional*) – Name of the field collection
- **labels** (*list of str*, *optional*) – Names of the individual fields

**smooth** (*sigma*: *float* = 1, \*, *out*: *Optional*[`FieldCollection`] = None, *label*: *str* = None) → *FieldCollection*  
applies Gaussian smoothing with the given standard deviation

This function respects periodic boundary conditions of the underlying grid, using reflection when no periodicity is specified.

**sigma** (*float*): Gives the standard deviation of the smoothing in real length units (default: 1)

**out (FieldCollection, optional):** Optional field into which the smoothed data is stored

**label (str, optional):** Name of the returned field

**Returns** Field collection with smoothed data, stored at *out* if given.

**classmethod `unserialize_attributes`** (*attributes: Dict[str, str]*) → Dict[str, Any]  
unserializes the given attributes

**Parameters** *attributes* (*dict*) – The serialized attributes

**Returns** The unserialized attributes

**Return type** dict

### 4.1.3 `pde.fields.scalar` module

Defines a scalar field over a grid

**class `ScalarField`** (*grid: GridBase, data: Optional[Union[int, float, complex, numpy.ndarray, Sequence[NumberOrArray], Sequence[Sequence[Any]]], str] = 'zeros', \*, label: str = None, dtype=None, with\_ghost\_cells: bool = False*)

Bases: `pde.fields.base.DataFieldBase`

Scalar field discretized on a grid

#### Parameters

- **grid** (*GridBase*) – Grid defining the space on which this field is defined.
- **data** (Number or `ndarray`, optional) – Field values at the support points of the grid. The flag *with\_ghost\_cells* determines whether this data array contains values for the ghost cells, too. The resulting field will contain real data unless the *data* argument contains complex values. Special values are “zeros” or `None`, initializing the field with zeros, and “empty”, just allocating memory with unspecified values.
- **label** (*str*, optional) – Name of the field
- **dtype** (*numpy dtype*) – The data type of the field. All the numpy dtypes are supported. If omitted, it will be determined from *data* automatically.
- **with\_ghost\_cells** (*bool*) – Indicates whether the ghost cells are included in data

**classmethod `from_expression`** (*grid: GridBase, expression: str, \*, label: str = None, dtype=None*) → *ScalarField*

create a scalar field on a grid from a given expression

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur.

#### Parameters

- **grid** (*GridBase*) – Grid defining the space on which this field is defined
- **expression** (*str*) – Mathematical expression for the scalar value as a function of the position on the grid. The expression may contain standard mathematical functions and it may depend on the axes labels of the grid.
- **label** (*str*, optional) – Name of the field

- **dtype** (*numpy dtype*) – The data type of the field. All the numpy dtypes are supported. If omitted, it will be determined from *data* automatically.

**classmethod from\_image** (*path: Union[pathlib.Path, str], bounds=None, periodic=False, \*, label: str = None*) → *ScalarField*

create a scalar field from an image

#### Parameters

- **path** (*Path or str*) – The path to the image
- **bounds** (*tuple, optional*) – Gives the coordinate range for each axis. This should be two tuples of two numbers each, which mark the lower and upper bound for each axis.
- **periodic** (*bool or list*) – Specifies which axes possess periodic boundary conditions. This is either a list of booleans defining periodicity for each individual axis or a single boolean value specifying the same periodicity for all axes.
- **label** (*str, optional*) – Name of the field

**gradient** (*bc: Optional[BoundariesData], out: Optional['VectorField'] = None, \*\*kwargs*) → *VectorField*  
apply gradient operator and return result as a field

#### Parameters

- **bc** – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by ‘periodic’). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value NUM (specified by {‘value’: NUM}) and Neumann conditions enforcing the value DERIV for the derivative in the normal direction (specified by {‘derivative’: DERIV}) are supported. Note that the special value ‘natural’ imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#). If the special value *None* is given, no boundary conditions are enforced. The user then needs to ensure that the ghost cells are set accordingly.
- **out** (*VectorField, optional*) – Optional vector field to which the result is written.
- **label** (*str, optional*) – Name of the returned field

**Returns** result of applying the operator

**Return type** *VectorField*

**gradient\_squared** (*bc: Optional[BoundariesData], out: Optional[ScalarField] = None, \*\*kwargs*) → *ScalarField*

apply squared gradient operator and return result as a field

This evaluates  $|\nabla\phi|^2$  for the scalar field  $\phi$

#### Parameters

- **bc** – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by ‘periodic’). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value NUM (specified by {‘value’: NUM}) and Neumann conditions enforcing the value DERIV for the derivative in the normal direction (specified by {‘derivative’: DERIV}) are supported. Note that the special value ‘natural’ imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#). If the special value *None* is given, no boundary conditions are enforced. The user then needs to ensure that the ghost cells are set accordingly.

- **out** (*ScalarField*, *optional*) – Optional vector field to which the result is written.
- **label** (*str*, *optional*) – Name of the returned field
- **central** (*bool*) – Determines whether a central difference approximation is used for the gradient operator or not. If not, the squared gradient is calculated as the mean of the squared values of the forward and backward derivatives, which thus includes the value at a support point in the result at the same point.

**Returns** the squared gradient of the field

**Return type** *ScalarField*

**property integral:** `Union[int, float, complex]`

integral of the scalar field over space

**Type** Number

**laplace** (*bc: Optional[BoundariesData]*, *out: Optional[ScalarField] = None*, *\*\*kwargs*) → *ScalarField*  
apply Laplace operator and return result as a field

#### Parameters

- **bc** – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by ‘periodic’). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value NUM (specified by `{‘value’: NUM}`) and Neumann conditions enforcing the value DERIV for the derivative in the normal direction (specified by `{‘derivative’: DERIV}`) are supported. Note that the special value ‘natural’ imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#). If the special value *None* is given, no boundary conditions are enforced. The user then needs to ensure that the ghost cells are set accordingly.
- **out** (*ScalarField*, *optional*) – Optional scalar field to which the result is written.
- **label** (*str*, *optional*) – Name of the returned field
- **backend** (*str*) – The backend (e.g., ‘numba’ or ‘scipy’) used for this operator.

**Returns** the Laplacian of the field

**Return type** *ScalarField*

**project** (*axes: Union[str, Sequence[str]]*, *method: str = ‘integral’*, *label: str = None*) → *ScalarField*  
project scalar field along given axes

#### Parameters

- **axes** (*list of str*) – The names of the axes that are removed by the projection operation. The valid names for a given grid are the ones in the `GridBase.axes` attribute.
- **method** (*str*) – The projection method. This can be either ‘integral’ to integrate over the removed axes or ‘average’ to perform an average instead.
- **label** (*str*, *optional*) – The label of the returned field

**Returns** The projected data in a scalar field with a subgrid of the original grid.

**Return type** *ScalarField*

**rank:** `int = 0`

**slice** (*position: Dict[str, float]*, *\**, *method: str = ‘nearest’*, *label: str = None*) → *ScalarField*  
slice data at a given position

**Parameters**

- **position** (*dict*) – Determines the location of the slice using a dictionary supplying coordinate values for a subset of axes. Axes not mentioned in the dictionary are retained and form the slice. For instance, in a 2d Cartesian grid, *position* = {'x': 1} slices along the y-direction at x=1. Additionally, the special positions 'low', 'mid', and 'high' are supported to reference relative positions along the axis.
- **method** (*str*) – The method used for slicing. *nearest* takes data from cells defined on the grid.
- **label** (*str*, *optional*) – The label of the returned field

**Returns** The sliced data in a scalar field with a subgrid of the original grid.

**Return type** *ScalarField*

**to\_scalar** (*scalar*: *Union[str, Callable]* = 'auto', \*, *label*: *str* = None) → *ScalarField*  
 return a modified scalar field by applying method *scalar*

**Parameters**

- **scalar** (*str* or *callable*) – Determines the method used for obtaining the scalar. If this is a callable, it is simply applied to self.data and a new scalar field with this data is returned. Alternatively, pre-defined methods can be selected using strings. Here, *abs* and *norm* denote the norm of each entry of the field, while *norm\_squared* returns the squared norm. The default *auto* is to return a (unchanged) copy of a real field and the norm of a complex field.
- **label** (*str*, *optional*) – Name of the returned field

**Returns** Scalar field after applying the operation

**Return type** *ScalarField*

#### 4.1.4 `pde.fields.tensorial` module

Defines a tensorial field of rank 2 over a grid

**class** **Tensor2Field** (*grid*: *GridBase*, *data*: *Optional[Union[int, float, complex, numpy.ndarray, Sequence[NumberOrArray], Sequence[Sequence[Any]]]*, *str*] = 'zeros', \*, *label*: *str* = None, *dtype*=None, *with\_ghost\_cells*: *bool* = False)

Bases: *pde.fields.base.DataFieldBase*

Tensor field of rank 2 discretized on a grid

**Parameters**

- **grid** (*GridBase*) – Grid defining the space on which this field is defined.
- **data** (Number or *ndarray*, *optional*) – Field values at the support points of the grid. The flag *with\_ghost\_cells* determines whether this data array contains values for the ghost cells, too. The resulting field will contain real data unless the *data* argument contains complex values. Special values are “zeros” or None, initializing the field with zeros, and “empty”, just allocating memory with unspecified values.
- **label** (*str*, *optional*) – Name of the field
- **dtype** (*numpy dtype*) – The data type of the field. All the numpy dtypes are supported. If omitted, it will be determined from *data* automatically.
- **with\_ghost\_cells** (*bool*) – Indicates whether the ghost cells are included in data

**divergence** (*bc*: *Optional*[*BoundariesData*], *out*: *Optional*[*VectorField*] = *None*, *\*\*kwargs*) → *VectorField*  
 apply tensor divergence and return result as a field

The tensor divergence is a vector field  $v_\alpha$  resulting from a contracting of the derivative of the tensor field  $t_{\alpha\beta}$ :

$$v_\alpha = \sum_\beta \frac{\partial t_{\alpha\beta}}{\partial x_\beta}$$

#### Parameters

- **bc** – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by ‘periodic’). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value NUM (specified by {‘value’: NUM}) and Neumann conditions enforcing the value DERIV for the derivative in the normal direction (specified by {‘derivative’: DERIV}) are supported. Note that the special value ‘natural’ imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#). If the special value *None* is given, no boundary conditions are enforced. The user then needs to ensure that the ghost cells are set accordingly.
- **out** (*VectorField*, *optional*) – Optional scalar field to which the result is written.
- **label** (*str*, *optional*) – Name of the returned field

**Returns** result of applying the operator

**Return type** *VectorField*

**dot** (*other*: *Union*[*VectorField*, *Tensor2Field*], *out*: *Optional*[*Union*[*VectorField*, *Tensor2Field*]] = *None*, *\**, *conjugate*: *bool* = *True*, *label*: *str* = ‘dot product’) → *Union*[*VectorField*, *Tensor2Field*]  
 calculate the dot product involving a tensor field

This supports the dot product between two tensor fields as well as the product between a tensor and a vector. The resulting fields will be a tensor or vector, respectively.

#### Parameters

- **other** (*VectorField* or *Tensor2Field*) – the second field
- **out** (*VectorField* or *Tensor2Field*, *optional*) – Optional field to which the result is written.
- **conjugate** (*bool*) – Whether to use the complex conjugate for the second operand
- **label** (*str*, *optional*) – Name of the returned field

**Returns** *VectorField* or *Tensor2Field*: result of applying the dot operator

**classmethod from\_expression** (*grid*: *GridBase*, *expressions*: *Sequence*[*Sequence*[*str*]], *\**, *label*: *str* = *None*, *dtype*=*None*) → *Tensor2Field*  
 create a tensor field on a grid from given expressions

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur.

#### Parameters

- **grid** (*GridBase*) – Grid defining the space on which this field is defined

- **expressions** (*list of str*) – A 2d list of mathematical expression, one for each component of the tensor field. The expressions determine the values as a function of the position on the grid. The expressions may contain standard mathematical functions and they may depend on the axes labels of the grid.
- **label** (*str, optional*) – Name of the field
- **dtype** (*numpy dtype*) – The data type of the field. All the numpy dtypes are supported. If omitted, it will be determined from *data* automatically.

**property integral:** `numpy.ndarray`

integral of each component over space

Type `ndarray`

**make\_dot\_operator** (*backend: str = 'numba', \*, conjugate: bool = True*) → `Callable[[numpy.ndarray, numpy.ndarray, numpy.ndarray], numpy.ndarray]`

return operator calculating the dot product involving vector fields

This supports both products between two vectors as well as products between a vector and a tensor.

**Warning:** This function does not check types or dimensions.

**Parameters** `conjugate` (*bool*) – Whether to use the complex conjugate for the second operand

**Returns** function that takes two instance of `ndarray`, which contain the discretized data of the two operands. An optional third argument can specify the output array to which the result is written. Note that the returned function is jitted with numba for speed.

**plot\_components** (*kind: str = 'auto', \*args, title: str = None, constrained\_layout: bool = True, filename: str = None, action: str = 'auto', fig\_style: Optional[Dict[str, Any]] = None, fig=None, \*\*kwargs*) → `List[List[PlotReference]]`

visualize all the components of this tensor field

**Parameters**

- **kind** (*str or list of str*) – Determines the kind of the visualizations. Supported values are *image* or *line*. Alternatively, *auto* determines the best visualization based on the grid.
- **title** (*str*) – Title of the plot. If omitted, the title might be chosen automatically. This is shown above all panels.
- **constrained\_layout** (*bool*) – Whether to use *constrained\_layout* in `matplotlib.pyplot.figure()` call to create a figure. This affects the layout of all plot elements. Generally, spacing might be better with this flag enabled, but it can also lead to problems when plotting multiple plots successively, e.g., when creating a movie.
- **filename** (*str, optional*) – If given, the figure is written to the specified file.
- **action** (*str*) – Decides what to do with the final figure. If the argument is set to *show*, `matplotlib.pyplot.show()` will be called to show the plot. If the value is *none*, the figure will be created, but not necessarily shown. The value *close* closes the figure, after saving it to a file when *filename* is given. The default value *auto* implies that the plot is shown if it is not a nested plot call.
- **fig\_style** (*dict*) – Dictionary with properties that will be changed on the figure after the plot has been drawn by calling `matplotlib.pyplot.setp()`. For instance, using `fig_style={'dpi': 200}` increases the resolution of the figure.

- **fig** (`matplotlib.figure.Figure`) – Figure that is used for plotting. If omitted, a new figure is created.
- **\*\*kwargs** – All additional keyword arguments are forwarded to the actual plotting function of all subplots.

**Returns** Instances that contain information to update all the plots with new data later.

**Return type** 2d list of `PlotReference`

**rank:** `int = 2`

**symmetrize** (`make_traceless: bool = False, inplace: bool = False`) → `Tensor2Field`

symmetrize the tensor field in place

**Parameters**

- **make\_traceless** (`bool`) – Determines whether the result is also traceless
- **inplace** (`bool`) – Flag determining whether to symmetrize the current field or return a new one

**Returns** result of the operation

**Return type** `Tensor2Field`

**to\_scalar** (`scalar: str = 'auto', *, label: str = 'scalar {scalar}'`) → `ScalarField`

return a scalar field by applying *method*

The invariants of the tensor field  $\mathbf{A}$  are

$$\begin{aligned}I_1 &= \text{tr}(\mathbf{A}) \\I_2 &= \frac{1}{2} [(\text{tr}(\mathbf{A}))^2 - \text{tr}(\mathbf{A}^2)] \\I_3 &= \det(\mathbf{A})\end{aligned}$$

where *tr* denotes the trace and *det* denotes the determinant. Note that the three invariants can only be distinct and non-zero in three dimensions. In two dimensional spaces, we have the identity  $2I_2 = I_3$  and in one-dimensional spaces, we have  $I_1 = I_3$  as well as  $I_2 = 0$ .

**Parameters**

- **scalar** (`str`) – The method to calculate the scalar. Possible choices include *norm* (the default chosen when the value is *auto*), *min*, *max*, *squared\_sum*, *norm\_squared*, *trace* (or *invariant1*), *invariant2*, and *determinant* (or *invariant3*)
- **label** (`str, optional`) – Name of the returned field

**Returns** the scalar field after applying the operation

**Return type** `ScalarField`

**trace** (`label: str = 'trace'`) → `ScalarField`

return the trace of the tensor field as a scalar field

**Parameters** **label** (`str, optional`) – Name of the returned field

**Returns** scalar field of traces

**Return type** `ScalarField`

**transpose** (`label: str = 'transpose'`) → `Tensor2Field`

return the transpose of the tensor field

**Parameters** **label** (`str, optional`) – Name of the returned field

**Returns** transpose of the tensor field

**Return type** *Tensor2Field*

### 4.1.5 `pde.fields.vectorial` module

Defines a vectorial field over a grid

```
class VectorField(grid: GridBase, data: Optional[Union[int, float, complex, numpy.ndarray,
Sequence[NumberOrArray], Sequence[Sequence[Any]], str]] = 'zeros', *, label: str = None,
dtype=None, with_ghost_cells: bool = False)
```

Bases: *pde.fields.base.DataFieldBase*

Vector field discretized on a grid

#### Parameters

- **grid** (*GridBase*) – Grid defining the space on which this field is defined.
- **data** (Number or *ndarray*, optional) – Field values at the support points of the grid. The flag *with\_ghost\_cells* determines whether this data array contains values for the ghost cells, too. The resulting field will contain real data unless the *data* argument contains complex values. Special values are “zeros” or None, initializing the field with zeros, and “empty”, just allocating memory with unspecified values.
- **label** (*str*, optional) – Name of the field
- **dtype** (*numpy dtype*) – The data type of the field. All the numpy dtypes are supported. If omitted, it will be determined from *data* automatically.
- **with\_ghost\_cells** (*bool*) – Indicates whether the ghost cells are included in data

**divergence** (*bc*: Optional[BoundariesData], *out*: Optional[ScalarField] = None, \*\*kwargs) → *ScalarField*  
 apply divergence operator and return result as a field

#### Parameters

- **bc** – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by ‘periodic’). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value NUM (specified by {‘value’: NUM}) and Neumann conditions enforcing the value DERIV for the derivative in the normal direction (specified by {‘derivative’: DERIV}) are supported. Note that the special value ‘natural’ imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#). If the special value None is given, no boundary conditions are enforced. The user then needs to ensure that the ghost cells are set accordingly.
- **out** (*ScalarField*, optional) – Optional scalar field to which the result is written.
- **label** (*str*, optional) – Name of the returned field

**Returns** result of applying the operator

**Return type** *ScalarField*

**dot** (*other*: Union[VectorField, Tensor2Field], *out*: Optional[Union[ScalarField, VectorField]] = None, \*, *conjugate*: bool = True, *label*: str = ‘dot product’) → Union[ScalarField, VectorField]  
 calculate the dot product involving a vector field

This supports the dot product between two vectors fields as well as the product between a vector and a tensor. The resulting fields will be a scalar or vector, respectively.

**Parameters**

- **other** (`VectorField` or `Tensor2Field`) – the second field
- **out** (`ScalarField` or `VectorField`, *optional*) – Optional field to which the result is written.
- **conjugate** (*bool*) – Whether to use the complex conjugate for the second operand
- **label** (*str*, *optional*) – Name of the returned field

**Returns** `ScalarField` or `VectorField`: result of applying the operator

**classmethod from\_expression** (*grid*: `GridBase`, *expressions*: `Sequence[str]`, \*, *label*: *str* = *None*, *dtype*=*None*) → `VectorField`

create a vector field on a grid from given expressions

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur.

**Parameters**

- **grid** (`GridBase`) – Grid defining the space on which this field is defined
- **expressions** (*list of str*) – A list of mathematical expression, one for each component of the vector field. The expressions determine the values as a function of the position on the grid. The expressions may contain standard mathematical functions and they may depend on the axes labels of the grid.
- **label** (*str*, *optional*) – Name of the field
- **dtype** (*numpy dtype*) – The data type of the field. All the numpy dtypes are supported. If omitted, it will be determined from *data* automatically.

**classmethod from\_scalars** (*fields*: `List[ScalarField]`, \*, *label*: *str* = *None*, *dtype*=*None*) → `VectorField`  
create a vector field from a list of `ScalarFields`

Note that the data of the scalar fields is copied in the process

**Parameters**

- **fields** (*list*) – The list of (compatible) scalar fields
- **label** (*str*, *optional*) – Name of the returned field
- **dtype** (*numpy dtype*) – The data type of the field. All the numpy dtypes are supported. If omitted, it will be determined from *data* automatically.

**Returns** the resulting vector field

**Return type** `VectorField`

**get\_vector\_data** (*transpose*: *bool* = *False*, *max\_points*: *int* = *None*, *\*\*kwargs*) → `Dict[str, Any]`  
return data for a vector plot of the field

**Parameters**

- **transpose** (*bool*) – Determines whether the transpose of the data should be plotted.
- **max\_points** (*int*) – The maximal number of points that is used along each axis. This option can be used to sub-sample the data.
- **\*\*kwargs** – Additional parameters are forwarded to `grid.get_image_data`

**Returns** Information useful for plotting an vector field

**Return type** `dict`

**gradient** (*bc*: *Optional[BoundariesData]*, *out*: *Optional[\'Tensor2Field\'] = None*, *\*\*kwargs*)  $\rightarrow$  *Tensor2Field*  
 apply vector gradient operator and return result as a field

The vector gradient field is a tensor field  $t_{\alpha\beta}$  that specifies the derivatives of the vector field  $v_\alpha$  with respect to all coordinates  $x_\beta$ :

**Parameters**

- **bc** – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by ‘periodic’). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value NUM (specified by  $\{‘value’: NUM\}$ ) and Neumann conditions enforcing the value DERIV for the derivative in the normal direction (specified by  $\{‘derivative’: DERIV\}$ ) are supported. Note that the special value ‘natural’ imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#). If the special value *None* is given, no boundary conditions are enforced. The user then needs to ensure that the ghost cells are set accordingly.
- **out** (*VectorField*, *optional*) – Optional vector field to which the result is written.
- **label** (*str*, *optional*) – Name of the returned field

**Returns** result of applying the operator

**Return type** *Tensor2Field*

**property integral**: `numpy.ndarray`  
 integral of each component over space

**Type** `ndarray`

**laplace** (*bc*: *Optional[BoundariesData]*, *out*: *Optional[VectorField] = None*, *\*\*kwargs*)  $\rightarrow$  *VectorField*  
 apply vector Laplace operator and return result as a field

The vector Laplacian is a vector field  $L_\alpha$  containing the second derivatives of the vector field  $v_\alpha$  with respect to the coordinates  $x_\beta$ :

$$L_\alpha = \sum_\beta \frac{\partial^2 v_\alpha}{\partial x_\beta \partial x_\beta}$$

**Parameters**

- **bc** – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by ‘periodic’). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value NUM (specified by  $\{‘value’: NUM\}$ ) and Neumann conditions enforcing the value DERIV for the derivative in the normal direction (specified by  $\{‘derivative’: DERIV\}$ ) are supported. Note that the special value ‘natural’ imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#). If the special value *None* is given, no boundary conditions are enforced. The user then needs to ensure that the ghost cells are set accordingly.
- **out** (*VectorField*, *optional*) – Optional vector field to which the result is written.
- **label** (*str*, *optional*) – Name of the returned field

**Returns** result of applying the operator

**Return type** *VectorField*

**make\_dot\_operator** (*backend*: *str* = 'numba', \*, *conjugate*: *bool* = True) → Callable[[*numpy.ndarray*, *numpy.ndarray*, *numpy.ndarray*]

return operator calculating the dot product involving vector fields

This supports both products between two vectors as well as products between a vector and a tensor.

**Warning:** This function does not check types or dimensions.

#### Parameters

- **backend** (*str*) – The backend (e.g., 'numba' or 'scipy') used for this operator.
- **conjugate** (*bool*) – Whether to use the complex conjugate for the second operand

**Returns** function that takes two instance of *ndarray*, which contain the discretized data of the two operands. An optional third argument can specify the output array to which the result is written. Note that the returned function is jitted with numba for speed.

**make\_outer\_prod\_operator** (*backend*: *str* = 'numba') → Callable[[*numpy.ndarray*, *numpy.ndarray*, *numpy.ndarray*]

return operator calculating the outer product of two vector fields

**Warning:** This function does not check types or dimensions.

**Parameters** **backend** (*str*) – The backend (e.g., 'numba' or 'scipy') used for this operator.

**Returns** function that takes two instance of *ndarray*, which contain the discretized data of the two operands. An optional third argument can specify the output array to which the result is written. Note that the returned function is jitted with numba for speed.

**outer\_product** (*other*: *VectorField*, *out*: *Optional*[*Tensor2Field*] = None, \*, *label*: *str* = None) → *Tensor2Field*

calculate the outer product of this vector field with another

#### Parameters

- **other** (*VectorField*) – The second vector field
- **out** (*Tensor2Field*, optional) – Optional tensorial field to which the result is written.
- **label** (*str*, optional) – Name of the returned field

**Returns** result of the operation

**Return type** *Tensor2Field*

**rank**: *int* = 1

**to\_scalar** (*scalar*: *Union*[*str*, *int*] = 'auto', \*, *label*: *str* = 'scalar {scalar}') → *ScalarField*

return a scalar field by applying *method*

#### Parameters

- **scalar** (*str*) – Choose the method to use. Possible choices are *norm*, *max*, *min*, *squared\_sum*, *norm\_squared*, or an integer specifying which component is returned (indexing starts at 0). The default value *auto* picks the method automatically. The first (and only)

component is returned for real fields on one-dimensional spaces, while the norm of the vector is returned otherwise.

- **label** (*str*, *optional*) – Name of the returned field

**Returns** the scalar field after applying the operation

**Return type** `pde.fields.scalar.ScalarField`

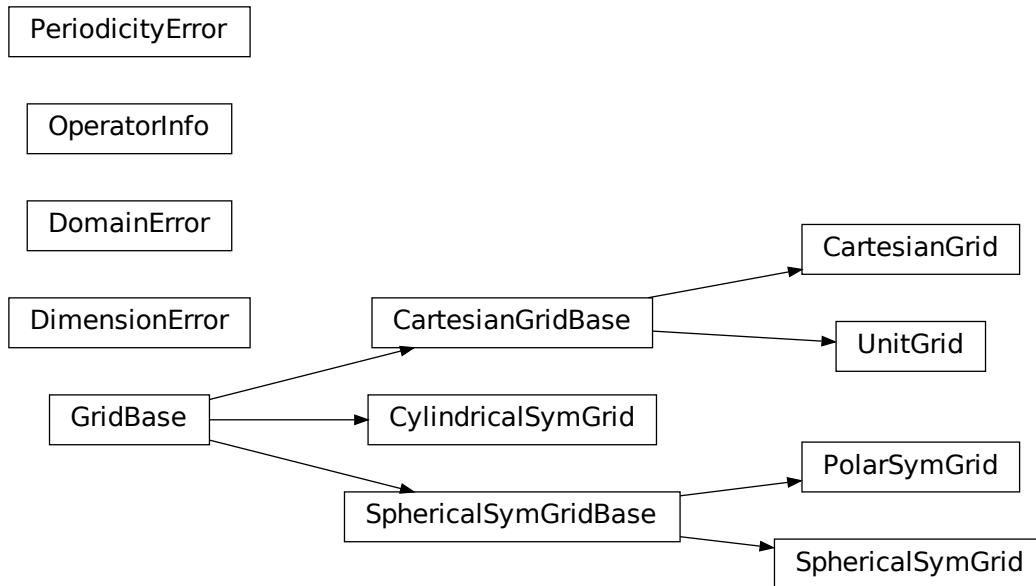
## 4.2 pde.grids package

Grids define the domains on which PDEs will be solved. In particular, symmetries, periodicities, and the discretizations are defined by the underlying grid.

We only consider regular, orthogonal grids, which are constructed from orthogonal coordinate systems with equidistant discretizations along each axis. The dimension of the space that the grid describes is given by the attribute `dim`. Cartesian coordinates can be mapped to grid coordinates and the corresponding discretization cells using the method `transform()`.

<i>UnitGrid</i>	d-dimensional Cartesian grid with unit discretization in all directions
<i>CartesianGrid</i>	d-dimensional Cartesian grid with uniform discretization for each axis
<i>PolarSymGrid</i>	2-dimensional polar grid assuming angular symmetry
<i>SphericalSymGrid</i>	3-dimensional spherical grid assuming spherical symmetry
<i>CylindricalSymGrid</i>	3-dimensional cylindrical grid assuming polar symmetry

Inheritance structure of the classes:



### Subpackages:

## 4.2.1 `pde.grids.boundaries` package

This package contains classes for handling the boundary conditions of fields.

### Boundary conditions

The mathematical details of boundary conditions for partial differential equations are treated in more detail in the `documentation` document. Since the `pde` package only supports orthogonal grids, boundary conditions need to be applied at the end of each axis. Consequently, methods expecting boundary conditions typically receive a list of conditions for each axes:

```
field = ScalarField(UnitGrid([16, 16], periodic=[True, False]))
field.laplace(bc=[bc_x, bc_y])
```

If an axis is periodic (like the first one in the example above), the only valid boundary condition is ‘periodic’. For non-periodic axes (e.g., the second axis), different boundary conditions can be specified for the lower and upper end of the axis, which is done using a tuple of two conditions. Typical choices for individual conditions are Dirichlet conditions that enforce a value `NUM` (specified by `{‘value’: NUM}`) and Neumann conditions that enforce the value `DERIV` for the derivative in the normal direction (specified by `{‘derivative’: DERIV}`). The specific choices for the example above could be

```
bc_x = "periodic"
bc_y = ({"value": 2}, {"derivative": -1})
```

which enforces a value of 2 at the lower side of the y-axis and a derivative (in outward normal direction) of -1 on the upper side. Instead of plain numbers, which enforce the same condition along the whole boundary, expressions can be used to

support inhomogeneous boundary conditions. These mathematical expressions are given as a string that can be parsed by *sympy*. They can depend on all coordinates of the grid. An alternative boundary condition to the example above could thus read

```
bc_y = ({ "value": "y**2"}, { "derivative": "-sin(x)" })
```

**Warning:** To interpret arbitrary expressions, the package uses `exec()`. It should therefore not be used in a context where malicious input could occur.

Inhomogeneous values can also be specified by directly supplying an array, whose shape needs to be compatible with the boundary, i.e., it needs to have the same shape as the grid but with the dimension of the axis along which the boundary is specified removed.

The package also supports mixed boundary conditions (depending on both the value and the derivative of the field) and imposing a second derivative. An example is

```
bc_y = ({ "type": "mixed", "value": 2, "const": 7},
        { "curvature": 2})
```

which enforces the condition  $\partial_n c + 2c = 7$  and  $\partial_n^2 c = 2$  onto the field  $c$  on the lower and upper side of the axis, respectively.

Beside the full specification of the boundary conditions, various short-hand notations are supported. If both sides of an axis have the same boundary condition, only one needs to be specified (instead of the tuple). For instance, `bc_y = { 'value': 2 }` imposes a value of 2 on both sides of the y-axis. Similarly, if all axes have the same boundary conditions, only one axis needs to be specified (instead of the list). For instance, the following example

```
field = ScalarField(UnitGrid([16, 16], periodic=False))
field.laplace(bc={ "value": 2})
```

imposes a value of 2 on all sides of the grid. Finally, the special values 'auto\_periodic\_neumann' and 'auto\_periodic\_dirichlet' impose periodic boundary conditions for periodic axis and a vanishing derivative or value otherwise. For example,

```
field = ScalarField(UnitGrid([16, 16], periodic=[True, False]))
field.laplace(bc="auto_periodic_neumann")
```

enforces periodic boundary conditions on the first axis, while the second one has standard Neumann conditions.

**Note:** Derivatives are given relative to the outward normal vector, such that positive derivatives correspond to a function that increases across the boundary.

## Boundaries overview

The *boundaries* package defines the following classes:

### Local boundary conditions:

- *DirichletBC*: Imposing a constant value of the field at the boundary
- *ExpressionValueBC*: Imposing the value of the field at the boundary given by an expression
- *NeumannBC*: Imposing a constant derivative of the field in the outward normal direction at the boundary

- *ExpressionDerivativeBC*: Imposing the derivative of the field in the outward normal direction at the boundary given by an expression
- *MixedBC*: Imposing the derivative of the field in the outward normal direction proportional to its value at the boundary
- *CurvatureBC*: Imposing a constant second derivative (curvature) of the field at the boundary

There are corresponding classes that only affect the normal component of a field, which can be useful when dealing with vector and tensor fields.

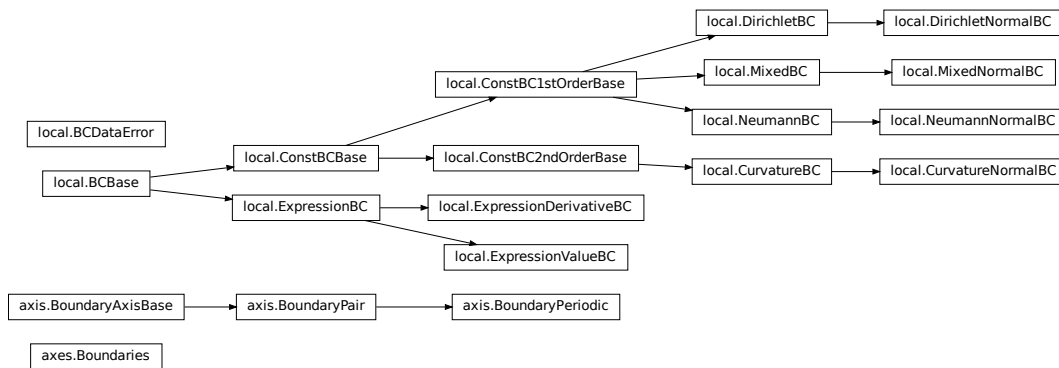
#### Boundaries for an axis:

- *BoundaryPair*: Uses the local boundary conditions to specify the two boundaries along an axis
- *BoundaryPeriodic*: Indicates that an axis has periodic boundary conditions

#### Boundaries for all axes of a grid:

- *Boundaries*: Collection of boundaries to describe conditions for all axes

#### Inheritance structure of the classes:



The details of the classes are explained below:

#### pde.grids.boundaries.axes module

This module handles the boundaries of all axes of a grid. It only defines *Boundaries*, which acts as a list of *BoundaryAxisBase*.

**class Boundaries** (*boundaries*)

Bases: *list*

class that bundles all boundary conditions for all axes

initialize with a list of boundaries

**check\_value\_rank** (*rank: int*) → *None*

check whether the values at the boundaries have the correct rank

**Parameters** *rank* (*int*) – The tensorial rank of the field for this boundary condition

**Throws:** *RuntimeError*: if any value does not have rank *rank*

**copy** () → *Boundaries*

create a copy of the current boundaries

**extract\_component** (\**indices*) → *Boundaries*

extracts the boundary conditions of the given component of the tensor.

**Parameters** \**indices* – One or two indices for vector or tensor fields, respectively

**classmethod from\_data** (*grid*: *GridBase*, *boundaries*, *rank*: *int* = 0) → *Boundaries*

Creates all boundaries from given data

**Parameters**

- **grid** (*GridBase*) – The grid with which the boundary condition is associated
- **boundaries** (*str or list or tuple or dict*) – Data that describes the boundaries. This can either be a list of specifications for each dimension or a single one, which is then applied to all dimensions. The boundary for a dimensions can be specified by one of the following formats:
  - string specifying a single type for all boundaries
  - dictionary specifying the type and values for all boundaries
  - tuple pair specifying the low and high boundary individually
- **rank** (*int*) – The tensorial rank of the field for this boundary condition

**classmethod get\_help** () → *str*

Return information on how boundary conditions can be set

**grid**: *pde.grids.base.GridBase*

*GridBase*: The grid for which the boundaries are defined

**make\_ghost\_cell\_setter** () → *Callable[[...], None]*

return function that sets the ghost cells on a full array

**property periodic**: *List[bool]*

a boolean array indicating which dimensions are periodic according to the boundary conditions

**Type** *ndarray*

**set\_ghost\_cells** (*data\_full*: *numpy.ndarray*, \*, *args=None*) → *None*

set the ghost cells for all boundaries

**Parameters**

- **data\_full** (*ndarray*) – The full field data including ghost points
- **args** – Additional arguments that might be supported by special boundary conditions.

## pde.grids.boundaries.axis module

This module handles the boundaries of a single axis of a grid. There are generally only two options, depending on whether the axis of the underlying grid is defined as periodic or not. If it is periodic, the class *BoundaryPeriodic* should be used, while non-periodic axes have more option, which are represented by *BoundaryPair*.

**class BoundaryAxisBase** (*low*: *BCBase*, *high*: *BCBase*)

Bases: *object*

base class for defining boundaries of a single axis in a grid

**Parameters**

- **low** (*BCBase*) – Instance describing the lower boundary

- **high** (*BCBase*) – Instance describing the upper boundary

**property axis:** *int*

The axis along which the boundaries are defined

**Type** *int*

**get\_data** (*idx: Tuple[int, ...]*) → *Tuple[float, Dict[int, float]]*

sets the elements of the sparse representation of this condition

**Parameters** *idx* (*tuple*) – The index of the point that must lie on the boundary condition

**Returns** A constant value and a dictionary with indices and factors that can be used to calculate this virtual point

**Return type** *float, dict*

**get\_point\_evaluator** (*fill: numpy.ndarray = None*) → *Callable[[numpy.ndarray, Tuple[int, ...]], NumberOrArray]*

return a function to evaluate values at a given point

The point can either be a point inside the domain or a virtual point right outside the domain

**Parameters** *fill* (*ndarray*, optional) – Determines how values out of bounds are handled. If *None*, a *DomainError* is raised when out-of-bounds points are requested. Otherwise, the given value is returned.

**Returns**

A function taking a 1d array and an index as an argument, returning the value of the array at this index.

**Return type** *function*

**property grid:** *pde.grids.base.GridBase*

Underlying grid

**Type** *GridBase*

**high:** *pde.grids.boundaries.local.BCBase*

Boundary condition at upper end

**Type** *BCBase*

**low:** *pde.grids.boundaries.local.BCBase*

Boundary condition at lower end

**Type** *BCBase*

**make\_derivative\_evaluator** (*order: int = 1*) → *Callable[[numpy.ndarray, Tuple[int, ...]], NumberOrArray]*

return a function to evaluate the derivative at a point

**Parameters** *order* (*int*) – The order of the derivative

**Returns** A function that can be called with the data array and a tuple indicating around what point the derivative is evaluated. The function returns the central finite difference at the point. The function takes boundary conditions into account if the point lies on the boundary.

**Return type** *function*

**make\_ghost\_cell\_setter** () → *Callable[[...], None]*

return function that sets the ghost cells for this axis on a full array

**make\_region\_evaluator** () → `Callable[[numpy.ndarray, Tuple[int, ...]], Tuple[NumberOrArray, NumberOrArray, NumberOrArray]]`

return a function to evaluate values in a neighborhood of a point

**Returns** A function that can be called with the data array and a tuple indicating around what point the region is evaluated. The function returns the data values left of the point, at the point, and right of the point along the axis associated with this boundary condition. The function takes boundary conditions into account if the point lies on the boundary.

**Return type** `function`

**make\_virtual\_point\_evaluators** () → `Tuple[Callable[\[...\], float], Callable[\[...\], float]]`

returns two functions evaluating the value at virtual support points

**Returns** Two functions that each take a 1d array as an argument and return the associated value at the virtual support point outside the lower and upper boundary, respectively.

**Return type** `tuple`

**property periodic:** `bool`

whether the axis is periodic

**Type** `bool`

**set\_ghost\_cells** (*data\_full*: [numpy.ndarray](#), \*, *args*=None) → `None`

set the ghost cell values for all boundaries

**Parameters**

- **data\_full** ([ndarray](#)) – The full field data including ghost points
- **args** – Additional arguments that might be supported by special boundary conditions.

**class BoundaryPair** (*low*: [BCBase](#), *high*: [BCBase](#))

Bases: [pde.grids.boundaries.axis.BoundaryAxisBase](#)

represents the two boundaries of an axis along a single dimension

**Parameters**

- **low** ([BCBase](#)) – Instance describing the lower boundary
- **high** ([BCBase](#)) – Instance describing the upper boundary

**check\_value\_rank** (*rank*: [int](#)) → `None`

check whether the values at the boundaries have the correct rank

**Parameters** **rank** ([int](#)) – The tensorial rank of the field for this boundary condition

**Throws:** `RuntimeError`: if the value does not have rank *rank*

**copy** () → [BoundaryPair](#)

return a copy of itself, but with a reference to the same grid

**extract\_component** (\**indices*) → [BoundaryPair](#)

extracts the boundary pair of the given index.

**Parameters** \***indices** – One or two indices for vector or tensor fields, respectively

**classmethod from\_data** (*grid*: [GridBase](#), *axis*: [int](#), *data*, *rank*: [int](#) = 0) → [BoundaryPair](#)

create boundary pair from some data

**Parameters**

- **grid** ([GridBase](#)) – The grid for which the boundary conditions are defined

- **axis** (*int*) – The axis to which this boundary condition is associated
- **data** (*str or dict*) – Data that describes the boundary pair
- **rank** (*int*) – The tensorial rank of the field for this boundary condition

**Returns** the instance created from the data

**Return type** *BoundaryPair*

**Throws:** *ValueError* if *data* cannot be interpreted as a boundary pair

**classmethod** `get_help()` → *str*

Return information on how boundary conditions can be set

**high:** *pde.grids.boundaries.local.BCBase*

Boundary condition at upper end

**Type** *BCBase*

**low:** *pde.grids.boundaries.local.BCBase*

Boundary condition at lower end

**Type** *BCBase*

**class** *BoundaryPeriodic* (*grid: GridBase, axis: int*)

Bases: *pde.grids.boundaries.axis.BoundaryPair*

represent a periodic axis

#### Parameters

- **grid** (*GridBase*) – The grid for which the boundary conditions are defined
- **axis** (*int*) – The axis to which this boundary condition is associated

**check\_value\_rank** (*rank: int*) → *None*

check whether the values at the boundaries have the correct rank

**Parameters** **rank** (*int*) – The tensorial rank of the field for this boundary condition

**copy** () → *BoundaryPeriodic*

return a copy of itself, but with a reference to the same grid

**extract\_component** (\**indices*) → *BoundaryPeriodic*

extracts the boundary pair of the given extract\_component.

**Parameters** \***indices** – One or two indices for vector or tensor fields, respectively

**high:** *pde.grids.boundaries.local.BCBase*

Boundary condition at upper end

**Type** *BCBase*

**low:** *pde.grids.boundaries.local.BCBase*

Boundary condition at lower end

**Type** *BCBase*

**get\_boundary\_axis** (*grid: GridBase, axis: int, data, rank: int = 0*) → *BoundaryAxisBase*

return object representing the boundary condition for a single axis

#### Parameters

- **grid** (*GridBase*) – The grid for which the boundary conditions are defined
- **axis** (*int*) – The axis to which this boundary condition is associated

- **data** (*str or tuple or dict*) – Data describing the boundary conditions for this axis
- **rank** (*int*) – The tensorial rank of the field for this boundary condition

**Returns** Appropriate boundary condition for the axis

**Return type** *BoundaryAxisBase*

## pde.grids.boundaries.local module

This module contains classes for handling a single boundary of a non-periodic axis. Since an axis has two boundary, we simply distinguish them by a boolean flag *upper*, which is True for the side of the axis with the larger coordinate.

The module currently supports different boundary conditions:

- *DirichletBC*: Imposing the value of a field at the boundary
- *NeumannBC*: Imposing the derivative of a field in the outward normal direction at the boundary
- *MixedBC*: Imposing the derivative of a field in the outward normal direction proportional to its value at the boundary
- *CurvatureBC*: Imposing the second derivative (curvature) of a field at the boundary

There are also additional classes that impose boundary conditions only for the normal components of fields, which can be important for vector and tensor fields. The classes corresponding to the ones listed above are *DirichletNormalBC*, *NeumannNormalBC*, *MixedNormalBC*, and *CurvatureNormalBC*.

Note that derivatives are generally given in the direction of the outward normal vector, such that positive derivatives correspond to a function that increases across the boundary.

**class** *BCBase* (*grid*: *GridBase*, *axis*: *int*, *upper*: *bool*, \*, *rank*: *int* = 0)

Bases: *object*

represents a single boundary in an *BoundaryPair* instance

### Parameters

- **grid** (*GridBase*) – The grid for which the boundary conditions are defined
- **axis** (*int*) – The axis to which this boundary condition is associated
- **upper** (*bool*) – Flag indicating whether this boundary condition is associated with the upper side of an axis or not. In essence, this determines the direction of the local normal vector of the boundary.
- **rank** (*int*) – The tensorial rank of the field for this boundary condition

**property** *axis\_coord*: *float*

value of the coordinate that defines this boundary condition

**Type** *float*

**check\_value\_rank** (*rank*: *int*) → *None*

check whether the values at the boundaries have the correct rank

**Parameters** **rank** (*int*) – The tensorial rank of the field for this boundary condition

**Throws:** *RuntimeError*: if the value does not have rank *rank*

**abstract** **copy** (*upper*: *Optional[bool]* = *None*, *rank*: *int* = *None*) → *BCBase*

**abstract** **extract\_component** (\**indices*)

**classmethod** `from_data` (*grid*: `GridBase`, *axis*: `int`, *upper*: `bool`, *data*: `Union[Dict, str, BCBase]`, *rank*: `int` = 0) → `BCBase`

create boundary from some data

#### Parameters

- **grid** (`GridBase`) – The grid for which the boundary conditions are defined
- **axis** (`int`) – The axis to which this boundary condition is associated
- **upper** (`bool`) – Indicates whether this boundary condition is associated with the upper or lower side of the axis.
- **data** (`str` or `dict`) – Data that describes the boundary
- **rank** (`int`) – The tensorial rank of the field for this boundary condition

**Returns** the instance created from the data

**Return type** `BCBase`

**Throws:** `ValueError` if *data* cannot be interpreted as a boundary condition

**classmethod** `from_dict` (*grid*: `GridBase`, *axis*: `int`, *upper*: `bool`, *data*: `Dict[str, Any]`, *rank*: `int` = 0) → `BCBase`

create boundary from data given in dictionary

#### Parameters

- **grid** (`GridBase`) – The grid for which the boundary conditions are defined
- **axis** (`int`) – The axis to which this boundary condition is associated
- **upper** (`bool`) – Indicates whether this boundary condition is associated with the upper or lower side of the axis.
- **data** (`dict`) – The dictionary defining the boundary condition
- **rank** (`int`) – The tensorial rank of the field for this boundary condition

**classmethod** `from_str` (*grid*: `GridBase`, *axis*: `int`, *upper*: `bool`, *condition*: `str`, *rank*: `int` = 0, **\*\*kwargs**) → `BCBase`

creates boundary from a given string identifier

#### Parameters

- **grid** (`GridBase`) – The grid for which the boundary conditions are defined
- **axis** (`int`) – The axis to which this boundary condition is associated
- **upper** (`bool`) – Indicates whether this boundary condition is associated with the upper or lower side of the axis.
- **condition** (`str`) – Identifies the boundary condition
- **rank** (`int`) – The tensorial rank of the field for this boundary condition
- **\*\*kwargs** – Additional arguments passed to the constructor

**get\_data** (*idx*: `Tuple[int, ...]`) → `Tuple[float, Dict[int, float]]`

**classmethod** `get_help` () → `str`

Return information on how boundary conditions can be set

**get\_virtual\_point** (*arr*, *idx*: `Optional[Tuple[int, ...]]` = None) → `float`

**homogeneous:** `bool`

determines whether the boundary condition depends on space

Type `bool`

**make\_adjacent\_evaluator** () → `Callable[[numpy.ndarray, int, Tuple[int, ...]], float]`

**make\_ghost\_cell\_setter** () → `Callable[[...], None]`

return function that sets the ghost cells for this boundary

**abstract make\_virtual\_point\_evaluator** () → `Callable[[...], float]`

**names:** `List[str]`

identifiers used to specify the given boundary class

Type `list`

**normal:** `bool = False`

Flag indicating whether only the normal components are affected

Type `bool`

**property periodic:** `bool`

whether the axis is periodic

Type `bool`

**abstract set\_ghost\_cells** (*data\_full*: `numpy.ndarray`, \*, *args*=None) → `None`

set the ghost cell values for this boundary

**exception BCDataError**

Bases: `ValueError`

exception that signals that incompatible data was supplied for the BC

**class ConstBC1stOrderBase** (*grid*: `GridBase`, *axis*: `int`, *upper*: `bool`, \*, *rank*: `int = 0`, *value*: `Union[float, numpy.ndarray, str] = 0`)

Bases: `pde.grids.boundaries.local.ConstBCBase`

represents a single boundary in an `BoundaryPair` instance

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur. However, the function is safe when *value* cannot be an arbitrary string.

### Parameters

- **grid** (`GridBase`) – The grid for which the boundary conditions are defined
- **axis** (`int`) – The axis to which this boundary condition is associated
- **upper** (`bool`) – Flag indicating whether this boundary condition is associated with the upper side of an axis or not. In essence, this determines the direction of the local normal vector of the boundary.
- **rank** (`int`) – The tensorial rank of the field for this boundary condition
- **value** (`float` or `str` or `ndarray`) – a value stored with the boundary condition. The interpretation of this value depends on the type of boundary condition. If *value* is a single value (or tensor in case of tensorial boundary conditions), the same value is applied to all points. Inhomogeneous boundary conditions are possible by supplying an expression as a string, which then may depend on the axes names of the respective grid.

**get\_data** (*idx*: *Tuple[int, ...]*) → *Tuple[float, Dict[int, float]]*

sets the elements of the sparse representation of this condition

**Parameters** *idx* (*tuple*) – The index of the point that must lie on the boundary condition

**Returns** A constant value and a dictionary with indices and factors that can be used to calculate this virtual point

**Return type** *float, dict*

**get\_virtual\_point** (*arr*, *idx*: *Optional[Tuple[int, ...]] = None*) → *float*

calculate the value of the virtual point outside the boundary

**Parameters**

- **arr** (*array*) – The data values associated with the grid
- **idx** (*tuple*) – The index of the point to evaluate. This is a tuple of length *grid.num\_axes* with the either -1 or *dim* as the entry for the axis associated with this boundary condition. Here, *dim* is the dimension of the axis. The index is optional if *dim* == 1.

**Returns** Value at the virtual support point

**Return type** *float*

**abstract get\_virtual\_point\_data** (*compiled*: *bool = False*) → *Tuple[Any, Any, int]*

**make\_adjacent\_evaluator** () → *Callable[[numpy.ndarray, int, Tuple[int, ...]], float]*

returns a function evaluating the value adjacent to a given point

**Returns** A function with signature (*arr\_1d*, *i\_point*, *bc\_idx*), where *arr\_1d* is the one-dimensional data array (the data points along the axis perpendicular to the boundary), *i\_point* is the index into this array for the current point and *bc\_idx* are the remaining indices of the current point, which indicate the location on the boundary plane. The result of the function is the data value at the adjacent point along the axis associated with this boundary condition in the upper (lower) direction when *upper* is True (False).

**Return type** *function*

**make\_virtual\_point\_evaluator** () → *Callable[[...], float]*

returns a function evaluating the value at the virtual support point

**Returns** A function that takes the data array and an index marking the current point, which is assumed to be a virtual point. The result is the data value at this point, which is calculated using the boundary condition.

**Return type** *function*

**set\_ghost\_cells** (*data\_full*: *numpy.ndarray*, \*, *args=None*) → *None*

set the ghost cell values for this boundary

**Parameters**

- **data\_full** (*ndarray*) – The full field data including ghost points
- **args** – Additional arguments that might be supported by special boundary conditions.

**value\_is\_linked**: *bool*

flag that indicates whether the value associated with this boundary condition is linked to *ndarray* managed by external code.

**Type** *bool*

```
class ConstBC2ndOrderBase (grid: GridBase, axis: int, upper: bool, *, rank: int = 0, value: Union[float,
                                                                    numpy.ndarray, str] = 0)
```

Bases: `pde.grids.boundaries.local.ConstBCBase`

abstract base class for boundary conditions of 2nd order

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur. However, the function is safe when *value* cannot be an arbitrary string.

### Parameters

- **grid** (*GridBase*) – The grid for which the boundary conditions are defined
- **axis** (*int*) – The axis to which this boundary condition is associated
- **upper** (*bool*) – Flag indicating whether this boundary condition is associated with the upper side of an axis or not. In essence, this determines the direction of the local normal vector of the boundary.
- **rank** (*int*) – The tensorial rank of the field for this boundary condition
- **value** (float or str or *ndarray*) – a value stored with the boundary condition. The interpretation of this value depends on the type of boundary condition. If value is a single value (or tensor in case of tensorial boundary conditions), the same value is applied to all points. Inhomogeneous boundary conditions are possible by supplying an expression as a string, which then may depend on the axes names of the respective grid.

```
get_data (idx: Tuple[int, ...]) → Tuple[float, Dict[int, float]]
```

sets the elements of the sparse representation of this condition

**Parameters** **idx** (*tuple*) – The index of the point that must lie on the boundary condition

**Returns** A constant value and a dictionary with indices and factors that can be used to calculate this virtual point

**Return type** *float, dict*

```
get_virtual_point (arr, idx: Optional[Tuple[int, ...]] = None) → float
```

calculate the value of the virtual point outside the boundary

### Parameters

- **arr** (*array*) – The data values associated with the grid
- **idx** (*tuple*) – The index of the point to evaluate. This is a tuple of length *grid.num\_axes* with the either -1 or *dim* as the entry for the axis associated with this boundary condition. Here, *dim* is the dimension of the axis. The index is optional if *dim* == 1.

**Returns** Value at the virtual support point

**Return type** *float*

```
abstract get_virtual_point_data () → Tuple[Any, Any, int, Any, int]
```

return data suitable for calculating virtual points

**Returns** the data associated with this virtual point

**Return type** *tuple*

```
make_adjacent_evaluator () → Callable[[numpy.ndarray, int, Tuple[int, ...]], float]
```

returns a function evaluating the value adjacent to a given point

**Returns** A function with signature `(arr_1d, i_point, bc_idx)`, where *arr\_1d* is the one-dimensional data array (the data points along the axis perpendicular to the boundary), *i\_point* is the index into this array for the current point and *bc\_idx* are the remaining indices of the current point, which indicate the location on the boundary plane. The result of the function is the data value at the adjacent point along the axis associated with this boundary condition in the upper (lower) direction when *upper* is True (False).

**Return type** function

**make\_virtual\_point\_evaluator** () → `Callable[[...], float]`  
returns a function evaluating the value at the virtual support point

**Returns** A function that takes the data array and an index marking the current point, which is assumed to be a virtual point. The result is the data value at this point, which is calculated using the boundary condition.

**Return type** function

**set\_ghost\_cells** (*data\_full*: `numpy.ndarray`, \*, *args*=None) → None  
set the ghost cell values for this boundary

**Parameters**

- **data\_full** (`ndarray`) – The full field data including ghost points
- **args** – Additional arguments that might be supported by special boundary conditions.

**value\_is\_linked**: `bool`  
flag that indicates whether the value associated with this boundary condition is linked to `ndarray` managed by external code.

**Type** `bool`

**class ConstBCBase** (*grid*: `GridBase`, *axis*: `int`, *upper*: `bool`, \*, *rank*: `int` = 0, *value*: `Union[float, numpy.ndarray, str]` = 0)

Bases: `pde.grids.boundaries.local.BCBase`

base class representing a boundary whose virtual point is set from constants

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur. However, the function is safe when *value* cannot be an arbitrary string.

**Parameters**

- **grid** (`GridBase`) – The grid for which the boundary conditions are defined
- **axis** (`int`) – The axis to which this boundary condition is associated
- **upper** (`bool`) – Flag indicating whether this boundary condition is associated with the upper side of an axis or not. In essence, this determines the direction of the local normal vector of the boundary.
- **rank** (`int`) – The tensorial rank of the field for this boundary condition
- **value** (float or str or `ndarray`) – a value stored with the boundary condition. The interpretation of this value depends on the type of boundary condition. If value is a single value (or tensor in case of tensorial boundary conditions), the same value is applied to all points. Inhomogeneous boundary conditions are possible by supplying an expression as a string, which then may depend on the axes names of the respective grid.

**copy** (*upper*: *Optional[bool]* = *None*, *rank*: *int* = *None*, *value*: *Optional[Union[float, numpy.ndarray, str]]* = *None*) → *ConstBCBase*

return a copy of itself, but with a reference to the same grid

**extract\_component** (*\*indices*)

extracts the boundary conditions for the given component

**Parameters** *\*indices* – One or two indices for vector or tensor fields, respectively

**link\_value** (*value*: *numpy.ndarray*)

link value of this boundary condition to external array

**property value**: *numpy.ndarray*

**value\_is\_linked**: *bool*

flag that indicates whether the value associated with this boundary condition is linked to *ndarray* managed by external code.

**Type** *bool*

**class CurvatureBC** (*grid*: *GridBase*, *axis*: *int*, *upper*: *bool*, *\**, *rank*: *int* = *0*, *value*: *Union[float, numpy.ndarray, str]* = *0*)

Bases: *pde.grids.boundaries.local.ConstBC2ndOrderBase*

represents a boundary condition imposing the 2nd normal derivative at the boundary

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur. However, the function is safe when *value* cannot be an arbitrary string.

#### Parameters

- **grid** (*GridBase*) – The grid for which the boundary conditions are defined
- **axis** (*int*) – The axis to which this boundary condition is associated
- **upper** (*bool*) – Flag indicating whether this boundary condition is associated with the upper side of an axis or not. In essence, this determines the direction of the local normal vector of the boundary.
- **rank** (*int*) – The tensorial rank of the field for this boundary condition
- **value** (*float* or *str* or *ndarray*) – a value stored with the boundary condition. The interpretation of this value depends on the type of boundary condition. If *value* is a single value (or tensor in case of tensorial boundary conditions), the same value is applied to all points. Inhomogeneous boundary conditions are possible by supplying an expression as a string, which then may depend on the axes names of the respective grid.

**get\_virtual\_point\_data** () → *Tuple[numpy.ndarray, numpy.ndarray, int, numpy.ndarray, int]*

return data suitable for calculating virtual points

**Returns** the data structure associated with this virtual point

**Return type** *tuple*

**homogeneous**: *bool*

determines whether the boundary condition depends on space

**Type** *bool*

**names**: *List[str]* = ['curvature', 'second\_derivative', 'extrapolate']

identifiers used to specify the given boundary class

Type `list`

**normal:** `bool` = `False`

Flag indicating whether only the normal components are affected

Type `bool`

**value\_is\_linked:** `bool`

flag that indicates whether the value associated with this boundary condition is linked to `ndarray` managed by external code.

Type `bool`

```
class CurvatureNormalBC (grid: GridBase, axis: int, upper: bool, *, rank: int = 0, value: Union[float,
                                                                    numpy.ndarray, str] = 0)
```

Bases: `pde.grids.boundaries.local.CurvatureBC`

represents a boundary condition imposing the 2nd normal derivative at the boundary only on the normal component of the tensor field

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur. However, the function is safe when *value* cannot be an arbitrary string.

#### Parameters

- **grid** (`GridBase`) – The grid for which the boundary conditions are defined
- **axis** (`int`) – The axis to which this boundary condition is associated
- **upper** (`bool`) – Flag indicating whether this boundary condition is associated with the upper side of an axis or not. In essence, this determines the direction of the local normal vector of the boundary.
- **rank** (`int`) – The tensorial rank of the field for this boundary condition
- **value** (float or str or `ndarray`) – a value stored with the boundary condition. The interpretation of this value depends on the type of boundary condition. If value is a single value (or tensor in case of tensorial boundary conditions), the same value is applied to all points. Inhomogeneous boundary conditions are possible by supplying an expression as a string, which then may depend on the axes names of the respective grid.

**homogeneous:** `bool`

determines whether the boundary condition depends on space

Type `bool`

**names:** `List[str]` = `['curvature_normal']`

identifiers used to specify the given boundary class

Type `list`

**normal:** `bool` = `True`

Flag indicating whether only the normal components are affected

Type `bool`

**value\_is\_linked:** `bool`

flag that indicates whether the value associated with this boundary condition is linked to `ndarray` managed by external code.

Type `bool`

```
class DirichletBC (grid: GridBase, axis: int, upper: bool, *, rank: int = 0, value: Union[float, numpy.ndarray, str] = 0)
```

Bases: `pde.grids.boundaries.local.ConstBC1stOrderBase`

represents a boundary condition imposing the value

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur. However, the function is safe when *value* cannot be an arbitrary string.

### Parameters

- **grid** (*GridBase*) – The grid for which the boundary conditions are defined
- **axis** (*int*) – The axis to which this boundary condition is associated
- **upper** (*bool*) – Flag indicating whether this boundary condition is associated with the upper side of an axis or not. In essence, this determines the direction of the local normal vector of the boundary.
- **rank** (*int*) – The tensorial rank of the field for this boundary condition
- **value** (float or str or `ndarray`) – a value stored with the boundary condition. The interpretation of this value depends on the type of boundary condition. If value is a single value (or tensor in case of tensorial boundary conditions), the same value is applied to all points. Inhomogeneous boundary conditions are possible by supplying an expression as a string, which then may depend on the axes names of the respective grid.

```
get_virtual_point_data (compiled: bool = False) → Tuple[Any, Any, int]
```

return data suitable for calculating virtual points

**Parameters** **compiled** (*bool*) – Flag indicating whether a compiled version is required, which automatically takes updated values into account when it is used in numba-compiled code.

**Returns** the data structure associated with this virtual point

**Return type** `BC1stOrderData`

```
homogeneous: bool
```

determines whether the boundary condition depends on space

**Type** `bool`

```
names: List[str] = ['value', 'dirichlet']
```

identifiers used to specify the given boundary class

**Type** `list`

```
normal: bool = False
```

Flag indicating whether only the normal components are affected

**Type** `bool`

```
value_is_linked: bool
```

flag that indicates whether the value associated with this boundary condition is linked to `ndarray` managed by external code.

**Type** `bool`

```
class DirichletNormalBC (grid: GridBase, axis: int, upper: bool, *, rank: int = 0, value: Union[float, numpy.ndarray, str] = 0)
```

Bases: `pde.grids.boundaries.local.DirichletBC`

represents a boundary condition imposing the normal component of a value

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur. However, the function is safe when *value* cannot be an arbitrary string.

#### Parameters

- **grid** (*GridBase*) – The grid for which the boundary conditions are defined
- **axis** (*int*) – The axis to which this boundary condition is associated
- **upper** (*bool*) – Flag indicating whether this boundary condition is associated with the upper side of an axis or not. In essence, this determines the direction of the local normal vector of the boundary.
- **rank** (*int*) – The tensorial rank of the field for this boundary condition
- **value** (float or str or *ndarray*) – a value stored with the boundary condition. The interpretation of this value depends on the type of boundary condition. If value is a single value (or tensor in case of tensorial boundary conditions), the same value is applied to all points. Inhomogeneous boundary conditions are possible by supplying an expression as a string, which then may depend on the axes names of the respective grid.

**homogeneous:** *bool*

determines whether the boundary condition depends on space

Type *bool*

**names:** *List[str]* = ['normal\_value', 'normal\_component', 'value\_normal', 'dirichlet\_normal']

identifiers used to specify the given boundary class

Type *list*

**normal:** *bool* = *True*

Flag indicating whether only the normal components are affected

Type *bool*

**value\_is\_linked:** *bool*

flag that indicates whether the value associated with this boundary condition is linked to *ndarray* managed by external code.

Type *bool*

**class ExpressionBC** (*grid*: *GridBase*, *axis*: *int*, *upper*: *bool*, \*, *rank*: *int* = 0, *value*: *Union[float, str]* = 0, *target*: *str* = 'virtual\_point')

Bases: *pde.grids.boundaries.local.BCBase*

represents a boundary whose virtual point is calculated from an expression

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur.

#### Parameters

- **grid** (*GridBase*) – The grid for which the boundary conditions are defined
- **axis** (*int*) – The axis to which this boundary condition is associated

- **upper** (*bool*) – Flag indicating whether this boundary condition is associated with the upper side of an axis or not. In essence, this determines the direction of the local normal vector of the boundary.
- **rank** (*int*) – The tensorial rank of the field for this boundary condition
- **value** (*float* or *str*) – An expression that determines the value of the boundary condition.
- **target** (*str*) – Selects which value is actually set. Possible choices include *value*, *derivative*, and *virtual\_point*.

**copy** (*upper*: *Optional[bool]* = *None*, *rank*: *int* = *None*) → *ExpressionBC*  
 return a copy of itself, but with a reference to the same grid

**extract\_component** (\**indices*)  
 extracts the boundary conditions for the given component

**Parameters** \**indices* – One or two indices for vector or tensor fields, respectively

**get\_data** (*idx*: *Tuple[int, ...]*) → *Tuple[float, Dict[int, float]]*

**get\_virtual\_point** (*arr*, *idx*: *Optional[Tuple[int, ...]]* = *None*) → *float*

**homogeneous**: *bool*  
 determines whether the boundary condition depends on space

**Type** *bool*

**make\_adjacent\_evaluator** () → *Callable[[numpy.ndarray, int, Tuple[int, ...]], float]*

**make\_virtual\_point\_evaluator** () → *Callable[[...], float]*  
 returns a function evaluating the value at the virtual support point

**Returns** A function that takes the data array and an index marking the current point, which is assumed to be a virtual point. The result is the data value at this point, which is calculated using the boundary condition.

**Return type** *function*

**names**: *List[str]* = ['virtual\_point']  
 identifiers used to specify the given boundary class

**Type** *list*

**set\_ghost\_cells** (*data\_full*: *numpy.ndarray*, \*, *args*=*None*) → *None*  
 set the ghost cell values for this boundary

**Parameters**

- **data\_full** (*ndarray*) – The full field data including ghost points
- **args** – Additional arguments that might be supported by special boundary conditions.

**class ExpressionDerivativeBC** (*grid*: *GridBase*, *axis*: *int*, *upper*: *bool*, \*, *rank*: *int* = 0, *value*: *Union[float, str]* = 0, *target*: *str* = 'derivative')

Bases: *pde.grids.boundaries.local.ExpressionBC*

represents a boundary whose outward derivative is calculated from an expression

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur.

**Parameters**

- **grid** (*GridBase*) – The grid for which the boundary conditions are defined
- **axis** (*int*) – The axis to which this boundary condition is associated
- **upper** (*bool*) – Flag indicating whether this boundary condition is associated with the upper side of an axis or not. In essence, this determines the direction of the local normal vector of the boundary.
- **rank** (*int*) – The tensorial rank of the field for this boundary condition
- **value** (*float or str*) – An expression that determines the value of the boundary condition.
- **target** (*str*) – Selects which value is actually set. Possible choices include *value*, *derivative*, and *virtual\_point*.

**homogeneous:** *bool*

determines whether the boundary condition depends on space

Type *bool*

**names:** *List[str]* = ['*derivative\_expression*', '*derivative\_expr*']

identifiers used to specify the given boundary class

Type *list*

**class ExpressionValueBC** (*grid: GridBase, axis: int, upper: bool, \*, rank: int = 0, value: Union[float, str] = 0, target: str = 'value'*)

Bases: *pde.grids.boundaries.local.ExpressionBC*

represents a boundary whose value is calculated from an expression

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur.

**Parameters**

- **grid** (*GridBase*) – The grid for which the boundary conditions are defined
- **axis** (*int*) – The axis to which this boundary condition is associated
- **upper** (*bool*) – Flag indicating whether this boundary condition is associated with the upper side of an axis or not. In essence, this determines the direction of the local normal vector of the boundary.
- **rank** (*int*) – The tensorial rank of the field for this boundary condition
- **value** (*float or str*) – An expression that determines the value of the boundary condition.
- **target** (*str*) – Selects which value is actually set. Possible choices include *value*, *derivative*, and *virtual\_point*.

**homogeneous:** *bool*

determines whether the boundary condition depends on space

Type *bool*

**names:** *List[str]* = ['*value\_expression*', '*value\_expr*']

identifiers used to specify the given boundary class

**Type list**

**class MixedBC** (*grid*: GridBase, *axis*: int, *upper*: bool, \*, *rank*: int = 0, *value*: Union[float, numpy.ndarray, str] = 0, *const*: Union[float, numpy.ndarray, str] = 0)

Bases: `pde.grids.boundaries.local.ConstBC1stOrderBase`

represents a mixed (or Robin) boundary condition imposing a derivative in the outward normal direction of the boundary that is given by an affine function involving the actual value:

$$\partial_n c + \gamma c = \beta$$

Here,  $c$  is the field to which the condition is applied,  $\gamma$  quantifies the influence of the field and  $\beta$  is the constant term. Note that  $\gamma = 0$  corresponds to Dirichlet conditions imposing  $\beta$  as the derivative. Conversely,  $\gamma \rightarrow \infty$  corresponds to imposing a zero value on  $c$ .

This condition can be enforced by using one of the following variants

```
bc = {'mixed': VALUE}
bc = {'type': 'mixed', 'value': VALUE, 'const': CONST}
```

where *VALUE* corresponds to  $\gamma$  and *CONST* to  $\beta$ .

**Parameters**

- **grid** (*GridBase*) – The grid for which the boundary conditions are defined
- **axis** (*int*) – The axis to which this boundary condition is associated
- **upper** (*bool*) – Flag indicating whether this boundary condition is associated with the upper side of an axis or not. In essence, this determines the direction of the local normal vector of the boundary.
- **rank** (*int*) – The tensorial rank of the field for this boundary condition
- **value** (*float or str or array*) – The parameter  $\gamma$  quantifying the influence of the field onto its normal derivative. If *value* is a single value (or tensor in case of tensorial boundary conditions), the same value is applied to all points. Inhomogeneous boundary conditions are possible by supplying an expression as a string, which then may depend on the axes names of the respective grid.
- **const** (*float or ndarray or str*) – The parameter  $\beta$  determining the constant term for the boundary condition. Supports the same input as *value*.

**copy** (*upper*: Optional[bool] = None, *rank*: int = None, *value*: Optional[Union[float, numpy.ndarray, str]] = None, *const*: Optional[Union[float, numpy.ndarray, str]] = None) → *MixedBC*  
return a copy of itself, but with a reference to the same grid

**get\_virtual\_point\_data** (*compiled*: bool = False) → Tuple[Any, Any, int]  
return data suitable for calculating virtual points

**Parameters** **compiled** (*bool*) – Flag indicating whether a compiled version is required, which automatically takes updated values into account when it is used in numba-compiled code.

**Returns** the data structure associated with this virtual point

**Return type** BC1stOrderData

**homogeneous**: bool  
determines whether the boundary condition depends on space

**Type** bool

**names**: List[str] = ['mixed', 'robin']  
identifiers used to specify the given boundary class

Type `list`

**normal:** `bool` = `False`

Flag indicating whether only the normal components are affected

Type `bool`

**value\_is\_linked:** `bool`

flag that indicates whether the value associated with this boundary condition is linked to `ndarray` managed by external code.

Type `bool`

**class MixedNormalBC** (*grid*: `GridBase`, *axis*: `int`, *upper*: `bool`, \*, *rank*: `int` = 0, *value*: `Union`[`float`, `numpy.ndarray`, `str`] = 0, *const*: `Union`[`float`, `numpy.ndarray`, `str`] = 0)

Bases: `pde.grids.boundaries.local.MixedBC`

represents a mixed (or Robin) boundary condition imposing a derivative in the outward normal direction of the boundary only for the normal component

#### Parameters

- **grid** (`GridBase`) – The grid for which the boundary conditions are defined
- **axis** (`int`) – The axis to which this boundary condition is associated
- **upper** (`bool`) – Flag indicating whether this boundary condition is associated with the upper side of an axis or not. In essence, this determines the direction of the local normal vector of the boundary.
- **rank** (`int`) – The tensorial rank of the field for this boundary condition
- **value** (`float` or `str` or `array`) – The parameter  $\gamma$  quantifying the influence of the field onto its normal derivative. If *value* is a single value (or tensor in case of tensorial boundary conditions), the same value is applied to all points. Inhomogeneous boundary conditions are possible by supplying an expression as a string, which then may depend on the axes names of the respective grid.
- **const** (`float` or `ndarray` or `str`) – The parameter  $\beta$  determining the constant term for the boundary condition. Supports the same input as *value*.

**homogeneous:** `bool`

determines whether the boundary condition depends on space

Type `bool`

**names:** `List`[`str`] = [`'mixed_normal'`, `'robin_normal'`]

identifiers used to specify the given boundary class

Type `list`

**normal:** `bool` = `True`

Flag indicating whether only the normal components are affected

Type `bool`

**value\_is\_linked:** `bool`

flag that indicates whether the value associated with this boundary condition is linked to `ndarray` managed by external code.

Type `bool`

**class NeumannBC** (*grid*: `GridBase`, *axis*: `int`, *upper*: `bool`, \*, *rank*: `int` = 0, *value*: `Union`[`float`, `numpy.ndarray`, `str`] = 0)

Bases: `pde.grids.boundaries.local.ConstBC1stOrderBase`

represents a boundary condition imposing the derivative in the outward normal direction of the boundary

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur. However, the function is safe when *value* cannot be an arbitrary string.

### Parameters

- **grid** (*GridBase*) – The grid for which the boundary conditions are defined
- **axis** (*int*) – The axis to which this boundary condition is associated
- **upper** (*bool*) – Flag indicating whether this boundary condition is associated with the upper side of an axis or not. In essence, this determines the direction of the local normal vector of the boundary.
- **rank** (*int*) – The tensorial rank of the field for this boundary condition
- **value** (float or str or *ndarray*) – a value stored with the boundary condition. The interpretation of this value depends on the type of boundary condition. If value is a single value (or tensor in case of tensorial boundary conditions), the same value is applied to all points. Inhomogeneous boundary conditions are possible by supplying an expression as a string, which then may depend on the axes names of the respective grid.

**get\_virtual\_point\_data** (*compiled: bool = False*) → *Tuple*[*Any*, *Any*, *int*]  
 return data suitable for calculating virtual points

**Parameters** **compiled** (*bool*) – Flag indicating whether a compiled version is required, which automatically takes updated values into account when it is used in numba-compiled code.

**Returns** the data structure associated with this virtual point

**Return type** *BC1stOrderData*

**homogeneous:** *bool*  
 determines whether the boundary condition depends on space

**Type** *bool*

**names:** *List*[*str*] = ['derivative', 'neumann']  
 identifiers used to specify the given boundary class

**Type** *list*

**normal:** *bool* = *False*  
 Flag indicating whether only the normal components are affected

**Type** *bool*

**value\_is\_linked:** *bool*  
 flag that indicates whether the value associated with this boundary condition is linked to *ndarray* managed by external code.

**Type** *bool*

**class** *NeumannNormalBC* (*grid: GridBase*, *axis: int*, *upper: bool*, \*, *rank: int = 0*, *value: Union*[*float*, *numpy.ndarray*, *str*] = *0*)

Bases: *pde.grids.boundaries.local.NeumannBC*

represents a boundary condition imposing the derivative in the outward normal direction of the boundary only on the normal component of the tensor field

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur. However, the function is safe when *value* cannot be an arbitrary string.

### Parameters

- **grid** (*GridBase*) – The grid for which the boundary conditions are defined
- **axis** (*int*) – The axis to which this boundary condition is associated
- **upper** (*bool*) – Flag indicating whether this boundary condition is associated with the upper side of an axis or not. In essence, this determines the direction of the local normal vector of the boundary.
- **rank** (*int*) – The tensorial rank of the field for this boundary condition
- **value** (float or str or *ndarray*) – a value stored with the boundary condition. The interpretation of this value depends on the type of boundary condition. If value is a single value (or tensor in case of tensorial boundary conditions), the same value is applied to all points. Inhomogeneous boundary conditions are possible by supplying an expression as a string, which then may depend on the axes names of the respective grid.

**homogeneous:** *bool*

determines whether the boundary condition depends on space

Type *bool*

**names:** *List[str]* = ['derivative\_normal', 'neumann\_normal']

identifiers used to specify the given boundary class

Type *list*

**normal:** *bool* = *True*

Flag indicating whether only the normal components are affected

Type *bool*

**value\_is\_linked:** *bool*

flag that indicates whether the value associated with this boundary condition is linked to *ndarray* managed by external code.

Type *bool*

**registered\_boundary\_condition\_classes** () → *Dict[str, Type[BCBase]]*

returns all boundary condition classes that are currently defined

**Returns** a dictionary with the names of the boundary condition classes

**Return type** *dict*

**registered\_boundary\_condition\_names** () → *Dict[str, Type[BCBase]]*

returns all named boundary conditions that are currently defined

**Returns** a dictionary with the names of the boundary conditions that can be used

**Return type** *dict*

## 4.2.2 pde.grids.operators package

Package collecting modules defining discretized operators for different grids.

These operators can either be used directly or they are imported by the respective methods defined on fields and grids.

<i>cartesian</i>	This module implements differential operators on Cartesian grids
<i>cylindrical_sym</i>	This module implements differential operators on cylindrical grids
<i>polar_sym</i>	This module implements differential operators on polar grids
<i>spherical_sym</i>	This module implements differential operators on spherical grids

### pde.grids.operators.cartesian module

This module implements differential operators on Cartesian grids

<i>make_laplace</i>	make a laplace operator on a Cartesian grid
<i>make_gradient</i>	make a gradient operator on a Cartesian grid
<i>make_divergence</i>	make a divergence operator on a Cartesian grid
<i>make_vector_gradient</i>	make a vector gradient operator on a Cartesian grid
<i>make_vector_laplace</i>	make a vector Laplacian on a Cartesian grid
<i>make_tensor_divergence</i>	make a tensor divergence operator on a Cartesian grid
<i>make_poisson_solver</i>	make an operator that solves Poisson's equation

**make\_divergence** (*grid*: CartesianGridBase, *backend*: *str* = 'auto') → Callable[[numpy.ndarray, numpy.ndarray], None]

make a divergence operator on a Cartesian grid

#### Parameters

- **grid** (CartesianGridBase) – The grid for which the operator is created
- **backend** (*str*) – Backend used for calculating the divergence operator. If backend='auto', a suitable backend is chosen automatically.

**Returns** A function that can be applied to an array of values

**make\_gradient** (*grid*: CartesianGridBase, *backend*: *str* = 'auto') → Callable[[numpy.ndarray, numpy.ndarray], None]

make a gradient operator on a Cartesian grid

#### Parameters

- **grid** (CartesianGridBase) – The grid for which the operator is created
- **backend** (*str*) – Backend used for calculating the gradient operator. If backend='auto', a suitable backend is chosen automatically.

**Returns** A function that can be applied to an array of values

**make\_laplace** (*grid*: CartesianGridBase, *backend*: *str* = 'auto') → Callable[[numpy.ndarray, numpy.ndarray], None]

make a laplace operator on a Cartesian grid

#### Parameters

- **grid** (*CartesianGridBase*) – The grid for which the operator is created
- **backend** (*str*) – Backend used for calculating the laplace operator. If backend='auto', a suitable backend is chosen automatically.

**Returns** A function that can be applied to an array of values

**make\_poisson\_solver** (*bcs*: *Boundaries*, *method*: *str* = 'auto') → *Callable*[[*numpy.ndarray*, *numpy.ndarray*], *None*]

make a operator that solves Poisson's equation

**Parameters**

- **bcs** (*Boundaries*) – {ARG\_BOUNDARIES\_INSTANCE}
- **method** (*str*) – Method used for calculating the tensor divergence operator. If method='auto', a suitable method is chosen automatically.

**Returns** A function that can be applied to an array of values

**make\_tensor\_divergence** (*grid*: *CartesianGridBase*, *backend*: *str* = 'numba') → *Callable*[[*numpy.ndarray*, *numpy.ndarray*], *None*]

make a tensor divergence operator on a Cartesian grid

**Parameters**

- **grid** (*CartesianGridBase*) – The grid for which the operator is created
- **backend** (*str*) – Backend used for calculating the tensor divergence operator.

**Returns** A function that can be applied to an array of values

**make\_vector\_gradient** (*grid*: *CartesianGridBase*, *backend*: *str* = 'numba') → *Callable*[[*numpy.ndarray*, *numpy.ndarray*], *None*]

make a vector gradient operator on a Cartesian grid

**Parameters**

- **grid** (*CartesianGridBase*) – The grid for which the operator is created
- **backend** (*str*) – Backend used for calculating the vector gradient operator.

**Returns** A function that can be applied to an array of values

**make\_vector\_laplace** (*grid*: *CartesianGridBase*, *backend*: *str* = 'numba') → *Callable*[[*numpy.ndarray*, *numpy.ndarray*], *None*]

make a vector Laplacian on a Cartesian grid

**Parameters**

- **grid** (*CartesianGridBase*) – The grid for which the operator is created
- **backend** (*str*) – Backend used for calculating the vector laplace operator.

**Returns** A function that can be applied to an array of values

## pde.grids.operators.common module

Common functions that are used by many operators

**make\_general\_poisson\_solver** (*matrix*, *vector*, *method*: *str* = 'auto') → Callable[[[numpy.ndarray](#), [numpy.ndarray](#)], None]

make an operator that solves Poisson's problem

### Parameters

- **matrix** – The (sparse) matrix representing the laplace operator on the given grid.
- **vector** – The constant part representing the boundary conditions of the Laplace operator.
- **method** (*str*) – The chosen method for implementing the operator

**Returns** A function that can be applied to an array of values to obtain the solution to Poisson's equation where the array is used as the right hand side

**make\_laplace\_from\_matrix** (*matrix*, *vector*) → Callable[[[numpy.ndarray](#), [numpy.ndarray](#)], None]

make a Laplace operator using matrix vector products

### Parameters

- **matrix** – The (sparse) matrix representing the laplace operator on the given grid.
- **vector** – The constant part representing the boundary conditions of the Laplace operator.

**Returns** A function that can be applied to an array of values to obtain the solution to Poisson's equation where the array is used as the right hand side

**uniform\_discretization** (*grid*: [GridBase](#)) → float

returns the uniform discretization or raises RuntimeError

## pde.grids.operators.cylindrical\_sym module

This module implements differential operators on cylindrical grids

<a href="#"><i>make_laplace</i></a>	make a discretized laplace operator for a cylindrical grid
<a href="#"><i>make_gradient</i></a>	make a discretized gradient operator for a cylindrical grid
<a href="#"><i>make_divergence</i></a>	make a discretized divergence operator for a cylindrical grid
<a href="#"><i>make_vector_gradient</i></a>	make a discretized vector gradient operator for a cylindrical grid
<a href="#"><i>make_vector_laplace</i></a>	make a discretized vector laplace operator for a cylindrical grid
<a href="#"><i>make_tensor_divergence</i></a>	make a discretized tensor divergence operator for a cylindrical grid

**make\_divergence** (*grid*: [CylindricalSymGrid](#)) → Callable[[[numpy.ndarray](#), [numpy.ndarray](#)], None]

make a discretized divergence operator for a cylindrical grid

The cylindrical grid assumes polar symmetry, so that fields only depend on the radial coordinate  $r$  and the axial coordinate  $z$ . Here, the first axis is along the radius, while the second axis is along the axis of the cylinder. The radial discretization is defined as  $r_i = (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ .

**Parameters** **grid** ([CylindricalSymGrid](#)) – The grid for which the operator is created

**Returns** A function that can be applied to an array of values

**make\_gradient** (*grid*: *CylindricalSymGrid*) → *Callable*[[*numpy.ndarray*, *numpy.ndarray*], *None*]  
make a discretized gradient operator for a cylindrical grid

The cylindrical grid assumes polar symmetry, so that fields only depend on the radial coordinate  $r$  and the axial coordinate  $z$ . Here, the first axis is along the radius, while the second axis is along the axis of the cylinder. The radial discretization is defined as  $r_i = (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ .

**Parameters** **grid** (*CylindricalSymGrid*) – The grid for which the operator is created

**Returns** A function that can be applied to an array of values

**make\_gradient\_squared** (*grid*: *CylindricalSymGrid*, *central*: *bool* = *True*) → *Callable*[[*numpy.ndarray*, *numpy.ndarray*], *None*]  
make a discretized gradient squared operator for a cylindrical grid

The cylindrical grid assumes polar symmetry, so that fields only depend on the radial coordinate  $r$  and the axial coordinate  $z$ . Here, the first axis is along the radius, while the second axis is along the axis of the cylinder. The radial discretization is defined as  $r_i = (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ .

**Parameters**

- **grid** (*CylindricalSymGrid*) – The grid for which the operator is created
- **central** (*bool*) – Whether a central difference approximation is used for the gradient operator. If this is *False*, the squared gradient is calculated as the mean of the squared values of the forward and backward derivatives.

**Returns** A function that can be applied to an array of values

**make\_laplace** (*grid*: *CylindricalSymGrid*) → *Callable*[[*numpy.ndarray*, *numpy.ndarray*], *None*]  
make a discretized laplace operator for a cylindrical grid

The cylindrical grid assumes polar symmetry, so that fields only depend on the radial coordinate  $r$  and the axial coordinate  $z$ . Here, the first axis is along the radius, while the second axis is along the axis of the cylinder. The radial discretization is defined as  $r_i = (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ .

**Parameters** **grid** (*CylindricalSymGrid*) – The grid for which the operator is created

**Returns** A function that can be applied to an array of values

**make\_tensor\_divergence** (*grid*: *CylindricalSymGrid*) → *Callable*[[*numpy.ndarray*, *numpy.ndarray*], *None*]  
make a discretized tensor divergence operator for a cylindrical grid

The cylindrical grid assumes polar symmetry, so that fields only depend on the radial coordinate  $r$  and the axial coordinate  $z$ . Here, the first axis is along the radius, while the second axis is along the axis of the cylinder. The radial discretization is defined as  $r_i = (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ .

**Parameters** **grid** (*CylindricalSymGrid*) – The grid for which the operator is created

**Returns** A function that can be applied to an array of values

**make\_vector\_gradient** (*grid*: *CylindricalSymGrid*) → *Callable*[[*numpy.ndarray*, *numpy.ndarray*], *None*]  
make a discretized vector gradient operator for a cylindrical grid

The cylindrical grid assumes polar symmetry, so that fields only depend on the radial coordinate  $r$  and the axial coordinate  $z$ . Here, the first axis is along the radius, while the second axis is along the axis of the cylinder. The radial discretization is defined as  $r_i = (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ .

**Parameters** **grid** (*CylindricalSymGrid*) – The grid for which the operator is created

**Returns** A function that can be applied to an array of values

**make\_vector\_laplace** (*grid*: *CylindricalSymGrid*) → *Callable*[[*numpy.ndarray*, *numpy.ndarray*], *None*]  
make a discretized vector laplace operator for a cylindrical grid

The cylindrical grid assumes polar symmetry, so that fields only depend on the radial coordinate  $r$  and the axial coordinate  $z$ . Here, the first axis is along the radius, while the second axis is along the axis of the cylinder. The radial discretization is defined as  $r_i = (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ .

**Parameters** `grid` (*CylindricalSymGrid*) – The grid for which the operator is created

**Returns** A function that can be applied to an array of values

## pde.grids.operators.polar\_sym module

This module implements differential operators on polar grids

<code>make_laplace</code>	make a discretized laplace operator for a polar grid
<code>make_gradient</code>	make a discretized gradient operator for a polar grid
<code>make_divergence</code>	make a discretized divergence operator for a polar grid
<code>make_vector_gradient</code>	make a discretized vector gradient operator for a polar grid
<code>make_tensor_divergence</code>	make a discretized tensor divergence operator for a polar grid

**make\_divergence** (*grid*: *PolarSymGrid*)  $\rightarrow$  *Callable*[[*numpy.ndarray*, *numpy.ndarray*], *None*]  
make a discretized divergence operator for a polar grid

The polar grid assumes polar symmetry, so that fields only depend on the radial coordinate  $r$ . The radial discretization is defined as  $r_i = r_{\min} + (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ , where  $r_{\min}$  is the radius of the inner boundary, which is zero by default. Note that the radius of the outer boundary is given by  $r_{\max} = r_{\min} + N_r\Delta r$ .

**Parameters** `grid` (*PolarSymGrid*) – The polar grid for which this operator will be defined

**Returns** A function that can be applied to an array of values

**make\_gradient** (*grid*: *PolarSymGrid*)  $\rightarrow$  *Callable*[[*numpy.ndarray*, *numpy.ndarray*], *None*]  
make a discretized gradient operator for a polar grid

The polar grid assumes polar symmetry, so that fields only depend on the radial coordinate  $r$ . The radial discretization is defined as  $r_i = r_{\min} + (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ , where  $r_{\min}$  is the radius of the inner boundary, which is zero by default. Note that the radius of the outer boundary is given by  $r_{\max} = r_{\min} + N_r\Delta r$ .

**Parameters** `grid` (*PolarSymGrid*) – The polar grid for which this operator will be defined

**Returns** A function that can be applied to an array of values

**make\_gradient\_squared** (*grid*: *PolarSymGrid*, *central*: *bool* = *True*)  $\rightarrow$  *Callable*[[*numpy.ndarray*, *numpy.ndarray*], *None*]  
make a discretized gradient squared operator for a polar grid

The polar grid assumes polar symmetry, so that fields only depend on the radial coordinate  $r$ . The radial discretization is defined as  $r_i = r_{\min} + (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ , where  $r_{\min}$  is the radius of the inner boundary, which is zero by default. Note that the radius of the outer boundary is given by  $r_{\max} = r_{\min} + N_r\Delta r$ .

**Parameters**

- **grid** (*PolarSymGrid*) – The polar grid for which this operator will be defined
- **central** (*bool*) – Whether a central difference approximation is used for the gradient operator. If this is *False*, the squared gradient is calculated as the mean of the squared values of the forward and backward derivatives.

**Returns** A function that can be applied to an array of values

**make\_laplace** (*grid*: [PolarSymGrid](#)) → [Callable](#)[[[numpy.ndarray](#), [numpy.ndarray](#)], [None](#)]  
make a discretized laplace operator for a polar grid

The polar grid assumes polar symmetry, so that fields only depend on the radial coordinate  $r$ . The radial discretization is defined as  $r_i = r_{\min} + (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ , where  $r_{\min}$  is the radius of the inner boundary, which is zero by default. Note that the radius of the outer boundary is given by  $r_{\max} = r_{\min} + N_r \Delta r$ .

**Parameters** **grid** ([PolarSymGrid](#)) – The polar grid for which this operator will be defined

**Returns** A function that can be applied to an array of values

**make\_poisson\_solver** (*bcs*: [Boundaries](#), *method*: *str* = 'auto') → [Callable](#)[[[numpy.ndarray](#), [numpy.ndarray](#)], [None](#)]

make a operator that solves Poisson's equation

The polar grid assumes polar symmetry, so that fields only depend on the radial coordinate  $r$ . The radial discretization is defined as  $r_i = r_{\min} + (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ , where  $r_{\min}$  is the radius of the inner boundary, which is zero by default. Note that the radius of the outer boundary is given by  $r_{\max} = r_{\min} + N_r \Delta r$ .

**Parameters**

- **bcs** ([Boundaries](#)) – Specifies the boundary conditions applied to the field. This must be an instance of [Boundaries](#), which can be created from various data formats using the class method [from\\_data\(\)](#).
- **method** (*str*) – The chosen method for implementing the operator

**Returns** A function that can be applied to an array of values

**make\_tensor\_divergence** (*grid*: [PolarSymGrid](#)) → [Callable](#)[[[numpy.ndarray](#), [numpy.ndarray](#)], [None](#)]  
make a discretized tensor divergence operator for a polar grid

The polar grid assumes polar symmetry, so that fields only depend on the radial coordinate  $r$ . The radial discretization is defined as  $r_i = r_{\min} + (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ , where  $r_{\min}$  is the radius of the inner boundary, which is zero by default. Note that the radius of the outer boundary is given by  $r_{\max} = r_{\min} + N_r \Delta r$ .

**Parameters** **grid** ([PolarSymGrid](#)) – The polar grid for which this operator will be defined

**Returns** A function that can be applied to an array of values

**make\_vector\_gradient** (*grid*: [PolarSymGrid](#)) → [Callable](#)[[[numpy.ndarray](#), [numpy.ndarray](#)], [None](#)]  
make a discretized vector gradient operator for a polar grid

The polar grid assumes polar symmetry, so that fields only depend on the radial coordinate  $r$ . The radial discretization is defined as  $r_i = r_{\min} + (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ , where  $r_{\min}$  is the radius of the inner boundary, which is zero by default. Note that the radius of the outer boundary is given by  $r_{\max} = r_{\min} + N_r \Delta r$ .

**Parameters** **grid** ([PolarSymGrid](#)) – The polar grid for which this operator will be defined

**Returns** A function that can be applied to an array of values

## pde.grids.operators.spherical\_sym module

This module implements differential operators on spherical grids

---

<a href="#">make_laplace</a>	make a discretized laplace operator for a spherical grid
<a href="#">make_gradient</a>	make a discretized gradient operator for a spherical grid
<a href="#">make_divergence</a>	make a discretized divergence operator for a spherical grid

---

continues on next page

Table 7 – continued from previous page

<code>make_vector_gradient</code>	make a discretized vector gradient operator for a spherical grid
<code>make_tensor_divergence</code>	make a discretized tensor divergence operator for a spherical grid

**make\_divergence** (*grid*: `SphericalSymGrid`, *safe*: `bool = True`)  $\rightarrow$  `Callable[[numpy.ndarray, numpy.ndarray], None]`

make a discretized divergence operator for a spherical grid

The spherical grid assumes spherical symmetry, so that fields only depend on the radial coordinate  $r$ . The radial discretization is defined as  $r_i = r_{\min} + (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ , where  $r_{\min}$  is the radius of the inner boundary, which is zero by default. Note that the radius of the outer boundary is given by  $r_{\max} = r_{\min} + N_r\Delta r$ .

**Warning:** This operator ignores the  $\theta$ -component of the field when calculating the divergence. This is because the resulting scalar field could not be expressed on a `SphericalSymGrid`.

#### Parameters

- **grid** (`SphericalSymGrid`) – The polar grid for which this operator will be defined
- **safe** (`bool`) – Add extra checks for the validity of the input

**Returns** A function that can be applied to an array of values

**make\_gradient** (*grid*: `SphericalSymGrid`)  $\rightarrow$  `Callable[[numpy.ndarray, numpy.ndarray], None]`

make a discretized gradient operator for a spherical grid

The spherical grid assumes spherical symmetry, so that fields only depend on the radial coordinate  $r$ . The radial discretization is defined as  $r_i = r_{\min} + (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ , where  $r_{\min}$  is the radius of the inner boundary, which is zero by default. Note that the radius of the outer boundary is given by  $r_{\max} = r_{\min} + N_r\Delta r$ .

**Parameters** **grid** (`SphericalSymGrid`) – The polar grid for which this operator will be defined

**Returns** A function that can be applied to an array of values

**make\_gradient\_squared** (*grid*: `SphericalSymGrid`, *central*: `bool = True`)  $\rightarrow$  `Callable[[numpy.ndarray, numpy.ndarray], None]`

make a discretized gradient squared operator for a spherical grid

The spherical grid assumes spherical symmetry, so that fields only depend on the radial coordinate  $r$ . The radial discretization is defined as  $r_i = r_{\min} + (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ , where  $r_{\min}$  is the radius of the inner boundary, which is zero by default. Note that the radius of the outer boundary is given by  $r_{\max} = r_{\min} + N_r\Delta r$ .

#### Parameters

- **grid** (`SphericalSymGrid`) – The polar grid for which this operator will be defined
- **central** (`bool`) – Whether a central difference approximation is used for the gradient operator. If this is `False`, the squared gradient is calculated as the mean of the squared values of the forward and backward derivatives.

**Returns** A function that can be applied to an array of values

**make\_laplace** (*grid*: `SphericalSymGrid`, *conservative*: `bool = True`)  $\rightarrow$  `Callable[[numpy.ndarray, numpy.ndarray], None]`

make a discretized laplace operator for a spherical grid

The spherical grid assumes spherical symmetry, so that fields only depend on the radial coordinate  $r$ . The radial discretization is defined as  $r_i = r_{\min} + (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ , where  $r_{\min}$  is the radius of the inner boundary, which is zero by default. Note that the radius of the outer boundary is given by  $r_{\max} = r_{\min} + N_r\Delta r$ .

#### Parameters

- **grid** (*SphericalSymGrid*) – The polar grid for which this operator will be defined
- **conservative** (*bool*) – Flag indicating whether the laplace operator should be conservative (which results in slightly slower computations).

**Returns** A function that can be applied to an array of values

**make\_poisson\_solver** (*bcs*: *Boundaries*, *method*: *str* = 'auto') → *Callable*[[*numpy.ndarray*, *numpy.ndarray*], *None*]

make a operator that solves Poisson's equation

The polar grid assumes polar symmetry, so that fields only depend on the radial coordinate  $r$ . The radial discretization is defined as  $r_i = r_{\min} + (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ , where  $r_{\min}$  is the radius of the inner boundary, which is zero by default. Note that the radius of the outer boundary is given by  $r_{\max} = r_{\min} + N_r\Delta r$ .

#### Parameters

- **bcs** (*Boundaries*) – Specifies the boundary conditions applied to the field. This must be an instance of *Boundaries*, which can be created from various data formats using the class method *from\_data()*.
- **method** (*str*) – The chosen method for implementing the operator

**Returns** A function that can be applied to an array of values

**make\_tensor\_divergence** (*grid*: *SphericalSymGrid*, *safe*: *bool* = *True*) → *Callable*[[*numpy.ndarray*, *numpy.ndarray*], *None*]

make a discretized tensor divergence operator for a spherical grid

The spherical grid assumes spherical symmetry, so that fields only depend on the radial coordinate  $r$ . The radial discretization is defined as  $r_i = r_{\min} + (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ , where  $r_{\min}$  is the radius of the inner boundary, which is zero by default. Note that the radius of the outer boundary is given by  $r_{\max} = r_{\min} + N_r\Delta r$ .

#### Parameters

- **grid** (*SphericalSymGrid*) – The polar grid for which this operator will be defined
- **safe** (*bool*) – Add extra checks for the validity of the input

**Returns** A function that can be applied to an array of values

**make\_vector\_gradient** (*grid*: *SphericalSymGrid*, *safe*: *bool* = *True*) → *Callable*[[*numpy.ndarray*, *numpy.ndarray*], *None*]

make a discretized vector gradient operator for a spherical grid

**Warning:** This operator ignores the two angular components of the field when calculating the gradient. This is because the resulting field could not be expressed on a *SphericalSymGrid*.

The spherical grid assumes spherical symmetry, so that fields only depend on the radial coordinate  $r$ . The radial discretization is defined as  $r_i = r_{\min} + (i + \frac{1}{2})\Delta r$  for  $i = 0, \dots, N_r - 1$ , where  $r_{\min}$  is the radius of the inner boundary, which is zero by default. Note that the radius of the outer boundary is given by  $r_{\max} = r_{\min} + N_r\Delta r$ .

#### Parameters

- **grid** (*SphericalSymGrid*) – The polar grid for which this operator will be defined
- **safe** (*bool*) – Add extra checks for the validity of the input

**Returns** A function that can be applied to an array of values

### 4.2.3 pde.grids.base module

Bases classes

**exception DimensionError**

Bases: `ValueError`

exception indicating that dimensions were inconsistent

**exception DomainError**

Bases: `ValueError`

exception indicating that point lies outside domain

**class GridBase**

Bases: `object`

Base class for all grids defining common methods and interfaces

initialize the grid

**assert\_grid\_compatible** (*other*: `GridBase`)  $\rightarrow$  `None`

checks whether *other* is compatible with the current grid

**Parameters** *other* (`GridBase`) – The grid compared to this one

**Raises** `ValueError` – if grids are not compatible

**axes**: `List[str]`

**property axes\_bounds**: `Tuple[Tuple[float, float], ...]`

lower and upper bounds of each axis

**Type** `tuple`

**property axes\_coords**: `Tuple[numpy.ndarray, ...]`

coordinates of the cells for each axis

**Type** `tuple`

**axes\_symmetric**: `List[str] = []`

The names of the additional axes that the fields do not depend on, e.g. along which they are constant.

**Type** `list`

**cell\_coords**

coordinate values for all axes of each cell

**Type** `ndarray`

**cell\_to\_point** (*cells*: `numpy.ndarray`, *cartesian*: `bool = True`)  $\rightarrow$  `numpy.ndarray`

convert cell coordinates to real coordinates

**Parameters**

- **cells** (`ndarray`) – Indices of the cells whose center coordinates are requested. This can be float values to indicate positions relative to the cell center.
- **cartesian** (`bool`) – Determines whether the point is returned in Cartesian coordinates or grid coordinates.

**Returns** The center points of the respective cells

Return type `ndarray`

**Warning:** This method is deprecated since 2022-03-14 and will be removed soon.

**cell\_volume\_data:** `Sequence[Union[float, numpy.ndarray]]`

**cell\_volumes**

volume of each cell

Type `ndarray`

**compatible\_with** (*other*: `GridBase`)  $\rightarrow$  `bool`

tests whether this grid is compatible with other grids.

Grids are compatible when they cover the same area with the same discretization. The difference to equality is that compatible grids do not need to have the same periodicity in their boundaries.

**Parameters** *other* (`GridBase`) – The other grid to test against

**Returns** Whether the grid is compatible

Return type `bool`

**contains\_point** (*points*: `numpy.ndarray`, \*, *coords*: `str` = 'cartesian')  $\rightarrow$  `numpy.ndarray`

check whether the point is contained in the grid

**Parameters**

- **point** (`ndarray`) – Coordinates of the point
- **coords** (`str`) – The coordinate system in which the points are given

**Returns** A boolean array indicating which points lie within the grid

Return type `ndarray`

**coordinate\_arrays**

for each axes: coordinate values for all cells

Type `tuple`

**coordinate\_constraints:** `List[int] = []`

**copy** ()  $\rightarrow$  `GridBase`

return a copy of the grid

**difference\_vector\_real** (*p1*: `numpy.ndarray`, *p2*: `numpy.ndarray`)  $\rightarrow$  `numpy.ndarray`

return the vector pointing from p1 to p2

In case of periodic boundary conditions, the shortest vector is returned.

**Parameters**

- **p1** (`ndarray`) – First point(s)
- **p2** (`ndarray`) – Second point(s)

**Returns** The difference vectors between the points with periodic boundary conditions applied.

Return type `ndarray`

**dim:** `int`

**property discretization:** `numpy.ndarray`

the linear size of a cell along each axis

Type `numpy.array`

**distance\_real** (*p1*: `numpy.ndarray`, *p2*: `numpy.ndarray`) → `float`

Calculate the distance between two points given in real coordinates

This takes periodic boundary conditions into account if necessary.

**Parameters**

- **p1** (`ndarray`) – First position
- **p2** (`ndarray`) – Second position

**Returns** Distance between the two positions

**Return type** `float`

**classmethod from\_state** (*state*: `Union[str, Dict[str, Any]]`) → `GridBase`

create a field from a stored *state*.

**Parameters** **state** (*str* or *dict*) – The state from which the grid is reconstructed. If *state* is a string, it is decoded as JSON, which should yield a *dict*.

**get\_axis\_index** (*key*: `Union[int, str]`, *allow\_symmetric*: `bool = True`) → `int`

return the index belonging to an axis

**Parameters**

- **key** (*int* or *str*) – The index or name of an axis
- **allow\_symmetric** (*bool*) – Whether axes with assumed symmetry are included

**Returns** The index of the axis

**Return type** `int`

**abstract get\_boundary\_conditions** (*bc*: `BoundariesData = 'auto_periodic_neumann'`, *rank*: `int = 0`) → `Boundaries`

**abstract get\_image\_data** (*data*: `numpy.ndarray`) → `Dict[str, Any]`

**abstract get\_line\_data** (*data*: `numpy.ndarray`, *extract*: *str = 'auto'*) → `Dict[str, Any]`

**abstract get\_random\_point** (\*, *boundary\_distance*: `float = 0`, *coords*: *str = 'cartesian'*) → `numpy.ndarray`

**get\_subgrid** (*indices*: `Sequence[int]`) → `GridBase`

return a subgrid of only the specified axes

**integrate** (*data*: `NumberOrArray`, *axes*: `Optional[Union[int, Sequence[int]]] = None`) → `numpy.ndarray`

Integrates the discretized data over the grid

**Parameters**

- **data** (`ndarray`) – The values at the support points of the grid that need to be integrated.
- **axes** (*list of int, optional*) – The axes along which the integral is performed. If omitted, all axes are integrated over.

**Returns** The values integrated over the entire grid

**Return type** `ndarray`

**abstract iter\_mirror\_points** (*point*: `numpy.ndarray`, *with\_self*: `bool = False`, *only\_periodic*: `bool = True`) → `Generator`

**make\_cell\_volume\_compiled** (*flat\_index*: `bool = False`) → `Callable[[...], float]`

return a compiled function returning the volume of a grid cell

**Parameters** `flat_index` (*bool*) – When True, cell\_volumes are indexed by a single integer into the flattened array.

**Returns** returning the volume of the chosen cell

**Return type** function

**make\_inserter\_compiled** (\*, *full\_data: bool = False*) → Callable[[*numpy.ndarray*, *numpy.ndarray*, *NumberOrArray*], *None*]

return a compiled function to insert values at interpolated positions

**Parameters** `full_data` (*bool*) – Flag indicating that the interpolator should work on the full data array that includes values for the grid points. If this is the case, the boundaries are not checked and the coordinates are used as is.

**Returns** A function with signature (data, position, amount), where *data* is the numpy array containing the field data, *position* is denotes the position in grid coordinates, and *amount* is the that is to be added to the field.

**make\_integrator** () → Callable[[*numpy.ndarray*], *numpy.ndarray*]

Return function that can be used to integrates discretized data over the grid

Note that currently only scalar fields are supported.

**Returns** A function that takes a numpy array and returns the integral with the correct weights given by the cell volumes.

**Return type** callable

**make\_normalize\_point\_compiled** (*reflect: bool = True*) → Callable[[*numpy.ndarray*], *None*]

return a compiled function that normalizes a point

Here, the point is assumed to be specified by the physical values along the non-symmetric axes of the grid. Normalizing points is useful to make sure they lie within the domain of the grid. This function respects periodic boundary conditions and can also reflect points off the boundary.

**Parameters** `reflect` (*bool*) – Flag determining whether coordinates along non-periodic axes are reflected to lie in the valid range. If *False*, such coordinates are left unchanged and only periodic boundary conditions are enforced.

**Returns** A function that takes a *ndarray* as an argument, which describes the coordinates of the points. This array is modified in-place!

**Return type** callable

**make\_operator** (*operator: Union[str, OperatorInfo]*, *bc: BoundariesData*, *\*\*kwargs*) → Callable[*..., np.ndarray*]

return a compiled function applying an operator with boundary conditions

The returned function takes the discretized data on the grid as an input and returns the data to which the operator *operator* has been applied. The function only takes the valid grid points and allocates memory for the ghost points internally to apply the boundary conditions specified as *bc*. Note that the function supports an optional argument *out*, which if given should provide space for the valid output array without the ghost cells. The result of the operator is then written into this output array. The function also accepts an optional parameter *args*, which is forwarded to *set\_ghost\_cells*.

**Parameters**

- **operator** (*str*) – Identifier for the operator. Some examples are ‘laplace’, ‘gradient’, or ‘divergence’. The registered operators for this grid can be obtained from the *operators* attribute.

- **bc** (*str or list or tuple or dict*) – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by ‘periodic’). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value NUM (specified by `{‘value’: NUM}`) and Neumann conditions enforcing the value DERIV for the derivative in the normal direction (specified by `{‘derivative’: DERIV}`) are supported. Note that the special value ‘natural’ imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#).
- **\*\*kwargs** – Specifies extra arguments influencing how the operator is created.

**Returns** the function that applies the operator. This function has the signature (arr: np.ndarray, out: np.ndarray = None, args=None).

**Return type** callable

**make\_operator\_no\_bc** (*operator: Union[str, OperatorInfo], \*\*kwargs*) → Callable[[numpy.ndarray, numpy.ndarray], None]

return a compiled function applying an operator without boundary conditions

A function that takes the discretized full data as an input and an array of valid data points to which the result of applying the operator is written.

---

**Note:** The resulting function does not check whether the ghost cells of the input array have been supplied with sensible values. It is the responsibility of the user to set the values of the ghost cells beforehand. Use this function only if you absolutely know what you’re doing. In all other cases, `make_operator()` is probably the better choice.

---

### Parameters

- **operator** (*str*) – Identifier for the operator. Some examples are ‘laplace’, ‘gradient’, or ‘divergence’. The registered operators for this grid can be obtained from the `operators` attribute.
- **\*\*kwargs** – Specifies extra arguments influencing how the operator is created.

**Returns** the function that applies the operator. This function has the signature (arr: np.ndarray, out: np.ndarray), so they *out* array need to be supplied explicitly.

**Return type** callable

**normalize\_point** (*point: numpy.ndarray, \*, reflect: bool = False*) → numpy.ndarray

normalize coordinates by applying periodic boundary conditions

Here, the point is assumed to be specified by the physical values along the non-symmetric axes of the grid. Normalizing points is useful to make sure they lie within the domain of the grid. This function respects periodic boundary conditions and can also reflect points off the boundary.

### Parameters

- **point** (*ndarray*) – Coordinates of a single point
- **reflect** (*bool*) – Flag determining whether coordinates along non-periodic axes are reflected to lie in the valid range. If *False*, such coordinates are left unchanged and only periodic boundary conditions are enforced.

**Returns** The respective coordinates with periodic boundary conditions applied.

Return type `ndarray`

`num_axes`: `int`

property `numba_type`: `str`

represents type of the grid data in numba signatures

Type `str`

`operators`: `Set[str] = {}`

names of all operators defined for this grid

Type `set`

`periodic`: `List[bool]`

`plot()`

visualize the grid

`abstract point_from_cartesian` (*points*: `numpy.ndarray`) → `numpy.ndarray`

`abstract point_to_cartesian` (*points*: `numpy.ndarray`, \*, *full*: `bool = False`) → `numpy.ndarray`

`point_to_cell` (*points*: `numpy.ndarray`) → `numpy.ndarray`

Determine cell(s) corresponding to given point(s)

Parameters **points** (`ndarray`) – Real coordinates

Returns The indices of the respective cells

Return type `ndarray`

**Warning:** This method is deprecated since 2022-03-14 and will be removed soon.

`abstract polar_coordinates_real` (*origin*: `numpy.ndarray`, \*, *ret\_angle*: `bool = False`) →  
`Union[numpy.ndarray, Tuple[numpy.ndarray, ...]]`

`classmethod register_operator` (*name*: `str`, *factory\_func*: `Optional[Callable] = None`, *rank\_in*: `int = 0`, *rank\_out*: `int = 0`)

register an operator for this grid

---

### Example

The method can either be used directly:

```
GridClass.register_operator("operator", make_operator)
```

or as a decorator for the factory function:

```
@GridClass.register_operator("operator")
def make_operator(bcs: Boundaries):
    ...
```

---

### Parameters

- **name** (`str`) – The name of the operator to register
- **factory\_func** (`callable`) – A function with signature (`bcs: Boundaries, **kwargs`), which takes boundary conditions and optional keyword arguments and returns an implementation of the given operator. This implementation is a function that takes a

`ndarray` of discretized values as arguments and returns the resulting discretized data in a `ndarray` after applying the operator.

- **rank\_in** (*int*) – The rank of the input field for the operator
- **rank\_out** (*int*) – The rank of the field that is returned by the operator

**property shape:** `Tuple[int, ...]`  
the number of support points of each axis

**Type** `tuple` of `int`

**abstract property state:** `Dict[str, Any]`

**property state\_serialized:** `str`

JSON-serialized version of the state of this grid

**Type** `str`

**transform** (*coordinates: numpy.ndarray, source: str, target: str*) → `numpy.ndarray`  
converts coordinates from one coordinate system to another

Supported coordinate systems include

- *cartesian*: Cartesian coordinates where each point carries *dim* values
- *cell*: Grid coordinates based on indexing the discretization cells
- *grid*: Grid coordinates where each point carries *num\_axes* values

---

**Note:** Some conversion might involve projections if the coordinate system imposes symmetries. For instance, converting 3d Cartesian coordinates to grid coordinates in a spherically symmetric grid will only return the radius from the origin. Conversely, converting these grid coordinates back to 3d Cartesian coordinates will only return coordinates along a particular ray originating at the origin.

---

#### Parameters

- **coordinates** (`ndarray`) – The coordinates to convert
- **source** (`str`) – The source coordinate system
- **target** (`str`) – The target coordinate system

**Returns** The transformed coordinates

**Return type** `ndarray`

**property typical\_discretization:** `float`  
the average side length of the cells

**Type** `float`

**uniform\_cell\_volumes**

returns True if all cell volumes are the same

**Type** `bool`

**abstract property volume:** `float`

**class OperatorInfo** (*factory: Callable[..., OperatorType], rank\_in: int, rank\_out: int, name: str = ""*)

Bases: `tuple`

stores information about an operator

Create new instance of `OperatorInfo`(factory, rank\_in, rank\_out, name)

**property** `factory`

Alias for field number 0

**property** `name`

Alias for field number 3

**property** `rank_in`

Alias for field number 1

**property** `rank_out`

Alias for field number 2

**exception** `PeriodicityError`

Bases: `RuntimeError`

exception indicating that the grid periodicity is inconsistent

**discretize\_interval** (*x\_min*: `float`, *x\_max*: `float`, *num*: `int`) → `Tuple[numpy.ndarray, float]`

construct a list of equidistantly placed intervals

The discretization is defined as

$$x_i = x_{\min} + \left(i + \frac{1}{2}\right) \Delta x \quad \text{for } i = 0, \dots, N - 1$$
$$\Delta x = \frac{x_{\max} - x_{\min}}{N}$$

where  $N$  is the number of intervals given by *num*.

#### Parameters

- **x\_min** (`float`) – Minimal value of the axis
- **x\_max** (`float`) – Maximal value of the axis
- **num** (`int`) – Number of intervals

**Returns** (midpoints, dx): the midpoints of the intervals and the used discretization  $dx$ .

**Return type** `tuple`

**registered\_operators** () → `Dict[str, List[str]]`

returns all operators that are currently defined

**Returns** a dictionary with the names of the operators defined for each grid class

**Return type** `dict`

## 4.2.4 `pde.grids.cartesian` module

Cartesian grids of arbitrary dimension.

**class** `CartesianGrid` (*bounds*: `Sequence[Tuple[float, float]]`, *shape*: `Union[int, Sequence[int]]`, *periodic*: `Union[Sequence[bool], bool] = False`)

Bases: `pde.grids.cartesian.CartesianGridBase`

d-dimensional Cartesian grid with uniform discretization for each axis

The grids can be thought of as a collection of n-dimensional boxes, called cells, of equal length in each dimension. The bounds then defined the total volume covered by these cells, while the cell coordinates give the location of the box centers. We index the boxes starting from 0 along each dimension. Consequently, the cell  $i - \frac{1}{2}$  corresponds

to the left edge of the covered interval and the index  $i + \frac{1}{2}$  corresponds to the right edge, when the dimension is covered by  $d$  boxes.

In particular, the discretization along dimension  $k$  is defined as

$$x_i^{(k)} = x_{\min}^{(k)} + \left(i + \frac{1}{2}\right) \Delta x^{(k)} \quad \text{for } i = 0, \dots, N^{(k)} - 1$$

$$\Delta x^{(k)} = \frac{x_{\max}^{(k)} - x_{\min}^{(k)}}{N^{(k)}}$$

where  $N^{(k)}$  is the number of cells along this dimension. Consequently, the cells have dimension  $\Delta x^{(k)}$  and cover the interval  $[x_{\min}^{(k)}, x_{\max}^{(k)}]$ .

#### Parameters

- **bounds** (*list of tuple*) – Give the coordinate range for each axis. This should be a tuple of two number (lower and upper bound) for each axis. The length of *bounds* thus determines the grid dimension.
- **shape** (*list*) – The number of support points for each axis. The length of *shape* needs to match the grid dimension.
- **periodic** (*bool or list*) – Specifies which axes possess periodic boundary conditions. This is either a list of booleans defining periodicity for each individual axis or a single boolean value specifying the same periodicity for all axes.

**cuboid:** `pde.tools.cuboid.Cuboid`

**classmethod from\_state** (*state: Dict[str, Any]*) → *CartesianGrid*  
create a field from a stored *state*.

**Parameters** *state* (*dict*) – The state from which the grid is reconstructed.

**get\_subgrid** (*indices: Sequence[int]*) → *CartesianGrid*  
return a subgrid of only the specified axes

**Parameters** *indices* (*list*) – Indices indicating the axes that are retained in the subgrid

**Returns** The subgrid

**Return type** *CartesianGrid*

**property state:** `Dict[str, Any]`  
the state of the grid

**Type** *dict*

**property volume:** `float`  
total volume of the grid

**Type** *float*

**class CartesianGridBase** (*shape: Sequence[int], periodic: Union[Sequence[bool], bool] = False*)  
Bases: `pde.grids.base.GridBase`

Base class for *UnitGrid* and *CartesianGrid*

#### Parameters

- **shape** (*list*) – The number of support points for each axis. The dimension of the grid is given by *len(shape)*.
- **periodic** (*bool or list*) – Specifies which axes possess periodic boundary conditions. This is either a list of booleans defining periodicity for each individual axis or a single boolean value specifying the same periodicity for all axes.

**property cell\_volume\_data**  
size associated with each cell

**cuboid:** `pde.tools.cuboid.Cuboid`

**from\_polar\_coordinates** (*distance: numpy.ndarray, angle: numpy.ndarray, origin: numpy.ndarray = None*)  $\rightarrow$  `numpy.ndarray`

convert polar coordinates to Cartesian coordinates

This function is currently only implemented for 1d and 2d systems.

#### Parameters

- **distance** (`ndarray`) – The radial distance
- **angle** (`ndarray`) – The angle with respect to the origin
- **origin** (`ndarray`, optional) – Sets the origin of the coordinate system. If omitted, the zero point is assumed as the origin.

**Returns** The Cartesian coordinates corresponding to the given polar coordinates.

**Return type** `ndarray`

**get\_boundary\_conditions** (*bc: BoundariesData = 'auto\_periodic\_neumann', rank: int = 0*)  $\rightarrow$  `Boundaries`

constructs boundary conditions from a flexible data format

#### Parameters

- **bc** (*str or list or tuple or dict*) – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by 'periodic'). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value NUM (specified by {'value': NUM}) and Neumann conditions enforcing the value DERIV for the derivative in the normal direction (specified by {'derivative': DERIV}) are supported. Note that the special value 'natural' imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#).
- **rank** (`int`) – The tensorial rank of the value associated with the boundary conditions.

#### Raises

- **ValueError** – If the data given in *bc* cannot be read
- **PeriodicityError** – If the boundaries are not compatible with the periodic axes of the grid.

**get\_image\_data** (*data: numpy.ndarray*)  $\rightarrow$  `Dict[str, Any]`  
return a 2d-image of the data

**Parameters** **data** (`ndarray`) – The values at the grid points

**Returns** A dictionary with information about the image, which is convenient for plotting.

**get\_line\_data** (*data: numpy.ndarray, extract: str = 'auto'*)  $\rightarrow$  `Dict[str, Any]`  
return a line cut through the given data

#### Parameters

- **data** (`ndarray`) – The values at the grid points

- **extract** (*str*) – Determines which cut is done through the grid. Possible choices are (default is *cut\_0*):
  - *cut\_#*: return values along the axis specified by # and use the mid point along all other axes.
  - *project\_#*: average values for all axes, except axis #.

Here, # can either be a zero-based index (from 0 to dim-1) or a letter denoting the axis.

**Returns** A dictionary with information about the line cut, which is convenient for plotting.

**get\_random\_point** (\*, *boundary\_distance*: *float* = 0, *coords*: *str* = 'cartesian', *rng*: *Optional*[*numpy.random.\_generator.Generator*] = *None*, *cartesian*: *Optional*[*bool*] = *None*) → *numpy.ndarray*  
 return a random point within the grid

#### Parameters

- **boundary\_distance** (*float*) – The minimal distance this point needs to have from all boundaries.
- **coords** (*str*) – Determines the coordinate system in which the point is specified. Valid values are *cartesian*, *cell*, and *grid*; see *transform()*.
- **rng** (*Generator*) – Random number generator (default: *default\_rng()*)

**Returns** The coordinates of the point

**Return type** *ndarray*

**iter\_mirror\_points** (*point*: *numpy.ndarray*, *with\_self*: *bool* = *False*, *only\_periodic*: *bool* = *True*) → *Generator*  
 generates all mirror points corresponding to *point*

#### Parameters

- **point** (*ndarray*) – the point within the grid
- **with\_self** (*bool*) – whether to include the point itself
- **only\_periodic** (*bool*) – whether to only mirror along periodic axes

**Returns** A generator yielding the coordinates that correspond to mirrors

**plot** (\*args, *title*: *str* = *None*, *filename*: *str* = *None*, *action*: *str* = 'auto', *ax\_style*: *Optional*[*Dict*[*str*, *Any*]] = *None*, *fig\_style*: *Optional*[*Dict*[*str*, *Any*]] = *None*, *ax*=*None*, \*\*kwargs)  
 visualize the grid

#### Parameters

- **title** (*str*) – Title of the plot. If omitted, the title might be chosen automatically.
- **filename** (*str*, *optional*) – If given, the plot is written to the specified file.
- **action** (*str*) – Decides what to do with the final figure. If the argument is set to *show*, *matplotlib.pyplot.show()* will be called to show the plot. If the value is *none*, the figure will be created, but not necessarily shown. The value *close* closes the figure, after saving it to a file when *filename* is given. The default value *auto* implies that the plot is shown if it is not a nested plot call.
- **ax\_style** (*dict*) – Dictionary with properties that will be changed on the axis after the plot has been drawn by calling *matplotlib.pyplot.setp()*. A special item in this dictionary is *use\_offset*, which is flag that can be used to control whether offset are shown along the axes of the plot.

- **fig\_style** (*dict*) – Dictionary with properties that will be changed on the figure after the plot has been drawn by calling `matplotlib.pyplot.setp()`. For instance, using `fig_style={'dpi': 200}` increases the resolution of the figure.
- **ax** (`matplotlib.axes.Axes`) – Figure axes to be used for plotting. The special value “create” creates a new figure, while “reuse” attempts to reuse an existing figure, which is the default.
- **\*\*kwargs** – Extra arguments are passed on to the matplotlib plotting routines, e.g., to set the color of the lines

**point\_from\_cartesian** (*coords: numpy.ndarray*) → *numpy.ndarray*  
convert points given in Cartesian coordinates to this grid

**Parameters** **coords** (*ndarray*) – Points in Cartesian coordinates.

**Returns** Points given in the coordinates of the grid

**Return type** *ndarray*

**point\_to\_cartesian** (*points: numpy.ndarray, \*, full: bool = False*) → *numpy.ndarray*  
convert coordinates of a point to Cartesian coordinates

**Parameters** **points** (*ndarray*) – Points given in the coordinates of the grid

**Returns** The Cartesian coordinates of the point

**Return type** *ndarray*

**polar\_coordinates\_real** (*origin: numpy.ndarray, \*, ret\_angle: bool = False*) → *Union[numpy.ndarray, Tuple[numpy.ndarray, numpy.ndarray, numpy.ndarray]]*  
return polar coordinates associated with the grid

**Parameters**

- **origin** (*ndarray*) – Coordinates of the origin at which the polar coordinate system is anchored.
- **ret\_angle** (*bool*) – Determines whether angles are returned alongside the distance. If *False* only the distance to the origin is returned for each support point of the grid. If *True*, the distance and angles are returned. For a 1d system, the angle is defined as the sign of the difference between the point and the origin, so that angles can either be 1 or -1. For 2d systems and 3d systems, polar coordinates and spherical coordinates are used, respectively.

**class UnitGrid** (*shape: Sequence[int], periodic: Union[Sequence[bool], bool] = False*)  
Bases: *pde.grids.cartesian.CartesianGridBase*

d-dimensional Cartesian grid with unit discretization in all directions

The grids can be thought of as a collection of d-dimensional cells of unit length. The *shape* parameter determines how many boxes there are in each direction. The cells are enumerated starting with 0, so the last cell has index  $n - 1$  if there are  $n$  cells along a dimension. A given cell  $i$  extends from coordinates  $i$  to  $i + 1$ , so the midpoint is at  $i + \frac{1}{2}$ , which is the cell coordinate. Taken together, the cells covers the interval  $[0, n]$  along this dimension.

**Parameters**

- **shape** (*list*) – The number of support points for each axis. The dimension of the grid is given by `len(shape)`.
- **periodic** (*bool or list*) – Specifies which axes possess periodic boundary conditions. This is either a list of booleans defining periodicity for each individual axis or a single boolean value specifying the same periodicity for all axes.

**axes:** *List[str]*

**cuboid:** `pde.tools.cuboid.Cuboid`

**dim:** `int`

**classmethod from\_state** (*state*: `Dict[str, Any]`)  $\rightarrow$  `UnitGrid`  
create a field from a stored *state*.

**Parameters** *state* (`dict`) – The state from which the grid is reconstructed.

**get\_subgrid** (*indices*: `Sequence[int]`)  $\rightarrow$  `UnitGrid`  
return a subgrid of only the specified axes

**Parameters** *indices* (`list`) – Indices indicating the axes that are retained in the subgrid

**Returns** The subgrid

**Return type** `UnitGrid`

**num\_axes:** `int`

**periodic:** `List[bool]`

**property state:** `Dict[str, Any]`  
the state of the grid

**Type** `dict`

**to\_cartesian** ()  $\rightarrow$  `CartesianGrid`  
convert unit grid to `CartesianGrid`

**property volume:** `float`  
total volume of the grid

**Type** `float`

## 4.2.5 pde.grids.cylindrical module

Cylindrical grids with azimuthal symmetry

**class CylindricalSymGrid** (*radius*: `float`, *bounds\_z*: `Tuple[float, float]`, *shape*: `Tuple[int, int]`, *periodic\_z*: `bool` = `False`)

Bases: `pde.grids.base.GridBase`

3-dimensional cylindrical grid assuming polar symmetry

The polar symmetry implies that states only depend on the radial and axial coordinates  $r$  and  $z$ , respectively. These are discretized uniformly as

$$\begin{aligned} r_i &= \left(i + \frac{1}{2}\right) \Delta r & \text{for } i = 0, \dots, N_r - 1 & \quad \text{with } \Delta r = \frac{R}{N_r} \\ z_j &= z_{\min} + \left(j + \frac{1}{2}\right) \Delta z & \text{for } j = 0, \dots, N_z - 1 & \quad \text{with } \Delta z = \frac{z_{\max} - z_{\min}}{N_z} \end{aligned}$$

where  $R$  is the radius of the cylindrical grid,  $z_{\min}$  and  $z_{\max}$  denote the respective lower and upper bounds of the axial direction, so that  $z_{\max} - z_{\min}$  is the total height. The two axes are discretized by  $N_r$  and  $N_z$  support points, respectively.

**Warning:** The order of components in the vector and tensor fields defined on this grid is different than in ordinary math. While it is common to use  $(r, \phi, z)$ , we here use the order  $(r, z, \phi)$ . It might thus be best to access components by name instead of index, e.g., use `field['z']` instead of `field[1]`.

**Parameters**

- **radius** (*float*) – The radius of the cylinder
- **bounds\_z** (*tuple*) – The lower and upper bound of the z-axis
- **shape** (*tuple*) – The number of support points in r and z direction, respectively.
- **periodic\_z** (*bool*) – Determines whether the z-axis has periodic boundary conditions.

**axes:** `List[str] = ['r', 'z']`

**axes\_symmetric:** `List[str] = ['phi']`

The names of the additional axes that the fields do not depend on, e.g. along which they are constant.

Type `list`

**cell\_volume\_data:** `Sequence[FloatNumerical]`

the volumes of all cells

Type `ndarray`

**coordinate\_constraints:** `List[int] = [0, 1]`

**dim:** `int = 3`

**classmethod from\_state** (*state: Dict[str, Any]*) → *CylindricalSymGrid*

create a field from a stored *state*.

**Parameters state** (*dict*) – The state from which the grid is reconstructed.

**get\_boundary\_conditions** (*bc: BoundariesData = 'auto\_periodic\_neumann', rank: int = 0*) →

*Boundaries*

constructs boundary conditions from a flexible data format

**Parameters**

- **bc** (*str or list or tuple or dict*) – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by 'periodic'). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value *NUM* (specified by {'value': *NUM*}) and Neumann conditions enforcing the value *DERIV* for the derivative in the normal direction (specified by {'derivative': *DERIV*}) are supported. Note that the special value 'natural' imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#).
- **rank** (*int*) – The tensorial rank of the value associated with the boundary conditions.

**Raises**

- **ValueError** – If the data given in *bc* cannot be read
- **PeriodicityError** – If the boundaries are not compatible with the periodic axes of the grid.

**get\_cartesian\_grid** (*mode: str = 'valid'*) → *CartesianGrid*

return a Cartesian grid for this Cylindrical one

**Parameters mode** (*str*) – Determines how the grid is determined. Setting it to 'valid' only returns points that are fully resolved in the cylindrical grid, e.g., the cylinder is circumscribed. Conversely, 'full' returns all data, so the cylinder is inscribed.

**Returns** The requested grid

**Return type** `pde.grids.cartesian.CartesianGrid`

**get\_image\_data** (*data*: `numpy.ndarray`) → `Dict[str, Any]`  
 return a 2d-image of the data

**Parameters** *data* (`ndarray`) – The values at the grid points

**Returns** A dictionary with information about the image, which is convenient for plotting.

**get\_line\_data** (*data*: `numpy.ndarray`, *extract*: `str` = 'auto') → `Dict[str, Any]`  
 return a line cut for the cylindrical grid

**Parameters**

- **data** (`ndarray`) – The values at the grid points
- **extract** (`str`) – Determines which cut is done through the grid. Possible choices are (default is `cut_axial`):
  - `cut_z` or `cut_axial`: values along the axial coordinate for  $r = 0$ .
  - `project_z` or `project_axial`: average values for each axial position (radial average).
  - `project_r` or `project_radial`: average values for each radial position (axial average)

**Returns** A dictionary with information about the line cut, which is convenient for plotting.

**get\_random\_point** (\*, *boundary\_distance*: `float` = 0, *avoid\_center*: `bool` = False, *coords*: `str` = 'cartesian', *rng*: `Optional[numpy.random._generator.Generator]` = None, *cartesian*: `Optional[bool]` = None) → `numpy.ndarray`

return a random point within the grid

Note that these points will be uniformly distributed on the radial axis, which implies that they are not uniformly distributed in the volume.

**Parameters**

- **boundary\_distance** (`float`) – The minimal distance this point needs to have from all boundaries.
- **avoid\_center** (`bool`) – Determines whether the boundary distance should also be kept from the center, i.e., whether points close to the center are returned.
- **coords** (`str`) – Determines the coordinate system in which the point is specified. Valid values are `cartesian`, `cell`, and `grid`; see `transform()`.
- **rng** (`Generator`) – Random number generator (default: `default_rng()`)

**Returns** The coordinates of the point

**Return type** `ndarray`

**get\_subgrid** (*indices*: `Sequence[int]`) → `Union[CartesianGrid, PolarSymGrid]`  
 return a subgrid of only the specified axes

**Parameters** *indices* (`list`) – Indices indicating the axes that are retained in the subgrid

**Returns** `CartesianGrid` or `PolarSymGrid`: The subgrid

**iter\_mirror\_points** (*point*: `numpy.ndarray`, *with\_self*: `bool` = False, *only\_periodic*: `bool` = True) → `Generator`

generates all mirror points corresponding to *point*

**Parameters**

- **point** (`ndarray`) – the point within the grid

- **with\_self** (*bool*) – whether to include the point itself
- **only\_periodic** (*bool*) – whether to only mirror along periodic axes

**Returns** A generator yielding the coordinates that correspond to mirrors

**property length:** *float*

length of the cylinder

**Type** *float*

**num\_axes:** *int* = 2

**periodic:** *List[bool]*

**point\_from\_cartesian** (*points: numpy.ndarray*) → *numpy.ndarray*

convert points given in Cartesian coordinates to this grid

This function returns points restricted to the x-z plane, i.e., the y-coordinate will be zero.

**Parameters** **points** (*ndarray*) – Points given in Cartesian coordinates.

**Returns** Points given in the coordinates of the grid

**Return type** *ndarray*

**point\_to\_cartesian** (*points: numpy.ndarray*, \*, *full: bool = False*) → *numpy.ndarray*

convert coordinates of a point to Cartesian coordinates

**Parameters**

- **points** (*ndarray*) – The grid coordinates of the points
- **full** (*bool*) – Flag indicating whether angular coordinates are specified

**Returns** The Cartesian coordinates of the point

**Return type** *ndarray*

**polar\_coordinates\_real** (*origin: numpy.ndarray*, \*, *ret\_angle: bool = False*) → *Union[numpy.ndarray, Tuple[numpy.ndarray, numpy.ndarray]]*

return spherical coordinates associated with the grid

**Parameters**

- **origin** (*ndarray*) – Coordinates of the origin at which the polar coordinate system is anchored. Note that this must be of the form  $[0, 0, z\_val]$ , where only  $z\_val$  can be chosen freely.
- **ret\_angle** (*bool*) – Determines whether the azimuthal angle is returned alongside the distance. If *False* only the distance to the origin is returned for each support point of the grid. If *True*, the distance and angles are returned.

**property radius:** *float*

radius of the cylinder

**Type** *float*

**property state:** *Dict[str, Any]*

the state of the grid

**Type** *state*

**property volume:** *float*

total volume of the grid

**Type** *float*

## 4.2.6 `pde.grids.spherical` module

Spherically-symmetric grids in 2 and 3 dimensions. These are grids that only discretize the radial direction, assuming symmetry with respect to all angles. This choice implies that differential operators might not be applicable to all fields. For instance, the divergence of a vector field on a spherical grid can only be represented as a scalar field on the same grid if the  $\theta$ -component of the vector field vanishes.

**class** `PolarSymGrid` (*radius*: `Union[float, Tuple[float, float]]`, *shape*: `Union[Tuple[int], int]`)

Bases: `pde.grids.spherical.SphericalSymGridBase`

2-dimensional polar grid assuming angular symmetry

The angular symmetry implies that states only depend on the radial coordinate  $r$ , which is discretized uniformly as

$$r_i = R_{\text{inner}} + \left(i + \frac{1}{2}\right) \Delta r \quad \text{for } i = 0, \dots, N-1 \quad \text{with} \quad \Delta r = \frac{R_{\text{outer}} - R_{\text{inner}}}{N}$$

where  $R_{\text{outer}}$  is the outer radius of the grid and  $R_{\text{inner}}$  corresponds to a possible inner radius, which is zero by default. The radial direction is discretized by  $N$  support points.

### Parameters

- **radius** (*float* or *tuple of floats*) – radius  $R_{\text{outer}}$  in case a simple float is given. If a tuple is supplied it is interpreted as the inner and outer radius,  $(R_{\text{inner}}, R_{\text{outer}})$ .
- **shape** (*tuple* or *int*) – A single number setting the number  $N$  of support points along the radial coordinate

**axes**: `List[str]` = `['r']`

**axes\_symmetric**: `List[str]` = `['phi']`

The names of the additional axes that the fields do not depend on, e.g. along which they are constant.

### Type list

**cell\_volume\_data**: `Sequence[FloatNumerical]`

**coordinate\_constraints**: `List[int]` = `[0, 1]`

**dim**: `int` = 2

**point\_to\_cartesian** (*points*: `numpy.ndarray`, \*, *full*: `bool` = `False`)  $\rightarrow$  `numpy.ndarray`  
convert coordinates of a point to Cartesian coordinates

This function returns points along the y-coordinate, i.e. the x coordinates will be zero.

### Parameters

- **points** (`ndarray`) – The grid coordinates of the points
- **full** (`bool`) – Flag indicating whether angular coordinates are specified

**Returns** The Cartesian coordinates of the point

**Return type** `ndarray`

**class** `SphericalSymGrid` (*radius*: `Union[float, Tuple[float, float]]`, *shape*: `Union[Tuple[int], int]`)

Bases: `pde.grids.spherical.SphericalSymGridBase`

3-dimensional spherical grid assuming spherical symmetry

The symmetry implies that states only depend on the radial coordinate  $r$ , which is discretized as follows:

$$r_i = R_{\text{inner}} + \left(i + \frac{1}{2}\right) \Delta r \quad \text{for } i = 0, \dots, N-1 \quad \text{with} \quad \Delta r = \frac{R_{\text{outer}} - R_{\text{inner}}}{N}$$

where  $R_{\text{outer}}$  is the outer radius of the grid and  $R_{\text{inner}}$  corresponds to a possible inner radius, which is zero by default. The radial direction is discretized by  $N$  support points.

**Warning:** Not all results of differential operators on vectorial and tensorial fields can be expressed in terms of fields that only depend on the radial coordinate  $r$ . In particular, the gradient of a vector field can only be calculated if the azimuthal component of the vector field vanishes. Similarly, the divergence of a tensor field can only be taken in special situations.

### Parameters

- **radius** (*float or tuple of floats*) – radius  $R_{\text{outer}}$  in case a simple float is given. If a tuple is supplied it is interpreted as the inner and outer radius,  $(R_{\text{inner}}, R_{\text{outer}})$ .
- **shape** (*tuple or int*) – A single number setting the number  $N$  of support points along the radial coordinate

**axes:** `List[str] = ['r']`

**axes\_symmetric:** `List[str] = ['theta', 'phi']`

The names of the additional axes that the fields do not depend on, e.g. along which they are constant.

Type `list`

**cell\_volume\_data:** `Sequence[FloatNumerical]`

**coordinate\_constraints:** `List[int] = [0, 1, 2]`

**dim:** `int = 3`

**point\_to\_cartesian** (*points: numpy.ndarray, \*, full: bool = False*)  $\rightarrow$  `numpy.ndarray`  
convert coordinates of a point to Cartesian coordinates

This function returns points along the z-coordinate, i.e. the x and y coordinates will be zero.

### Parameters

- **points** (`ndarray`) – The grid coordinates of the points
- **full** (`bool`) – Flag indicating whether angular coordinates are specified

**Returns** The Cartesian coordinates of the point

**Return type** `ndarray`

**class SphericalSymGridBase** (*radius: Union[float, Tuple[float, float]], shape: Union[Tuple[int], int]*)

Bases: `pde.grids.base.GridBase`

Base class for d-dimensional spherical grids with angular symmetry

The angular symmetry implies that states only depend on the radial coordinate  $r$ , which is discretized uniformly as

$$r_i = R_{\text{inner}} + \left(i + \frac{1}{2}\right) \Delta r \quad \text{for } i = 0, \dots, N-1 \quad \text{with} \quad \Delta r = \frac{R_{\text{outer}} - R_{\text{inner}}}{N}$$

where  $R_{\text{outer}}$  is the outer radius of the grid and  $R_{\text{inner}}$  corresponds to a possible inner radius, which is zero by default. The radial direction is discretized by  $N$  support points.

### Parameters

- **radius** (*float or tuple of floats*) – radius  $R_{\text{outer}}$  in case a simple float is given. If a tuple is supplied it is interpreted as the inner and outer radius,  $(R_{\text{inner}}, R_{\text{outer}})$ .

- **shape** (*tuple or int*) – A single number setting the number  $N$  of support points along the radial coordinate

**axes:** `List[str]`

**cell\_volume\_data:** `Sequence[FloatNumerical]`  
the volumes of all cells

**Type** tuple of `ndarray`

**dim:** `int`

**classmethod from\_state** (*state: Dict[str, Any]*) → *SphericalSymGridBase*  
create a field from a stored *state*.

**Parameters** *state* (*dict*) – The state from which the grid is reconstructed.

**get\_boundary\_conditions** (*bc='auto\_periodic\_neumann', rank: int = 0*) → *Boundaries*  
constructs boundary conditions from a flexible data format.

If the inner boundary condition for a grid without a hole is not specified, this condition is automatically set to a vanishing derivative at  $r = 0$ .

#### Parameters

- **bc** (*str or list or tuple or dict*) – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by ‘periodic’). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value *NUM* (specified by `{‘value’: NUM}`) and Neumann conditions enforcing the value *DERIV* for the derivative in the normal direction (specified by `{‘derivative’: DERIV}`) are supported. Note that the special value ‘natural’ imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#).
- **rank** (*int*) – The tensorial rank of the value associated with the boundary conditions.

#### Raises

- **ValueError** – If the data given in *bc* cannot be read
- **PeriodicityError** – If the boundaries are not compatible with the periodic axes of the grid.

**get\_cartesian\_grid** (*mode: str = ‘valid’, num: int = None*) → *CartesianGrid*  
return a Cartesian grid for this spherical one

#### Parameters

- **mode** (*str*) – Determines how the grid is determined. Setting it to ‘valid’ (or ‘inscribed’) only returns points that are fully resolved in the spherical grid, e.g., the Cartesian grid is inscribed in the sphere. Conversely, ‘full’ (or ‘circumscribed’) returns all data, so the Cartesian grid is circumscribed.
- **num** (*int*) – Number of support points along each axis of the returned grid.

**Returns** The requested grid

**Return type** `pde.grids.cartesian.CartesianGrid`

**get\_image\_data** (*data: numpy.ndarray, performance\_goal: str = ‘speed’, fill\_value: float = 0, masked: bool = True*) → `Dict[str, Any]`  
return a 2d-image of the data

**Parameters**

- **data** (`ndarray`) – The values at the grid points
- **performance\_goal** (`str`) – Determines the method chosen for interpolation. Possible options are *speed* and *quality*.
- **fill\_value** (`float`) – The value assigned to invalid positions (those inside the hole or outside the region).
- **masked** (`bool`) – Whether a `numpy.ma.MaskedArray` is returned for the data instead of the normal `ndarray`.

**Returns** A dictionary with information about the image, which is convenient for plotting.

**get\_line\_data** (*data*: `numpy.ndarray`, *extract*: `str` = 'auto') → `Dict[str, Any]`

return a line cut along the radial axis

**Parameters**

- **data** (`ndarray`) – The values at the grid points
- **extract** (`str`) – Determines which cut is done through the grid. This parameter is mainly supplied for a consistent interface and has no effect for polar grids.

**Returns** A dictionary with information about the line cut, which is convenient for plotting.

**get\_random\_point** (\*, *boundary\_distance*: `float` = 0, *avoid\_center*: `bool` = False, *coords*: `str` = 'cartesian', *rng*: `Optional[numpy.random._generator.Generator]` = None, *cartesian*: `Optional[bool]` = None) → `numpy.ndarray`

return a random point within the grid

Note that these points will be uniformly distributed in the volume, implying they are not uniformly distributed on the radial axis.

**Parameters**

- **boundary\_distance** (`float`) – The minimal distance this point needs to have from all boundaries.
- **avoid\_center** (`bool`) – Determines whether the boundary distance should also be kept from the center, i.e., whether points close to the center are returned.
- **coords** (`str`) – Determines the coordinate system in which the point is specified. Valid values are *cartesian*, *cell*, and *grid*; see `transform()`.
- **rng** (`Generator`) – Random number generator (default: `default_rng()`)

**Returns** The coordinates of the point

**Return type** `ndarray`

**property has\_hole**: `bool`

returns whether the inner radius is larger than zero

**iter\_mirror\_points** (*point*: `numpy.ndarray`, *with\_self*: `bool` = False, *only\_periodic*: `bool` = True) → `Generator`

generates all mirror points corresponding to *point*

**Parameters**

- **point** (`ndarray`) – the point within the grid
- **with\_self** (`bool`) – whether to include the point itself
- **only\_periodic** (`bool`) – whether to only mirror along periodic axes

**Returns** A generator yielding the coordinates that correspond to mirrors

**num\_axes:** `int = 1`

**periodic:** `List[bool] = [False]`

**plot** (\*args, title: *str* = None, filename: *str* = None, action: *str* = 'auto', ax\_style: *Optional*[*Dict*[*str*, *Any*]] = None, fig\_style: *Optional*[*Dict*[*str*, *Any*]] = None, ax=None, \*\*kwargs)  
visualize the spherically symmetric grid in two dimensions

#### Parameters

- **title** (*str*) – Title of the plot. If omitted, the title might be chosen automatically.
- **filename** (*str*, *optional*) – If given, the plot is written to the specified file.
- **action** (*str*) – Decides what to do with the final figure. If the argument is set to *show*, `matplotlib.pyplot.show()` will be called to show the plot. If the value is *none*, the figure will be created, but not necessarily shown. The value *close* closes the figure, after saving it to a file when *filename* is given. The default value *auto* implies that the plot is shown if it is not a nested plot call.
- **ax\_style** (*dict*) – Dictionary with properties that will be changed on the axis after the plot has been drawn by calling `matplotlib.pyplot.setp()`. A special item in this dictionary is *use\_offset*, which is flag that can be used to control whether offset are shown along the axes of the plot.
- **fig\_style** (*dict*) – Dictionary with properties that will be changed on the figure after the plot has been drawn by calling `matplotlib.pyplot.setp()`. For instance, using `fig_style={'dpi': 200}` increases the resolution of the figure.
- **ax** (`matplotlib.axes.Axes`) – Figure axes to be used for plotting. The special value “create” creates a new figure, while “reuse” attempts to reuse an existing figure, which is the default.
- **\*\*kwargs** – Extra arguments are passed on the to the matplotlib plotting routines, e.g., to set the color of the lines

**point\_from\_cartesian** (*points: numpy.ndarray*) → *numpy.ndarray*  
convert points given in Cartesian coordinates to this grid

**Parameters** **points** (*ndarray*) – Points given in Cartesian coordinates.

**Returns** Points given in the coordinates of the grid

**Return type** *ndarray*

**polar\_coordinates\_real** (*origin=None*, \*, *ret\_angle: bool = False*, \*\*kwargs) → *Union*[*numpy.ndarray*, *Tuple*[*numpy.ndarray*, ...]]  
return spherical coordinates associated with the grid

#### Parameters

- **origin** – Place holder variable to comply with the interface
- **ret\_angle** (*bool*) – Determines whether angles are returned alongside the distance. If *False* only the distance to the origin is returned for each support point of the grid. If *True*, the distance and angles are returned. Note that in the case of spherical grids, this angle is zero by convention.

**property radius:** *Union*[*float*, *Tuple*[*float*, *float*]]  
radius of the sphere

**Type** *float*

**property state:** Dict[str, Any]  
the state of the grid

Type state

**property volume:** float  
total volume of the grid

Type float

**volume\_from\_radius** (radius: TNumArr, dim: int) → TNumArr  
Return the volume of a sphere with a given radius

**Parameters**

- **radius** (float or ndarray) – Radius of the sphere
- **dim** (int) – Dimension of the space

**Returns** Volume of the sphere

**Return type** float or ndarray

## 4.3 pde.pdes package

Package that defines PDEs describing physical systems.

The examples in this package are often simple version of classical PDEs to demonstrate various aspects of the *py-pde* package. Clearly, not all extensions to these PDEs can be covered here, but this should serve as a starting point for custom investigations.

Publicly available methods should take fields with grid information and also only return such methods. There might be corresponding private methods that deal with raw data for faster simulations.

<i>PDE</i>	PDE defined by mathematical expressions
<i>AllenCahnPDE</i>	A simple Allen-Cahn equation
<i>CahnHilliardPDE</i>	A simple Cahn-Hilliard equation
<i>DiffusionPDE</i>	A simple diffusion equation
<i>KPZInterfacePDE</i>	The Kardar-Parisi-Zhang (KPZ) equation
<i>KuramotoSivashinskyPDE</i>	The Kuramoto-Sivashinsky equation
<i>SwiftHohenbergPDE</i>	The Swift-Hohenberg equation
<i>WavePDE</i>	A simple wave equation

Additionally, we offer two solvers for typical elliptical PDEs:

<i>solve_laplace_equation</i>	Solve Laplace's equation on a given grid.
<i>solve_poisson_equation</i>	Solve Laplace's equation on a given grid

### 4.3.1 `pde.pdes.allen_cahn` module

A Allen-Cahn equation

```
class AllenCahnPDE (interface_width: float = 1, bc: Union[Dict[str, Union[Dict, str, BCBase]], Dict, str,
                  BCBase, Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]],
                  Sequence[Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase, Tuple[Union[Dict,
                  str, BCBase], Union[Dict, str, BCBase]]]]] = 'auto_periodic_neumann')
```

Bases: `pde.pdes.base.PDEBase`

A simple Allen-Cahn equation

The mathematical definition is

$$\partial_t c = \gamma \nabla^2 c - c^3 + c$$

where  $c$  is a scalar field and  $\gamma$  sets the interfacial width.

#### Parameters

- **interface\_width** (*float*) – The diffusivity of the described species
- **bc** – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by 'periodic'). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value NUM (specified by {'value': NUM}) and Neumann conditions enforcing the value DERIV for the derivative in the normal direction (specified by {'derivative': DERIV}) are supported. Note that the special value 'natural' imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#).

**evolution\_rate** (*state*: `ScalarField`, *t*: *float* = 0) → `ScalarField`  
 evaluate the right hand side of the PDE

#### Parameters

- **state** (`ScalarField`) – The scalar field describing the concentration distribution
- **t** (*float*) – The current time point

**Returns** Scalar field describing the evolution rate of the PDE

**Return type** `ScalarField`

**explicit\_time\_dependence**: `Optional[bool]` = `False`

Flag indicating whether the right hand side of the PDE has an explicit time dependence.

**Type** `bool`

**property expression**: `str`

the expression of the right hand side of this PDE

**Type** `str`

**interface\_width**: `float`

### 4.3.2 `pde.pdes.base` module

Base classes

```
class PDEBase (noise: Union[int, float, complex, numpy.ndarray, Sequence[NumberOrArray],  
                Sequence[Sequence[Any]]] = 0, rng: Optional[numpy.random._generator.Generator] = None)
```

Bases: `object`

base class for solving partial differential equations

Custom PDEs can be implemented by specifying their evolution rate. In the simple case of deterministic PDEs, the methods `PDEBase.evolution_rate()` and `PDEBase._make_pde_rhs_numba()` need to be overwritten for the *numpy* and *numba* backend, respectively.

#### Parameters

- **noise** (float or `ndarray`) – Magnitude of the additive Gaussian white noise that is supported for all PDEs by default. If set to zero, a deterministic partial differential equation will be solved. Different noise magnitudes can be supplied for each field in coupled PDEs.
- **rng** (`Generator`) – Random number generator (default: `default_rng()`). Note that this random number generator is only used for *numpy* function, while compiled *numba* code is unaffected.

---

**Note:** If more complicated noise structures are required, the methods `PDEBase.noise_realization()` and `PDEBase._make_noise_realization_numba()` need to be overwritten for the *numpy* and *numba* backend, respectively.

---

**cache\_rhs:** `bool` = `False`

Flag indicating whether the right hand side of the equation should be cached. If `True`, the same implementation is used in subsequent calls to `solve`. Note that this might lead to wrong results if the parameters of the PDE were changed after the first call. This option is thus disabled by default and should be used with care.

Type `bool`

**check\_implementation:** `bool` = `True`

Flag determining whether (some) *numba*-compiled functions should be checked against their *numpy* counterparts. This can help with implementing a correct compiled version for a PDE class.

Type `bool`

**check\_rhs\_consistency** (state: `FieldBase`, t: `float` = 0, \*, tol: `float` = 1e-07, rhs\_numba: `Optional[Callable]` = None)

check the *numba* compiled right hand side versus the *numpy* variant

#### Parameters

- **state** (`FieldBase`) – The state for which the evolution rates should be compared
- **t** (`float`) – The associated time point
- **tol** (`float`) – Acceptance tolerance. The check passes if the evolution rates differ by less than this value
- **rhs\_numba** (`callable`) – The implementation of the *numba* variant that is to be checked. If omitted, an implementation is obtained by calling `PDEBase._make_pde_rhs_numba_cached()`.

**complex\_valued:** `bool` = `False`

Flag indicating whether the right hand side is a complex-valued PDE, which requires all involved variables to be of complex type

Type `bool`

**abstract evolution\_rate** (*state*: `FieldBase`, *t*: `float = 0`) → `FieldBase`

**explicit\_time\_dependence**: `Optional[bool] = None`

Flag indicating whether the right hand side of the PDE has an explicit time dependence.

Type `bool`

**property is\_sde**: `bool`

flag indicating whether this is a stochastic differential equation

The `BasePDF` class supports additive Gaussian white noise, whose magnitude is controlled by the `noise` property. In this case, `is_sde` is `True` if `self.noise != 0`.

**make\_modify\_after\_step** (*state*: `FieldBase`) → `Callable[[numpy.ndarray], float]`

returns a function that can be called to modify a state

This function is applied to the state after each integration step when an explicit stepper is used. The default behavior is to not change the state.

**Parameters** *state* (`FieldBase`) – An example for the state from which the grid and other information can be extracted

**Returns** Function that can be applied to a state to modify it and which returns a measure for the corrections applied to the state

**make\_pde\_rhs** (*state*: `FieldBase`, *backend*: `str = 'auto'`) → `Callable[[numpy.ndarray, float], numpy.ndarray]`

return a function for evaluating the right hand side of the PDE

**Parameters**

- **state** (`FieldBase`) – An example for the state from which the grid and other information can be extracted.
- **backend** (`str`) – Determines how the function is created. Accepted values are ‘numpy’ and ‘numba’. Alternatively, ‘auto’ lets the code decide for the most optimal backend.

**Returns** Function determining the right hand side of the PDE

**make\_sde\_rhs** (*state*: `FieldBase`, *backend*: `str = 'auto'`) → `Callable[[numpy.ndarray, float], Tuple[numpy.ndarray, numpy.ndarray]]`

return a function for evaluating the right hand side of the SDE

**Parameters**

- **state** (`FieldBase`) – An example for the state from which the grid and other information can be extracted
- **backend** (`str`) – Determines how the function is created. Accepted values are ‘python’ and ‘numba’. Alternatively, ‘auto’ lets the code decide for the most optimal backend.

**Returns** Function determining the deterministic part of the right hand side of the PDE together with a noise realization.

**noise\_realization** (*state*: `FieldBase`, *t*: `float = 0`, *label*: `str = 'Noise realization'`) → `FieldBase`

returns a realization for the noise

**Parameters**

- **state** (`ScalarField`) – The scalar field describing the concentration distribution
- **t** (`float`) – The current time point
- **label** (`str`) – The label for the returned field

**Returns** Scalar field describing the evolution rate of the PDE

**Return type** `ScalarField`

**solve** (*state*: `FieldBase`, *t\_range*: `TRangeType`, *dt*: `float` = `None`, *tracker*: `Optional[Union[Sequence[Union[TrackerBase, str]], TrackerBase, str]]` = `'auto'`, *method*: `Union[str, SolverBase]` = `'auto'`, *ret\_info*: `bool` = `False`, *\*\*kwargs*)  $\rightarrow$  `Union[FieldBase, Tuple[FieldBase, Dict[str, Any]]]`

convenience method for solving the partial differential equation

The method constructs a suitable solver (`SolverBase`) and controller (`Controller`) to advance the state over the temporal range specified by *t\_range*. To obtain full flexibility, it is advisable to construct these classes explicitly.

#### Parameters

- **state** (`FieldBase`) – The initial state (which also defines the spatial grid)
- **t\_range** (`float` or `tuple`) – Sets the time range for which the PDE is solved. This should typically be a tuple of two numbers, (*t\_start*, *t\_end*), specifying the initial and final time of the simulation. If only a single value is given, it is interpreted as *t\_end* and the time range is assumed to be (*0*, *t\_end*).
- **dt** (`float`) – Time step of the chosen stepping scheme. If `None`, a default value based on the stepper will be chosen. In particular, if *method* == `'auto'`, the `ScipySolver` with an automatic, adaptive time step is used. This is a flexible choice, but might be slower than using a fixed time step, where the explicit solver `ExplicitSolver` is when *method* == `'auto'`.
- **tracker** – Defines a tracker that process the state of the simulation at specified time intervals. A tracker is either an instance of `TrackerBase` or a string, which identifies a tracker. All possible identifiers can be obtained by calling `get_named_trackers()`. Multiple trackers can be specified as a list. The default value `auto` checks the state for consistency (tracker `'consistency'`) and displays a progress bar (tracker `'progress'`) when `tqdm` is installed. More general trackers are defined in `trackers`, where all options are explained in detail. In particular, the interval at which the tracker is evaluated can be chosen when creating a tracker object explicitly.
- **method** (`SolverBase` or `str`) – Specifies a method for solving the differential equation. This can either be an instance of `SolverBase` or a descriptive name like `'explicit'` or `'scipy'`. The valid names are given by `pde.solvers.base.SolverBase.registered_solvers()`. The default value `'auto'` selects `ScipySolver` if *dt* is not specified and otherwise `ExplicitSolver`.
- **ret\_info** (`bool`) – Flag determining whether diagnostic information about the solver process should be returned.
- **\*\*kwargs** – Additional keyword arguments are forwarded to the solver class chosen with the *method* argument. In particular, several *schemes* can be selected for the `ExplicitSolver` and the additional arguments of `scipy.integrate.solve_ivp()` are accepted for `ScipySolver`.

**Returns** The state at the final time point. In the case *ret\_info* == `True`, a tuple with the final state and a dictionary with additional information is returned.

**Return type** `FieldBase`

**expr\_prod** (*factor*: `float`, *expression*: `str`)  $\rightarrow$  `str`

helper function for building an expression with an (optional) pre-factor

#### Parameters

- **factor** (*float*) – The value of the prefactor
- **expression** (*str*) – The remaining expression

**Returns** The expression with the factor appended if necessary

**Return type** *str*

### 4.3.3 pde.pdes.cahn\_hilliard module

A Cahn-Hilliard equation

```
class CahnHilliardPDE (interface_width: float = 1, bc_c: Union[Dict[str, Union[Dict, str, BCBase]], Dict, str,
                    BCBase, Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]],
                    Sequence[Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase],
                    Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]]]] =
                    'auto_periodic_neumann', bc_mu: Union[Dict[str, Union[Dict, str, BCBase]], Dict, str,
                    BCBase, Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]],
                    Sequence[Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase],
                    Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]]]] =
                    'auto_periodic_neumann')
```

Bases: *pde.pdes.base.PDEBase*

A simple Cahn-Hilliard equation

The mathematical definition is

$$\partial_t c = \nabla^2 (c^3 - c - \gamma \nabla^2 c)$$

where  $c$  is a scalar field taking values on the interval  $[-1, 1]$  and  $\gamma$  sets the interfacial width.

#### Parameters

- **interface\_width** (*float*) – The width of the interface between the separated phases. This defines a characteristic length in the simulation. The grid needs to resolve this length of a stable simulation.
- **bc\_c** – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by 'periodic'). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value NUM (specified by `{'value': NUM}`) and Neumann conditions enforcing the value DERIV for the derivative in the normal direction (specified by `{'derivative': DERIV}`) are supported. Note that the special value 'natural' imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#).
- **bc\_mu** – The boundary conditions applied to the chemical potential associated with the scalar field  $c$ . Supports the same options as `bc_c`.

**evolution\_rate** (*state*: *ScalarField*, *t*: *float* = 0) → *ScalarField*  
 evaluate the right hand side of the PDE

#### Parameters

- **state** (*ScalarField*) – The scalar field describing the concentration distribution
- **t** (*float*) – The current time point

**Returns** Scalar field describing the evolution rate of the PDE

**Return type** `ScalarField`

**explicit\_time\_dependence:** `Optional[bool] = False`

Flag indicating whether the right hand side of the PDE has an explicit time dependence.

**Type** `bool`

**property expression:** `str`

the expression of the right hand side of this PDE

**Type** `str`

### 4.3.4 `pde.pdes.diffusion` module

A simple diffusion equation

```
class DiffusionPDE (diffusivity: float = 1, noise: float = 0, bc: Union[Dict[str, Union[Dict, str, BCBase]], Dict,
                        str, BCBase, Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]],
                        Sequence[Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase, Tuple[Union[Dict,
                        str, BCBase], Union[Dict, str, BCBase]]]]] = 'auto_periodic_neumann')
```

Bases: `pde.pdes.base.PDEBase`

A simple diffusion equation

The mathematical definition is

$$\partial_t c = D \nabla^2 c$$

where  $c$  is a scalar field that is distributed with diffusivity  $D$ .

#### Parameters

- **diffusivity** (`float`) – The diffusivity of the described species
- **noise** (`float`) – Strength of the (additive) noise term
- **bc** – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by 'periodic'). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value `NUM` (specified by `{'value': NUM}`) and Neumann conditions enforcing the value `DERIV` for the derivative in the normal direction (specified by `{'derivative': DERIV}`) are supported. Note that the special value 'natural' imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#).

**evolution\_rate** (`state: ScalarField, t: float = 0`) → `ScalarField`

evaluate the right hand side of the PDE

#### Parameters

- **state** (`ScalarField`) – The scalar field describing the concentration distribution
- **t** (`float`) – The current time point

**Returns** `Scalar field describing the evolution rate of the PDE`

**Return type** `ScalarField`

**explicit\_time\_dependence:** `Optional[bool] = False`

Flag indicating whether the right hand side of the PDE has an explicit time dependence.

**Type** `bool`

**property expression:** `str`  
the expression of the right hand side of this PDE

**Type** `str`

### 4.3.5 `pde.pdes.kpz_interface` module

The Kardar–Parisi–Zhang (KPZ) equation describing the evolution of an interface

```
class KPZInterfacePDE (nu: float = 0.5, lmbda: float = 1, noise: float = 0, bc: Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase, Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]], Sequence[Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase, Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]]]]] = 'auto_periodic_neumann')
```

Bases: `pde.pdes.base.PDEBase`

The Kardar–Parisi–Zhang (KPZ) equation

The mathematical definition is

$$\partial_t h = \nu \nabla^2 h + \frac{\lambda}{2} (\nabla h)^2 + \eta(\mathbf{r}, t)$$

where  $h$  is the height of the interface in Monge parameterization. The dynamics are governed by the two parameters  $\nu$  and  $\lambda$ , while  $\eta$  is Gaussian white noise, whose strength is controlled by the *noise* argument.

#### Parameters

- **nu** (*float*) – Parameter  $\nu$  for the strength of the diffusive term
- **lmbda** (*float*) – Parameter  $\lambda$  for the strenth of the gradient term
- **noise** (*float*) – Strength of the (additive) noise term
- **bc** – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by 'periodic'). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value NUM (specified by {'value': NUM}) and Neumann conditions enforcing the value DERIV for the derivative in the normal direction (specified by {'derivative': DERIV}) are supported. Note that the special value 'natural' imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#).

**evolution\_rate** (*state*: `ScalarField`, *t*: *float* = 0) → `ScalarField`  
evaluate the right hand side of the PDE

#### Parameters

- **state** (`ScalarField`) – The scalar field describing the concentration distribution
- **t** (*float*) – The current time point

**Returns** `ScalarField` describing the evolution rate of the PDE

**Return type** `ScalarField`

**explicit\_time\_dependence:** `Optional[bool]` = `False`

Flag indicating whether the right hand side of the PDE has an explicit time dependence.

**Type** `bool`

**property expression:** `str`  
 the expression of the right hand side of this PDE

**Type** `str`

### 4.3.6 `pde.pdes.kuramoto_sivashinsky` module

The Kardar–Parisi–Zhang (KPZ) equation describing the evolution of an interface

```
class KuramotoSivashinskyPDE (nu: float = 1, noise: float = 0, bc: Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase, Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]], Sequence[Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase, Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]]]]]
    = 'auto_periodic_neumann', bc_lap: Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase, Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]], Sequence[Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase, Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]]]]]
    = None)
```

Bases: `pde.pdes.base.PDEBase`

The Kuramoto-Sivashinsky equation

The mathematical definition is

$$\partial_t u = -\nu \nabla^4 u - \nabla^2 u - \frac{1}{2} (\nabla h)^2 + \eta(\mathbf{r}, t)$$

where  $u$  is the height of the interface in Monge parameterization. The dynamics are governed by the parameters  $\nu$ , while  $\eta$  is Gaussian white noise, whose strength is controlled by the `noise` argument.

#### Parameters

- **nu** (`float`) – Parameter  $\nu$  for the strength of the fourth-order term
- **noise** (`float`) – Strength of the (additive) noise term
- **bc** – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by ‘periodic’). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value NUM (specified by `{‘value’: NUM}`) and Neumann conditions enforcing the value DERIV for the derivative in the normal direction (specified by `{‘derivative’: DERIV}`) are supported. Note that the special value ‘natural’ imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#).
- **bc\_lap** – The boundary conditions applied to the second derivative of the scalar field  $c$ . If `None`, the same boundary condition as `bc` is chosen. Otherwise, this supports the same options as `bc`.

**evolution\_rate** (`state: ScalarField, t: float = 0`) → `ScalarField`  
 evaluate the right hand side of the PDE

#### Parameters

- **state** (`ScalarField`) – The scalar field describing the concentration distribution
- **t** (`float`) – The current time point

**Returns** Scalar field describing the evolution rate of the PDE

**Return type** `ScalarField`

**explicit\_time\_dependence:** `Optional[bool] = False`

Flag indicating whether the right hand side of the PDE has an explicit time dependence.

Type `bool`

**property\_expression:** `str`

the expression of the right hand side of this PDE

Type `str`

### 4.3.7 `pde.pdes.laplace` module

Solvers for Poisson's and Laplace's equation

**solve\_laplace\_equation** (*grid*: `GridBase`, *bc*: `Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase, Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]], Sequence[Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase], Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]]]`], *label*: `str = "Solution to Laplace's equation"`)  $\rightarrow$  `ScalarField`

Solve Laplace's equation on a given grid.

This is implemented by calling `solve_poisson_equation()` with a vanishing right hand side.

#### Parameters

- **grid** (`GridBase`) – The grid on which the equation is solved
- **bc** – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by 'periodic'). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value `NUM` (specified by `{'value': NUM}`) and Neumann conditions enforcing the value `DERIV` for the derivative in the normal direction (specified by `{'derivative': DERIV}`) are supported. Note that the special value 'natural' imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#).
- **label** (`str`) – The label of the returned field.

**Returns** The field that solves the equation. This field will be defined on the given *grid*.

**Return type** `ScalarField`

**solve\_poisson\_equation** (*rhs*: `ScalarField`, *bc*: `Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase, Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]], Sequence[Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase], Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]]]`], *label*: `str = "Solution to Poisson's equation"`, *\*\*kwargs*)  $\rightarrow$  `ScalarField`

Solve Laplace's equation on a given grid

Denoting the current field by  $u$ , we thus solve for  $f$ , defined by the equation

$$\nabla^2 u(\mathbf{r}) = -f(\mathbf{r})$$

with boundary conditions specified by *bc*.

**Note:** In case of periodic or Neumann boundary conditions, the right hand side  $f(\mathbf{r})$  needs to satisfy the following condition

$$\int f \, dV = \oint g \, dS ,$$

where  $g$  denotes the function specifying the outwards derivative for Neumann conditions. Note that for periodic boundaries  $g$  vanishes, so that this condition implies that the integral over  $f$  must vanish for neutral Neumann or periodic conditions.

### Parameters

- **rhs** (*ScalarField*) – The scalar field  $f$  describing the right hand side
- **bc** – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by ‘periodic’). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value `NUM` (specified by `{‘value’: NUM}`) and Neumann conditions enforcing the value `DERIV` for the derivative in the normal direction (specified by `{‘derivative’: DERIV}`) are supported. Note that the special value ‘natural’ imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#).
- **label** (*str*) – The label of the returned field.

**Returns** The field  $u$  that solves the equation. This field will be defined on the same grid as *rhs*.

**Return type** *ScalarField*

## 4.3.8 pde.pdes.pde module

Defines a PDE class whose right hand side is given as a string

```
class PDE (rhs: Dict[str, str], noise: Union[int, float, complex, numpy.ndarray, Sequence[NumberOrArray],
Sequence[Sequence[Any]]] = 0, bc: Union[Dict[str, Union[Dict[str, BCBase]], Dict[str, BCBase],
Tuple[Union[Dict[str, BCBase], Union[Dict[str, BCBase]], Sequence[Union[Dict[str, Union[Dict[str,
BCBase]], Dict[str, BCBase, Tuple[Union[Dict[str, BCBase], Union[Dict[str, BCBase]]]]]]] =
‘auto_periodic_neumann’, bc_ops: Optional[Dict[str, Union[Dict[str, Union[Dict[str, BCBase]], Dict[str,
BCBase, Tuple[Union[Dict[str, BCBase], Union[Dict[str, BCBase]], Sequence[Union[Dict[str,
Union[Dict[str, BCBase]], Dict[str, BCBase, Tuple[Union[Dict[str, BCBase], Union[Dict[str,
BCBase]]]]]]]]] = None, user_funcs: Optional[Dict[str, Any]] = None, consts: Optional[Dict[str, Any]] =
None)
```

Bases: *pde.pdes.base.PDEBase*

PDE defined by mathematical expressions

### variables

The name of the variables (i.e., fields) in the order they are expected to appear in the *state*.

**Type** *tuple*

### diagnostics

Additional diagnostic information that might help with analyzing problems, e.g., when `sympy` cannot parse or `mod`numba`` cannot compile a function.

**Type** *dict*

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur.

### Parameters

- **rhs** (*dict*) – The expressions defining the evolution rate. The dictionary keys define the name of the fields whose evolution is considered, while the values specify their evolution rate as a string that can be parsed by `sympy`. These expression may contain variables (i.e., the fields themselves, spatial coordinates of the grid, and *t* for the time), standard local mathematical operators defined by `sympy`, and the operators defined in the `pde` package. Note that operators need to be specified with their full name, i.e., `laplace` for a scalar Laplacian and `vector_laplace` for a Laplacian operating on a vector field. Moreover, the dot product between two vector fields can be denoted by using `dot(field1, field2)` in the expression, an outer product is calculated using `outer(field1, field2)`, and `integral(field)` denotes an integral over a field.
- **noise** (float or `ndarray`) – Magnitude of additive Gaussian white noise. The default value of zero implies deterministic partial differential equations will be solved. Different noise magnitudes can be supplied for each field in coupled PDEs by either specifying a sequence of numbers or a dictionary with values for each field.
- **bc** – Boundary conditions for the operators used in the expression. The conditions here are applied to all operators that do not have a specialized condition given in `bc_ops`. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by ‘periodic’). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value NUM (specified by `{‘value’: NUM}`) and Neumann conditions enforcing the value DERIV for the derivative in the normal direction (specified by `{‘derivative’: DERIV}`) are supported. Note that the special value ‘natural’ imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#).
- **bc\_ops** (*dict*) – Special boundary conditions for some operators. The keys in this dictionary specify where the boundary condition will be applied. The keys follow the format “VARIABLE:OPERATOR”, where VARIABLE specifies the expression in *rhs* where the boundary condition is applied to the operator specified by OPERATOR. For both identifiers, the wildcard symbol “\*” denotes that all fields and operators are affected, respectively. For instance, the identifier “c:\*” allows specifying a condition for all operators of the field named *c*.
- **user\_funcs** (*dict*, *optional*) – A dictionary with user defined functions that can be used in the expressions in *rhs*.
- **consts** (*dict*, *optional*) – A dictionary with user defined constants that can be used in the expression. These can be either scalar numbers or fields defined on the same grid as the actual simulation.

---

**Note:** The order in which the fields are given in *rhs* defines the order in which they need to appear in the *state* variable when the evolution rate is calculated. Note that *dict* keep the insertion order since Python version 3.7, so a normal dictionary can be used to define the equations.

---

**evolution\_rate** (*state*: `FieldBase`, *t*: `float` = 0.0) → `FieldBase`

evaluate the right hand side of the PDE

#### Parameters

- **state** (`FieldBase`) – The field describing the state of the PDE
- **t** (`float`) – The current time point

**Returns** Field describing the evolution rate of the PDE

**Return type** `FieldBase`

**property expressions:** `Dict[str, str]`  
 show the expressions of the PDE

### 4.3.9 `pde.pdes.swift_hohenberg` module

The Swift-Hohenberg equation

```
class SwiftHohenbergPDE (rate: float = 0.1, kc2: float = 1.0, delta: float = 1.0, bc: Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase, Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]], Sequence[Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase, Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]]]]] = 'auto_periodic_neumann', bc_lap: Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase, Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]], Sequence[Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase, Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]]]]] = None)
```

Bases: `pde.pdes.base.PDEBase`

The Swift-Hohenberg equation

The mathematical definition is

$$\partial_t c = \left[ \epsilon - (k_c^2 + \nabla^2)^2 \right] c + \delta c^2 - c^3$$

where  $c$  is a scalar field and  $\epsilon$ ,  $k_c^2$ , and  $\delta$  are parameters of the equation.

#### Parameters

- **rate** (*float*) – The bifurcation parameter  $\epsilon$
- **kc2** (*float*) – Squared wave vector  $k_c^2$  of the linear instability
- **delta** (*float*) – Parameter  $\delta$  of the non-linearity
- **bc** – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by ‘periodic’). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value NUM (specified by `{‘value’: NUM}`) and Neumann conditions enforcing the value DERIV for the derivative in the normal direction (specified by `{‘derivative’: DERIV}`) are supported. Note that the special value ‘natural’ imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#).
- **bc\_lap** – The boundary conditions applied to the second derivative of the scalar field  $c$ . If *None*, the same boundary condition as *bc* is chosen. Otherwise, this supports the same options as *bc*.

**evolution\_rate** (*state: ScalarField, t: float = 0*)  $\rightarrow$  *ScalarField*  
 evaluate the right hand side of the PDE

#### Parameters

- **state** (*ScalarField*) – The scalar field describing the concentration distribution
- **t** (*float*) – The current time point

**Returns** Scalar field describing the evolution rate of the PDE

**Return type** *ScalarField*

**explicit\_time\_dependence:** `Optional[bool] = False`

Flag indicating whether the right hand side of the PDE has an explicit time dependence.

Type `bool`

**property expression:** `str`

the expression of the right hand side of this PDE

Type `str`

### 4.3.10 pde.pdes.wave module

A simple diffusion equation

```
class WavePDE (speed: float = 1, bc: Union[Dict[str, Union[Dict, str, BCBase]], Dict, str, BCBase,
      Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]], Sequence[Union[Dict[str, Union[Dict,
      str, BCBase]], Dict, str, BCBase, Tuple[Union[Dict, str, BCBase], Union[Dict, str, BCBase]]]]] =
      'auto_periodic_neumann')
```

Bases: `pde.pdes.base.PDEBase`

A simple wave equation

The mathematical definition,

$$\partial_t^2 u = c^2 \nabla^2 u$$

is implemented as two first-order equations:

$$\begin{aligned}\partial_t u &= v \\ \partial_t v &= c^2 \nabla^2 u\end{aligned}$$

where  $u$  is the density field that and  $c$  sets the wave speed.

#### Parameters

- **speed** (`float`) – The speed  $c$  of the wave
- **bc** – The boundary conditions applied to the field. Boundary conditions are generally given as a list with one condition for each axis. For periodic axis, only periodic boundary conditions are allowed (indicated by 'periodic'). For non-periodic axes, different boundary conditions can be specified for the lower and upper end (using a tuple of two conditions). For instance, Dirichlet conditions enforcing a value `NUM` (specified by `{'value': NUM}`) and Neumann conditions enforcing the value `DERIV` for the derivative in the normal direction (specified by `{'derivative': DERIV}`) are supported. Note that the special value 'natural' imposes periodic boundary conditions for periodic axis and a vanishing derivative otherwise. More information can be found in the [boundaries documentation](#).

**evolution\_rate** (`state: FieldCollection, t: float = 0`) → `FieldCollection`

evaluate the right hand side of the PDE

#### Parameters

- **state** (`FieldCollection`) – The fields  $u$  and  $v$  distribution
- **t** (`float`) – The current time point

**Returns** Scalar field describing the evolution rate of the PDE

**Return type** `FieldCollection`

**explicit\_time\_dependence:** `Optional[bool] = False`

Flag indicating whether the right hand side of the PDE has an explicit time dependence.

Type `bool`

**property expressions:** `Dict[str, str]`  
the expressions of the right hand side of this PDE

Type `dict`

**get\_initial\_condition** (*u*: `ScalarField`, *v*: `Optional[ScalarField]` = `None`)  
create a suitable initial condition

**Parameters**

- **u** (`ScalarField`) – The initial density on the grid
- **v** (`ScalarField`, optional) – The initial rate of change. This is assumed to be zero if the value is omitted.

**Returns** The combined fields `u` and `v`, suitable for the simulation

**Return type** `FieldCollection`

## 4.4 `pde.solvers` package

Solvers define how a PDE is solved, i.e., how the initial state is advanced in time.

<code>Controller</code>	class controlling a simulation
<code>ExplicitSolver</code>	class for solving partial differential equations explicitly
<code>ImplicitSolver</code>	class for solving partial differential equations implicitly
<code>ScipySolver</code>	class for solving partial differential equations using scipy
<code>registered_solvers</code>	returns all solvers that are currently registered

**class Controller** (*solver*: `SolverBase`, *t\_range*: `Union[float, Tuple[float, float]]`, *tracker*: `Optional[Union[Sequence[Union[TrackerBase, str]], TrackerBase, str]]` = `'auto'`)

Bases: `object`

class controlling a simulation

**Parameters**

- **solver** (`SolverBase`) – Solver instance that is used to advance the simulation in time
- **t\_range** (`float` or `tuple`) – Sets the time range for which the simulation is run. If only a single value `t_end` is given, the time range is assumed to be `[0, t_end]`.
- **tracker** – Defines a tracker that process the state of the simulation at specified time intervals. A tracker is either an instance of `TrackerBase` or a string, which identifies a tracker. All possible identifiers can be obtained by calling `get_named_trackers()`. Multiple trackers can be specified as a list. The default value `auto` checks the state for consistency (tracker ‘consistency’) and displays a progress bar (tracker ‘progress’) when `tqdm` is installed. More general trackers are defined in `trackers`, where all options are explained in detail. In particular, the interval at which the tracker is evaluated can be chosen when creating a tracker object explicitly.

**get\_current\_time** ()  
process\_time() -> float

Process time for profiling: sum of the kernel and user-space CPU time.

**run** (*state*: `TState`, *dt*: `float` = `None`) → `TState`  
run the simulation

Diagnostic information about the solver procedure are available in the *diagnostics* property of the instance after this function has been called.

#### Parameters

- **state** – The initial state of the simulation. This state will be copied and thus not modified by the simulation. Instead, the final state will be returned and trackers can be used to record intermediate states.
- **dt** (*float*) – Time step of the chosen stepping scheme. If *None*, a default value based on the stepper will be chosen.

**Returns** The state at the final time point.

**property** `t_range`: `Tuple[float, float]`

**class** `ExplicitSolver` (*pde*: `PDEBase`, *scheme*: *str* = 'euler', *backend*: *str* = 'auto', *adaptive*: *bool* = *False*, *tolerance*: *float* = 0.0001)

Bases: `pde.solvers.base.SolverBase`

class for solving partial differential equations explicitly

#### Parameters

- **pde** (`PDEBase`) – The instance describing the pde that needs to be solved
- **scheme** (*str*) – Defines the explicit scheme to use. Supported values are 'euler' and 'runge-kutta' (or 'rk' for short).
- **backend** (*str*) – Determines how the function is created. Accepted values are 'numpy' and 'numba'. Alternatively, 'auto' lets the code decide for the most optimal backend.
- **adaptive** (*bool*) – When enabled, the time step is adjusted during the simulation using the error tolerance set with *tolerance*.
- **tolerance** (*float*) – The error tolerance used in adaptive time stepping. This is used in adaptive time stepping to choose a time step which is small enough so the truncation error of a single step is below *tolerance*.

`dt_max` = 10000000000.0

`dt_min` = 1e-10

**make\_stepper** (*state*: `FieldBase`, *dt*=*None*) → `Callable[[FieldBase, float, float], float]`

return a stepper function using an explicit scheme

#### Parameters

- **state** (`FieldBase`) – An example for the state from which the grid and other information can be extracted
- **dt** (*float*) – Time step of the explicit stepping. If *None*, this solver specifies 1e-3 as a default value.

**Returns** Function that can be called to advance the *state* from time *t\_start* to time *t\_end*. The function call signature is (*state*: `numpy.ndarray`, *t\_start*: *float*, *t\_end*: *float*)

`name` = 'explicit'

**class** `ImplicitSolver` (*pde*: `PDEBase`, *maxiter*: *int* = 100, *maxerror*: *float* = 0.0001, *backend*: *str* = 'auto')

Bases: `pde.solvers.base.SolverBase`

class for solving partial differential equations implicitly

#### Parameters

- **pde** (*PDEBase*) – The instance describing the pde that needs to be solved
- **maxiter** (*int*) – The maximal number of iterations per step
- **maxerror** (*float*) – The maximal error that is permitted in each step
- **backend** (*str*) – Determines how the function is created. Accepted values are ‘numpy’ and ‘numba’. Alternatively, ‘auto’ lets the code decide for the most optimal backend.

**make\_stepper** (*state*: *FieldBase*, *dt=None*) → *Callable*[[*FieldBase*, *float*, *float*], *float*]  
return a stepper function using an implicit scheme

#### Parameters

- **state** (*FieldBase*) – An example for the state from which the grid and other information can be extracted
- **dt** (*float*) – Time step of the explicit stepping. If *None*, this solver specifies 1e-3 as a default value.

**Returns** Function that can be called to advance the *state* from time *t\_start* to time *t\_end*. The function call signature is (*state*: *numpy.ndarray*, *t\_start*: *float*, *t\_end*: *float*)

**name** = 'implicit'

**class ScipySolver** (*pde*: *PDEBase*, *backend*: *str* = 'auto', *\*\*kwargs*)  
Bases: *pde.solvers.base.SolverBase*

class for solving partial differential equations using scipy

This class is a thin wrapper around `scipy.integrate.solve_ivp()`. In particular, it supports all the methods implemented by this function.

#### Parameters

- **pde** (*PDEBase*) – The instance describing the pde that needs to be solved
- **backend** (*str*) – Determines how the function is created. Accepted values are ‘numpy’ and ‘numba’. Alternatively, ‘auto’ lets the code decide for the most optimal backend.
- **\*\*kwargs** – All extra arguments are forwarded to `scipy.integrate.solve_ivp()`.

**make\_stepper** (*state*: *FieldBase*, *dt*: *float* = *None*) → *Callable*[[*FieldBase*, *float*, *float*], *float*]  
return a stepper function

#### Parameters

- **state** (*FieldBase*) – An example for the state from which the grid and other information can be extracted.
- **dt** (*float*) – Initial time step for the simulation. If *None*, the solver will choose a suitable initial value.

**Returns** Function that can be called to advance the *state* from time *t\_start* to time *t\_end*.

**name** = 'scipy'

**registered\_solvers** () → *List*[*str*]  
returns all solvers that are currently registered

**Returns** List with the names of the solvers

**Return type** list of *str*

### 4.4.1 `pde.solvers.base` module

Package that contains base classes for solvers

**class** `SolverBase` (*pde*: `PDEBase`)

Bases: `object`

base class for solvers

**Parameters** `pde` (`PDEBase`) – The partial differential equation that should be solved

**classmethod** `from_name` (*name*: `str`, *pde*: `PDEBase`, *\*\*kwargs*) → `SolverBase`  
create solver class based on its name

Solver classes are automatically registered when they inherit from `SolverBase`. Note that this also requires that the respective python module containing the solver has been loaded before it is attempted to be used.

**Parameters**

- **name** (`str`) – The name of the solver to construct
- **pde** (`PDEBase`) – The partial differential equation that should be solved
- **\*\*kwargs** – Additional arguments for the constructor of the solver

**Returns** An instance of a subclass of `SolverBase`

**abstract** `make_stepper` (*state*, *dt*: `float` = `None`) → `Callable`[[`FieldBase`, `float`, `float`], `float`]

`registered_solvers` = [`'ExplicitSolver'`, `'ImplicitSolver'`, `'ScipySolver'`, `'explicit'`, `'implicit'`, `'scipy'`]

### 4.4.2 `pde.solvers.controller` module

Defines the `Controller` class for solving pdes.

**class** `Controller` (*solver*: `SolverBase`, *t\_range*: `Union`[`float`, `Tuple`[`float`, `float`]], *tracker*: `Optional`[`Union`[`Sequence`[`Union`[`TrackerBase`, `str`]], `TrackerBase`, `str`]] = `'auto'`)

Bases: `object`

class controlling a simulation

**Parameters**

- **solver** (`SolverBase`) – Solver instance that is used to advance the simulation in time
- **t\_range** (`float` or `tuple`) – Sets the time range for which the simulation is run. If only a single value `t_end` is given, the time range is assumed to be `[0, t_end]`.
- **tracker** – Defines a tracker that process the state of the simulation at specified time intervals. A tracker is either an instance of `TrackerBase` or a string, which identifies a tracker. All possible identifiers can be obtained by calling `get_named_trackers()`. Multiple trackers can be specified as a list. The default value `auto` checks the state for consistency (tracker ‘consistency’) and displays a progress bar (tracker ‘progress’) when `tqdm` is installed. More general trackers are defined in `trackers`, where all options are explained in detail. In particular, the interval at which the tracker is evaluated can be chosen when creating a tracker object explicitly.

**get\_current\_time** ()  
process\_time() -> float

Process time for profiling: sum of the kernel and user-space CPU time.

**run** (*state*: *TState*, *dt*: *float* = *None*) → *TState*  
run the simulation

Diagnostic information about the solver procedure are available in the *diagnostics* property of the instance after this function has been called.

#### Parameters

- **state** – The initial state of the simulation. This state will be copied and thus not modified by the simulation. Instead, the final state will be returned and trackers can be used to record intermediate states.
- **dt** (*float*) – Time step of the chosen stepping scheme. If *None*, a default value based on the stepper will be chosen.

**Returns** The state at the final time point.

property **t\_range**: **Tuple**[*float*, *float*]

### 4.4.3 `pde.solvers.explicit` module

Defines an explicit solver supporting various methods

**class ExplicitSolver** (*pde*: *PDEBase*, *scheme*: *str* = 'euler', *backend*: *str* = 'auto', *adaptive*: *bool* = *False*, *tolerance*: *float* = 0.0001)

Bases: `pde.solvers.base.SolverBase`

class for solving partial differential equations explicitly

#### Parameters

- **pde** (*PDEBase*) – The instance describing the pde that needs to be solved
- **scheme** (*str*) – Defines the explicit scheme to use. Supported values are 'euler' and 'runge-kutta' (or 'rk' for short).
- **backend** (*str*) – Determines how the function is created. Accepted values are 'numpy' and 'numba'. Alternatively, 'auto' lets the code decide for the most optimal backend.
- **adaptive** (*bool*) – When enabled, the time step is adjusted during the simulation using the error tolerance set with *tolerance*.
- **tolerance** (*float*) – The error tolerance used in adaptive time stepping. This is used in adaptive time stepping to choose a time step which is small enough so the truncation error of a single step is below *tolerance*.

**dt\_max** = 10000000000.0

**dt\_min** = 1e-10

**info**: **Dict**[*str*, *Any*]

**make\_stepper** (*state*: *FieldBase*, *dt*=*None*) → **Callable**[[*FieldBase*, *float*, *float*], *float*]  
return a stepper function using an explicit scheme

#### Parameters

- **state** (*FieldBase*) – An example for the state from which the grid and other information can be extracted
- **dt** (*float*) – Time step of the explicit stepping. If *None*, this solver specifies 1e-3 as a default value.

**Returns** Function that can be called to advance the *state* from time *t\_start* to time *t\_end*. The function call signature is (*state*: *numpy.ndarray*, *t\_start*: *float*, *t\_end*: *float*)

```
name = 'explicit'
```

#### 4.4.4 pde.solvers.implicit module

Defines an implicit solver

**exception ConvergenceError**

Bases: *RuntimeError*

**class ImplicitSolver** (*pde*: *PDEBase*, *maxiter*: *int* = 100, *maxerror*: *float* = 0.0001, *backend*: *str* = 'auto')

Bases: *pde.solvers.base.SolverBase*

class for solving partial differential equations implicitly

##### Parameters

- **pde** (*PDEBase*) – The instance describing the pde that needs to be solved
- **maxiter** (*int*) – The maximal number of iterations per step
- **maxerror** (*float*) – The maximal error that is permitted in each step
- **backend** (*str*) – Determines how the function is created. Accepted values are ‘numpy’ and ‘numba’. Alternatively, ‘auto’ lets the code decide for the most optimal backend.

**info**: *Dict[str, Any]*

**make\_stepper** (*state*: *FieldBase*, *dt*=*None*) → *Callable[[FieldBase, float, float], float]*

return a stepper function using an implicit scheme

##### Parameters

- **state** (*FieldBase*) – An example for the state from which the grid and other information can be extracted
- **dt** (*float*) – Time step of the explicit stepping. If *None*, this solver specifies 1e-3 as a default value.

**Returns** Function that can be called to advance the *state* from time *t\_start* to time *t\_end*. The function call signature is (*state*: *numpy.ndarray*, *t\_start*: *float*, *t\_end*: *float*)

```
name = 'implicit'
```

#### 4.4.5 pde.solvers.scipy module

Defines a solver using *scipy.integrate*

**class ScipySolver** (*pde*: *PDEBase*, *backend*: *str* = 'auto', *\*\*kwargs*)

Bases: *pde.solvers.base.SolverBase*

class for solving partial differential equations using scipy

This class is a thin wrapper around *scipy.integrate.solve\_ivp()*. In particular, it supports all the methods implemented by this function.

##### Parameters

- **pde** (*PDEBase*) – The instance describing the pde that needs to be solved

- **backend** (*str*) – Determines how the function is created. Accepted values are ‘numpy’ and ‘numba’. Alternatively, ‘auto’ lets the code decide for the most optimal backend.
- **\*\*kwargs** – All extra arguments are forwarded to `scipy.integrate.solve_ivp()`.

**info:** Dict[*str*, Any]

**make\_stepper** (*state*: FieldBase, *dt*: float = None) → Callable[[FieldBase, float, float], float]  
return a stepper function

#### Parameters

- **state** (FieldBase) – An example for the state from which the grid and other information can be extracted.
- **dt** (float) – Initial time step for the simulation. If *None*, the solver will choose a suitable initial value.

**Returns** Function that can be called to advance the *state* from time *t\_start* to time *t\_end*.

**name** = 'scipy'

## 4.5 pde.storage package

Module defining classes for storing simulation data.

<code>get_memory_storage</code>	a context manager that can be used to create a MemoryStorage
<code>MemoryStorage</code>	store discretized fields in memory
<code>FileStorage</code>	store discretized fields in a hdf5 file

### 4.5.1 pde.storage.base module

Base classes for storing data

**class StorageBase** (*info*: Optional[Dict[*str*, Any]] = None, *write\_mode*: *str* = 'truncate\_once')  
Bases: `object`

base class for storing time series of discretized fields

These classes store time series of *FieldBase*, i.e., they store the values of the fields at particular time points. Iterating of the storage will return the fields in order and individual time points can also be accessed.

#### Parameters

- **info** (*dict*) – Supplies extra information that is stored in the storage
- **write\_mode** (*str*) – Determines how new data is added to already existing one. Possible values are: ‘append’ (data is always appended), ‘truncate’ (data is cleared every time this storage is used for writing), or ‘truncate\_once’ (data is cleared for the first writing, but subsequent data using the same instances are appended). Alternatively, specifying ‘readonly’ will disable writing completely.

**append** (*field*: FieldBase, *time*: float = None) → None  
add field to the storage

#### Parameters

- **field** (FieldBase) – The field that is added to the storage

- **time** (*float*, *optional*) – The time point

**apply** (*func*: *Callable*, *out*: *Optional[StorageBase]* = *None*, \*, *progress*: *bool* = *False*) → *StorageBase*  
 applies function to each field in a storage

#### Parameters

- **func** (*callable*) – The function to apply to each stored field. The function must either take as a single argument the field or as two arguments the field and the associated time point. In both cases, it should return a field.
- **out** (*StorageBase*) – Storage to which the output is written. If omitted, a new *MemoryStorage* is used and returned
- **progress** (*bool*) – Flag indicating whether the progress is shown during the calculation

**Returns** The new storage that contains the data after the function *func* has been applied

**Return type** *StorageBase*

**clear** (*clear\_data\_shape*: *bool* = *False*) → *None*  
 truncate the storage by removing all stored data.

**Parameters** **clear\_data\_shape** (*bool*) – Flag determining whether the data shape is also deleted.

**copy** (*out*: *Optional[StorageBase]* = *None*, \*, *progress*: *bool* = *False*) → *StorageBase*  
 copies all fields in a storage to a new one

#### Parameters

- **out** (*StorageBase*) – Storage to which the output is written. If omitted, a new *MemoryStorage* is used and returned
- **progress** (*bool*) – Flag indicating whether the progress is shown during the calculation

**Returns** The new storage that contains the copied data

**Return type** *StorageBase*

**data**: *Any*

**property data\_shape**: *Tuple[int, ...]*  
 the current data shape.

**Raises** *RuntimeError* – if *data\_shape* was not set

**property dtype**: *Tuple[int, ...]*  
 the current data type.

**Raises** *RuntimeError* – if *data\_type* was not set

**end\_writing** () → *None*  
 finalize the storage after writing

**extract\_field** (*field\_id*: *Union[int, str]*, *label*: *str* = *None*) → *MemoryStorage*  
 extract the time course of a single field from a collection

---

**Note:** This might return a view into the original data, so modifying the returned data can also change the underlying original data.

---

#### Parameters

- **field\_id** (*int or str*) – The index into the field collection. This determines which field of the collection is returned. Instead of a numerical index, the field label can also be supplied. If there are multiple fields with the same label, only the first field is returned.
- **label** (*str*) – The label of the returned field. If omitted, the stored label is used.

**Returns** a storage instance that contains the data for the single field

**Return type** `MemoryStorage`

**extract\_time\_range** (*t\_range: Union[float, Tuple[float, float]] = None*) → *MemoryStorage*  
extract a particular time interval

---

**Note:** This might return a view into the original data, so modifying the returned data can also change the underlying original data.

---

**Parameters** **t\_range** (*float or tuple*) – Determines the range of time points included in the result. If only a single number is given, all data up to this time point are included.

**Returns** a storage instance that contains the extracted data.

**Return type** `MemoryStorage`

**property** **grid**: `Optional[pde.grids.base.GridBase]`  
the grid associated with this storage

This returns *None* if grid was not stored in *self.info*.

**Type** *GridBase*

**property** **has\_collection**: `bool`  
whether the storage is storing a collection

**Type** `bool`

**items** () → `Iterator[Tuple[float, FieldBase]]`  
iterate over all times and stored fields, returning pairs

**property** **shape**: `Optional[Tuple[int, ...]]`  
the shape of the stored data

**start\_writing** (*field: FieldBase, info: Optional[Dict[str, Any]] = None*) → *None*  
initialize the storage for writing data

**Parameters**

- **field** (*FieldBase*) – An example of the data that will be written to extract the grid and the data\_shape
- **info** (*dict*) – Supplies extra information that is stored in the storage

**times**: `Sequence[float]`

**tracker** (*interval: Union[int, float, ConstantIntervals] = 1*) → *StorageTracker*  
create object that can be used as a tracker to fill this storage

**Parameters** **interval** – Determines how often the tracker interrupts the simulation. Simple numbers are interpreted as durations measured in the simulation time variable. Alternatively, a string using the format 'hh:mm:ss' can be used to give durations in real time. Finally, instances of the classes defined in *intervals* can be given for more control.

**Returns** The tracker that fills the current storage

Return type *StorageTracker*

**write\_mode:** *str*

**class StorageTracker** (*storage, interval: Union[ConstantIntervals, float, int, str] = 1*)

Bases: *pde.trackers.base.TrackerBase*

Tracker that stores data in special storage classes

**storage**

The underlying storage class through which the data can be accessed

Type *StorageBase*

**Parameters**

- **storage** (*StorageBase*) – Storage instance to which the data is written
- **interval** – Determines how often the tracker interrupts the simulation. Simple numbers are interpreted as durations measured in the simulation time variable. Alternatively, a string using the format ‘hh:mm:ss’ can be used to give durations in real time. Finally, instances of the classes defined in *intervals* can be given for more control.

**finalize** (*info: Optional[Dict[str, Any]] = None*) → *None*

finalize the tracker, supplying additional information

**Parameters** **info** (*dict*) – Extra information from the simulation

**handle** (*field: FieldBase, t: float*) → *None*

handle data supplied to this tracker

**Parameters**

- **field** (*FieldBase*) – The current state of the simulation
- **t** (*float*) – The associated time

**initialize** (*field: FieldBase, info: Optional[Dict[str, Any]] = None*) → *float*

**Parameters**

- **field** (*FieldBase*) – An example of the data that will be analyzed by the tracker
- **info** (*dict*) – Extra information from the simulation

**Returns** The first time the tracker needs to handle data

**Return type** *float*

## 4.5.2 pde.storage.file module

Defines a class storing data on the file system using the hierarchical data format (hdf).

**class FileStorage** (*filename: str, info: Optional[Dict[str, Any]] = None, write\_mode: str = 'truncate\_once', max\_length: int = None, compression: bool = True, keep\_opened: bool = True*)

Bases: *pde.storage.base.StorageBase*

store discretized fields in a hdf5 file

**Parameters**

- **filename** (*str*) – The path to the hdf5-file where the data is stored
- **info** (*dict*) – Supplies extra information that is stored in the storage

- **write\_mode** (*str*) – Determines how new data is added to already existing data. Possible values are: ‘append’ (data is always appended), ‘truncate’ (data is cleared every time this storage is used for writing), or ‘truncate\_once’ (data is cleared for the first writing, but appended subsequently). Alternatively, specifying ‘readonly’ will disable writing completely.
- **max\_length** (*int*, *optional*) – Maximal number of entries that will be stored in the file. This can be used to preallocate data, which can lead to smaller files, but is also less flexible. Giving *max\_length* = *None*, allows for arbitrarily large data, which might lead to larger files.
- **compression** (*bool*) – Whether to store the data in compressed form. Automatically enabled chunked storage.
- **keep\_opened** (*bool*) – Flag indicating whether the file should be kept opened after each writing. If *False*, the file will be closed after writing a dataset. This keeps the file in a consistent state, but also requires more work before data can be written.

**clear** (*clear\_data\_shape*: *bool* = *False*)  
truncate the storage by removing all stored data.

**Parameters** **clear\_data\_shape** (*bool*) – Flag determining whether the data shape is also deleted.

**close** () → *None*  
close the currently opened file

**property data**  
The actual data for all time

**Type** *ndarray*

**end\_writing** () → *None*  
finalize the storage after writing.

This makes sure the data is actually written to a file when *self.keep\_opened* == *False*

**start\_writing** (*field*: *FieldBase*, *info*: *Optional*[*Dict*[*str*, *Any*]] = *None*) → *None*  
initialize the storage for writing data

**Parameters**

- **field** (*FieldBase*) – An example of the data that will be written to extract the grid and the *data\_shape*
- **info** (*dict*) – Supplies extra information that is stored in the storage

**property times**  
The times at which data is available

**Type** *ndarray*

**write\_mode**: *str*

### 4.5.3 pde.storage.memory module

Defines a class storing data in memory.

```
class MemoryStorage (times: Optional[Sequence[float]] = None, data: Optional[List[numpy.ndarray]] = None,  
                    field_obj: Optional[FieldBase] = None, info: Optional[Dict[str, Any]] = None,  
                    write_mode: str = 'truncate_once')
```

Bases: [pde.storage.base.StorageBase](#)

store discretized fields in memory

#### Parameters

- **times** ([ndarray](#)) – Sequence of times for which data is known
- **data** (list of [ndarray](#)) – The field data at the given times
- **field\_obj** ([FieldBase](#)) – An instance of the field class store data for a single time point.
- **info** (*dict*) – Supplies extra information that is stored in the storage
- **write\_mode** (*str*) – Determines how new data is added to already existing data. Possible values are: 'append' (data is always appended), 'truncate' (data is cleared every time this storage is used for writing), or 'truncate\_once' (data is cleared for the first writing, but appended subsequently). Alternatively, specifying 'readonly' will disable writing completely.

```
clear (clear_data_shape: bool = False) → None  
truncate the storage by removing all stored data.
```

**Parameters** **clear\_data\_shape** (*bool*) – Flag determining whether the data shape is also deleted.

**data:** *Any*

```
classmethod from_collection (storages: Sequence[StorageBase], label: str = None, *, rtol: float =  
                            1e-05, atol: float = 1e-08) → MemoryStorage
```

combine multiple memory storages into one

This method can be used to combine multiple time series of different fields into a single representation. This requires that all time series contain data at the same time points.

#### Parameters

- **storages** (*list*) – A collection of instances of [StorageBase](#) whose data will be concatenated into a single [MemoryStorage](#)
- **label** (*str, optional*) – The label of the instances of [FieldCollection](#) that represent the concatenated data
- **rtol** (*float*) – Relative tolerance used when checking times for merging
- **atol** (*float*) – Absolute tolerance used when checking times for merging

**Returns** Storage containing all the data.

**Return type** [MemoryStorage](#)

```
classmethod from_fields (times: Optional[Sequence[float]] = None, fields:  
                        Optional[Sequence[FieldBase]] = None, info: Optional[Dict[str, Any]] =  
                        None, write_mode: str = 'truncate_once') → MemoryStorage
```

create [MemoryStorage](#) from a list of fields

#### Parameters

- **times** ([ndarray](#)) – Sequence of times for which data is known

- **fields** (list of `FieldBase`) – The fields at all given time points
- **info** (*dict*) – Supplies extra information that is stored in the storage
- **write\_mode** (*str*) – Determines how new data is added to already existing data. Possible values are: ‘append’ (data is always appended), ‘truncate’ (data is cleared every time this storage is used for writing), or ‘truncate\_once’ (data is cleared for the first writing, but appended subsequently). Alternatively, specifying ‘readonly’ will disable writing completely.

**start\_writing** (*field*: `FieldBase`, *info*: *Optional*[*Dict*[*str*, *Any*]] = *None*) → *None*  
initialize the storage for writing data

#### Parameters

- **field** (`FieldBase`) – An instance of the field class store data for a single time point.
- **info** (*dict*) – Supplies extra information that is stored in the storage

**times**: *Sequence*[`float`]

**write\_mode**: `str`

**get\_memory\_storage** (*field*: `FieldBase`, *info*: *Optional*[*Dict*[*str*, *Any*]] = *None*)  
a context manager that can be used to create a `MemoryStorage`

---

#### Example

This can be used to quickly store data:

```
with get_memory_storage(field_class) as storage:
    storage.append(numpy_array0, 0)
    storage.append(numpy_array1, 1)

# use storage thereafter
```

---

#### Parameters

- **field** (`FieldBase`) – An instance of the field class store data for a single time point.
- **info** (*dict*) – Supplies extra information that is stored in the storage

**Yields** *MemoryStorage*

## 4.6 pde.tools package

Package containing several tools required in py-pde

<i>cache</i>	Functions, classes, and decorators for managing caches
<i>config</i>	Handles configuration variables of the package
<i>cuboid</i>	An n-dimensional, axes-aligned cuboid
<i>docstrings</i>	Methods for automatic transformation of docstrings
<i>expressions</i>	Handling mathematical expressions with sympy
<i>math</i>	Auxiliary mathematical functions
<i>misc</i>	Miscellaneous python functions
<i>numba</i>	Helper functions for just-in-time compilation with numba
<i>output</i>	Python functions for handling output

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Table 12 – continued from previous page

<i>parameters</i>	Infrastructure for managing classes with parameters
<i>parse_duration</i>	Parsing time durations from strings
<i>plotting</i>	Tools for plotting and controlling plot output using context managers
<i>spectral</i>	Functions making use of spectral decompositions
<i>spherical</i>	Module collecting functions for handling spherical geometry
<i>typing</i>	Provides support for mypy type checking of the package

### 4.6.1 `pde.tools.cache` module

Functions, classes, and decorators for managing caches

<i>cached_property</i>	Decorator to use a method as a cached property
<i>cached_method</i>	Decorator to enable caching of a method
<i>hash_mutable</i>	return hash also for (nested) mutable objects.
<i>hash_readable</i>	return human readable hash also for (nested) mutable objects.
<i>make_serializer</i>	returns a function that serialize data with the given method.
<i>make_unserializer</i>	returns a function that unserialize data with the given method
<i>DictFiniteCapacity</i>	cache with a limited number of items
<i>SerializedDict</i>	a key value database which is stored on the disk This class provides hooks for converting arbitrary keys and values to strings, which are then stored in the database.

```
class DictFiniteCapacity (*args, **kwargs)
```

Bases: `collections.OrderedDict`

cache with a limited number of items

```
check_length()
```

ensures that the dictionary does not grow beyond its capacity

```
default_capacity: int = 100
```

```
update ([E], **F) → None. Update D from dict/iterable E and F.
```

If E is present and has a `.keys()` method, then does: for k in E: D[k] = E[k] If E is present and lacks a `.keys()` method, then does: for k, v in E: D[k] = v In either case, this is followed by: for k in F: D[k] = F[k]

```
class SerializedDict (key_serialization: str = 'pickle', value_serialization: str = 'pickle', storage_dict:
Optional[Dict] = None)
```

Bases: `collections.abc.MutableMapping`

a key value database which is stored on the disk This class provides hooks for converting arbitrary keys and values to strings, which are then stored in the database.

provides a dictionary whose keys and values are serialized

**Parameters**

- **key\_serialization** (*str*) – Determines the serialization method for keys
- **value\_serialization** (*str*) – Determines the serialization method for values

- **storage\_dict** (*dict*) – Can be used to chose a different dictionary for the underlying storage mechanism, e.g., `storage_dict = PersistentDict()`

**class cached\_method** (*factory=None, extra\_args=None, ignore\_args=None, hash\_function='hash\_mutable', doc=None, name=None*)

Bases: `pde.tools.cache._class_cache`

Decorator to enable caching of a method

The function is only called the first time and each successive call returns the cached result of the first call.

---

### Example

The decorator can be used like so:

```
class Foo:

    @cached_method
    def bar(self):
        return "Cached"

foo = Foo()
result = foo.bar()
```

The data is stored in a dictionary named `_cache_methods` attached to the instance of each object. The cache can thus be cleared by setting `self._cache_methods = {}`. The cache of specific property can be cleared using `self._cache_methods[property_name] = {}`, where `property_name` is the name of the property

decorator that caches calls in a dictionary attached to the instances. This can be used with most classes

---

### Example

An example for using the class is:

```
class Foo():

    @cached_property()
    def property(self):
        return "Cached property"

    @cached_method()
    def method(self):
        return "Cached method"

foo = Foo()
foo.property
foo.method()
```

The cache can be cleared by setting `foo._cache_methods = {}` if the cache factory is a simple dict, i.e, if `factory == None`. Alternatively, each cached method has a `clear_cache_of_obj()` method, which clears the cache of this particular method. In the example above we could thus call `foo.bar.clear_cache_of_obj(foo)` to clear the cache. Note that the object instance has to be passed as a parameter, since the method `bar()` is defined on the class, not the instance, i.e., we could also call `Foo.bar.clear_cache_of_obj(foo)`. To clear the cache from within

a method, one can thus call `self.method_name.clear_cache_of_obj(self)`, where `method_name` is the name of the method whose cache is cleared

---

### Example

An advanced example is:

```
class Foo():

    def get_cache(self, name):
        # `name` is the name of the method to cache
        return DictFiniteCapacity()

    @cached_method(factory='get_cache')
    def foo(self):
        return "Cached"
```

---

### Parameters

- **factory** (*callable*) – Function/class creating an empty cache. *dict* by default. This can be used with user-supplied storage backends by. The cache factory should return a dict-like object that handles the cache for the given method.
- **extra\_args** (*list*) – List of attributes of the class that are included in the cache key. They are then treated as if they are supplied as arguments to the method. This is important to include when the result of a method depends not only on method arguments but also on instance attributes.
- **ignore\_args** (*list*) – List of keyword arguments that are not included in the cache key. These should be arguments that do not influence the result of a method, e.g., because they only affect how intermediate results are displayed.
- **hash\_function** (*str*) – An identifier determining what hash function is used on the argument list.
- **doc** (*str*) – Optional string giving the docstring of the decorated method
- **name** (*str*) – Optional string giving the name of the decorated method

```
class cached_property(factory=None, extra_args=None, ignore_args=None, hash_function='hash_mutable',
                      doc=None, name=None)
```

Bases: `pde.tools.cache._class_cache`

Decorator to use a method as a cached property

The function is only called the first time and each successive call returns the cached result of the first call.

---

### Example

Here is an example for how to use the decorator:

```
class Foo():

    @cached_property
    def bar(self):
        return "Cached"
```

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```
foo = Foo()
result = foo.bar
```

The data is stored in a dictionary named `_cache_methods` attached to the instance of each object. The cache can thus be cleared by setting `self._cache_methods = {}`. The cache of specific property can be cleared using `self._cache_methods[property_name] = {}`, where `property_name` is the name of the property

Adapted from <<https://wiki.python.org/moin/PythonDecoratorLibrary>>.

decorator that caches calls in a dictionary attached to the instances. This can be used with most classes

---

### Example

An example for using the class is:

```
class Foo():

    @cached_property()
    def property(self):
        return "Cached property"

    @cached_method()
    def method(self):
        return "Cached method"

foo = Foo()
foo.property
foo.method()
```

The cache can be cleared by setting `foo._cache_methods = {}` if the cache factory is a simple dict, i.e, if `factory == None`. Alternatively, each cached method has a `clear_cache_of_obj()` method, which clears the cache of this particular method. In the example above we could thus call `foo.bar.clear_cache_of_obj(foo)` to clear the cache. Note that the object instance has to be passed as a parameter, since the method `bar()` is defined on the class, not the instance, i.e., we could also call `Foo.bar.clear_cache_of_obj(foo)`. To clear the cache from within a method, one can thus call `self.method_name.clear_cache_of_obj(self)`, where `method_name` is the name of the method whose cache is cleared

---

### Example

An advanced example is:

```
class Foo():

    def get_cache(self, name):
        # `name` is the name of the method to cache
        return DictFiniteCapacity()

    @cached_method(factory='get_cache')
    def foo(self):
        return "Cached"
```

**Parameters**

- **factory** (*callable*) – Function/class creating an empty cache. *dict* by default. This can be used with user-supplied storage backends by. The cache factory should return a dict-like object that handles the cache for the given method.
- **extra\_args** (*list*) – List of attributes of the class that are included in the cache key. They are then treated as if they are supplied as arguments to the method. This is important to include when the result of a method depends not only on method arguments but also on instance attributes.
- **ignore\_args** (*list*) – List of keyword arguments that are not included in the cache key. These should be arguments that do not influence the result of a method, e.g., because they only affect how intermediate results are displayed.
- **hash\_function** (*str*) – An identifier determining what hash function is used on the argument list.
- **doc** (*str*) – Optional string giving the docstring of the decorated method
- **name** (*str*) – Optional string giving the name of the decorated method

**hash\_mutable** (*obj*) → *int*

return hash also for (nested) mutable objects.

---

**Notes**

This function might be a bit slow, since it iterates over all containers and hashes objects recursively. Moreover, the returned value might change with each run of the python interpreter, since the hash values of some basic objects, like *None*, change with each instance of the interpreter.

---

**Parameters** *obj* – A general python object

**Returns** A hash value associated with the data of *obj*

**Return type** *int*

**hash\_readable** (*obj*) → *str*

return human readable hash also for (nested) mutable objects.

This function returns a JSON-like representation of the object. The function might be a bit slow, since it iterates over all containers and hashes objects recursively. Note that this hash function tries to return the same value for equivalent objects, but it does not ensure that the objects can be reconstructed from this data.

**Parameters** *obj* – A general python object

**Returns** A hash value associated with the data of *obj*

**Return type** *str*

**make\_serializer** (*method: str*) → *Callable*

returns a function that serialize data with the given method. Note that some of the methods destroy information and cannot be reverted.

**Parameters** *method* (*str*) – An identifier determining the serializer that will be returned

**Returns** A function that serializes objects

**Return type** *callable*

**make\_unserializer** (*method: str*) → Callable

returns a function that unserialize data with the given method

This is the inverse function of `make_serializer()`.

**Parameters** `method (str)` – An identifier determining the unserializer that will be returned

**Returns** A function that serializes objects

**Return type** callable

**objects\_equal** (*a, b*) → bool

compares two objects to see whether they are equal

In particular, this uses `numpy.array_equal()` to check for numpy arrays

**Parameters**

- **a** – The first object
- **b** – The second object

**Returns** Whether the two objects are considered equal

**Return type** bool

## 4.6.2 pde.tools.config module

Handles configuration variables of the package

<code>Config</code>	class handling the package configuration
<code>get_package_versions</code>	tries to load certain python packages and returns their version
<code>parse_version_str</code>	helper function converting a version string into a list of integers
<code>check_package_version</code>	checks whether a package has a sufficient version
<code>environment</code>	obtain information about the compute environment

**class Config** (*items: Optional[Dict[str, Any]] = None, mode: str = 'update'*)

Bases: `collections.UserDict`

class handling the package configuration

**Parameters**

- **items** (*dict, optional*) – Configuration values that should be added or overwritten to initialize the configuration.
- **mode** (*str*) – Defines the mode in which the configuration is used. Possible values are
  - *insert*: any new configuration key can be inserted
  - *update*: only the values of pre-existing items can be updated
  - *locked*: no values can be changed

Note that the items specified by *items* will always be inserted, independent of the *mode*.

**to\_dict** () → Dict[str, Any]

convert the configuration to a simple dictionary

**Returns** A representation of the configuration in a normal `dict`.

**Return type** `dict`

**check\_package\_version** (*package\_name*: `str`, *min\_version*: `str`)  
checks whether a package has a sufficient version

**environment** () → `Dict[str, Any]`  
obtain information about the compute environment

**Returns** information about the python installation and packages

**Return type** `dict`

**get\_package\_versions** (*packages*: `List[str]`, \*, *na\_str*='not available') → `Dict[str, str]`  
tries to load certain python packages and returns their version

**Parameters**

- **packages** (`list`) – The names of all packages
- **na\_str** (`str`) – Text to return if package is not available

**Returns** Dictionary with version for each package name

**Return type** `dict`

**parse\_version\_str** (*ver\_str*: `str`) → `List[int]`  
helper function converting a version string into a list of integers

### 4.6.3 pde.tools.cuboid module

An n-dimensional, axes-aligned cuboid

This module defines the `Cuboid` class, which represents an n-dimensional cuboid that is aligned with the axes of a Cartesian coordinate system.

**class Cuboid** (*pos*, *size*, *mutable*: `bool` = `True`)  
Bases: `object`

class that represents a cuboid in *n* dimensions

defines a cuboid from a position and a size vector

**Parameters**

- **pos** (`list`) – The position of the lower left corner. The length of this list determines the dimensionality of space
- **size** (`list`) – The size of the cuboid along each dimension.
- **mutable** (`bool`) – Flag determining whether the cuboid parameters can be changed

**property bounds**: `Tuple[Tuple[float, float], ...]`

**buffer** (*amount*: `Union[float, numpy.ndarray]` = 0, *inplace*=`False`) → `Cuboid`  
dilate the cuboid by a certain amount in all directions

**property centroid**

**contains\_point** (*points*: `numpy.ndarray`) → `numpy.ndarray`  
returns a True when *points* are within the Cuboid

**Parameters** **points** (`ndarray`) – List of point coordinates

**Returns** list of booleans indicating which points are inside

**Return type** `ndarray`

`copy()` → *Cuboid*

**property corners:** `Tuple[numpy.ndarray, numpy.ndarray]`  
return coordinates of two extreme corners defining the cuboid

**property diagonal:** `float`  
returns the length of the diagonal

**property dim:** `int`

**classmethod from\_bounds** (*bounds: numpy.ndarray, \*\*kwargs*) → *Cuboid*  
create cuboid from bounds

**Parameters** *bounds* (*list*) – Two dimensional array of axes bounds

**Returns** cuboid with positive size

**Return type** *Cuboid*

**classmethod from\_centerpoint** (*centerpoint: numpy.ndarray, size: numpy.ndarray, \*\*kwargs*) → *Cuboid*  
create cuboid from two points

**Parameters**

- **centerpoint** (*list*) – Coordinates of the center
- **size** (*list*) – Size of the cuboid

**Returns** cuboid with positive size

**Return type** *Cuboid*

**classmethod from\_points** (*p1: numpy.ndarray, p2: numpy.ndarray, \*\*kwargs*) → *Cuboid*  
create cuboid from two points

**Parameters**

- **p1** (*list*) – Coordinates of first corner point
- **p2** (*list*) – Coordinates of second corner point

**Returns** cuboid with positive size

**Return type** *Cuboid*

**property mutable:** `bool`

**property size:** `numpy.ndarray`

**property surface\_area:** `float`  
surface area of a cuboid in  $n$  dimensions.

The surface area is the volume of the  $(n - 1)$ -dimensional hypercubes that bound the current cuboid:

- $n = 1$ : the number of end points (2)
- $n = 2$ : the perimeter of the rectangle
- $n = 3$ : the surface area of the cuboid

**property vertices:** `List[List[float]]`  
return the coordinates of all the corners

**property volume:** `float`

**asanyarray\_flags** (*data*: `numpy.ndarray`, *dtype*=`None`, *writeable*: `bool = True`)  
turns data into an array and sets the respective flags.

A copy is only made if necessary

**Parameters**

- **data** (`ndarray`) – numpy array that whose flags are adjusted
- **dtype** – the resultant dtype
- **writeable** (`bool`) – Flag determining whether the results is writable

**Returns** array with same data as *data* but with flags adjusted.

**Return type** `ndarray`

## 4.6.4 `pde.tools.docstrings` module

Methods for automatic transformation of docstrings

<code>get_text_block</code>	return a single text block
<code>replace_in_docstring</code>	replace a text in a docstring using the correct indentation
<code>fill_in_docstring</code>	decorator that replaces text in the docstring of a function

**fill\_in\_docstring** (*f*: `TFunc`) → `TFunc`  
decorator that replaces text in the docstring of a function

**get\_text\_block** (*identifier*: `str`) → `str`  
return a single text block

**Parameters** **identifier** (`str`) – The name of the text block

**Returns** the text block as one long line.

**Return type** `str`

**replace\_in\_docstring** (*f*: `TFunc`, *token*: `str`, *value*: `str`, *docstring*: `str = None`) → `TFunc`  
replace a text in a docstring using the correct indentation

**Parameters**

- **f** (`callable`) – The function with the docstring to handle
- **token** (`str`) – The token to search for
- **value** (`str`) – The replacement string
- **docstring** (`str`) – A docstring that should be used instead of `f.__doc__`

**Returns** The function with the modified docstring

**Return type** `callable`

## 4.6.5 `pde.tools.expressions` module

Handling mathematical expressions with sympy

This module provides classes representing expressions that can be provided as human-readable strings and are converted to `numpy` and `numba` representations using `sympy`.

<code>parse_number</code>	return a number compiled from an expression
<code>ScalarExpression</code>	describes a mathematical expression of a scalar quantity
<code>TensorExpression</code>	describes a mathematical expression of a tensorial quantity

```
class ExpressionBase (expression: sympy.core.basic.Basic, signature: Optional[Sequence[Union[str, List[str]]]]
                      = None, *, user_funcs: Optional[Dict[str, Any]] = None, consts: Optional[Dict[str,
                      Any]] = None)
```

Bases: `object`

abstract base class for handling expressions

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur.

### Parameters

- **expression** (`sympy.core.basic.Basic`) – A sympy expression or array. This could for instance be an instance of `Expr` or `NDimArray`.
- **signature** (*list of str, optional*) – The signature defines which variables are expected in the expression. This is typically a list of strings identifying the variable names. Individual names can be specified as list, in which case any of these names can be used. The first item in such a list is the definite name and if another name of the list is used, the associated variable is renamed to the definite name. If signature is `None`, all variables in *expressions* are allowed.
- **user\_funcs** (*dict, optional*) – A dictionary with user defined functions that can be used in the expression.
- **consts** (*dict, optional*) – A dictionary with user defined constants that can be used in the expression. The values of these constants should either be numbers or `ndarray`.

```
classmethod check_reserved_symbols (symbols: Iterable[str], strict: bool = True) → None
throws an error if reserved symbols are found
```

### Parameters

- **symbols** (*iterable*) – A sequence or set of strings with symbols to check.
- **strict** (*bool*) – Flag determining whether an exception is raised

```
property complex: bool
whether the expression contains the imaginary unit I
```

Type `bool`

```
property constant: bool
whether the expression is a constant
```

Type `bool`

**depends\_on** (*variable: str*) → bool

determine whether the expression depends on *variable*

**Parameters** *variable* (*str*) – the name of the variable to check for

**Returns** whether the variable appears in the expression

**Return type** bool

**property expression: str**

the expression in string form

**Type** str

**get\_compiled** (*single\_arg: bool = False*) → Callable[[...], NumberOrArray]

return numba function evaluating expression

**Parameters** *single\_arg* (*bool*) – Determines whether the returned function accepts all variables in a single argument as an array or whether all variables need to be supplied separately

**Returns** the compiled function

**Return type** function

**property rank: int**

the rank of the expression

**Type** int

**abstract property shape: Tuple[int, ...]**

```
class ScalarExpression (expression: Union[float, str, numpy.ndarray, sympy.core.basic.Basic,
                                     ExpressionBase] = 0, signature: Optional[Sequence[Union[str, List[str]]]] = None,
                        *, user_funcs: Optional[Dict[str, Any]] = None, consts: Optional[Dict[str, Any]] =
                        None, allow_indexed: bool = False)
```

Bases: `pde.tools.expressions.ExpressionBase`

describes a mathematical expression of a scalar quantity

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur.

### Parameters

- **expression** (*str* or *float*) – The expression, which is either a number or a string that sympy can parse
- **signature** (*list of str*) – The signature defines which variables are expected in the expression. This is typically a list of strings identifying the variable names. Individual names can be specified as lists, in which case any of these names can be used. The first item in such a list is the definite name and if another name of the list is used, the associated variable is renamed to the definite name. If signature is *None*, all variables in *expressions* are allowed.
- **user\_funcs** (*dict*, *optional*) – A dictionary with user defined functions that can be used in the expression
- **consts** (*dict*, *optional*) – A dictionary with user defined constants that can be used in the expression. The values of these constants should either be numbers or `ndarray`.
- **allow\_indexed** (*bool*) – Whether to allow indexing of variables. If enabled, array variables are allowed to be indexed using square bracket notation.

**copy** () → *ScalarExpression*

return a copy of the current expression

**derivatives**

differentiate the expression with respect to all variables

**differentiate** (var: *str*) → *ScalarExpression*

return the expression differentiated with respect to var

**property is\_zero**: **bool**

returns whether the expression is zero

**Type** **bool**

**shape**: **Tuple**[**int**, ...] = ()

**property value**: **Union**[**int**, **float**, **complex**]

the value for a constant expression

**Type** **float**

**class** **TensorExpression** (expression: *Union*[*float*, *str*, *numpy.ndarray*, *sympy.core.basic.Basic*, *ExpressionBase*], signature: *Optional*[*Sequence*[*Union*[*str*, *List*[*str*]]]] = *None*, \*, user\_funcs: *Optional*[*Dict*[*str*, *Any*]] = *None*)

Bases: *pde.tools.expressions.ExpressionBase*

describes a mathematical expression of a tensorial quantity

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur.

### Parameters

- **expression** (*str* or *float*) – The expression, which is either a number or a string that sympy can parse
- **signature** (*list of str*) – The signature defines which variables are expected in the expression. This is typically a list of strings identifying the variable names. Individual names can be specified as list, in which case any of these names can be used. The first item in such a list is the definite name and if another name of the list is used, the associated variable is renamed to the definite name. If signature is *None*, all variables in *expressions* are allowed.
- **user\_funcs** (*dict*, *optional*) – A dictionary with user defined functions that can be used in the expression.

**derivatives**

differentiate the expression with respect to all variables

**differentiate** (var: *str*) → *TensorExpression*

return the expression differentiated with respect to var

**get\_compiled\_array** (single\_arg: *bool* = *True*) → *Callable*[[*numpy.ndarray*, *numpy.ndarray*], *numpy.ndarray*]

compile the tensor expression such that a numpy array is returned

**Parameters** **single\_arg** (*bool*) – Whether the compiled function expects all arguments as a single array or whether they are supplied individually.

**property shape**: **Tuple**[**int**, ...]

the shape of the tensor

Type `tuple`

**property value**

the value for a constant expression

**parse\_number** (*expression*: `Union[str, int, float, complex]`, *variables*: `Optional[Mapping[str, Number]] = None`)  $\rightarrow$  `Number`

return a number compiled from an expression

**Warning:** This implementation uses `exec()` and should therefore not be used in a context where malicious input could occur.

**Parameters**

- **expression** (*str* or *Number*) – An expression that can be interpreted as a number
- **variables** (*dict*) – A dictionary of values that replace variables in the expression

**Returns** the calculated value

**Return type** `Number`

## 4.6.6 pde.tools.math module

Auxiliary mathematical functions

**class SmoothData1D** (*x*, *y*, *sigma*: `float = None`)

Bases: `object`

allows smoothing data in 1d using a Gaussian kernel of defined width

The data is given a pairs of *x* and *y*, the assumption being that there is an underlying relation  $y = f(x)$ .

initialize with data

**Parameters**

- **x** – List of *x* values
- **y** – List of *y* values
- **sigma** (*float*) – The size of the smoothing window in units of *x*. If omitted, the average distance of *x* values multiplied by *sigma\_auto\_scale* is used.

**property bounds:** `Tuple[float, float]`

return minimal and maximal *x* values

**sigma\_auto\_scale:** `float = 10`

scale for setting automatic values for sigma

Type `float`

## 4.6.7 `pde.tools.misc` module

Miscellaneous python functions

<code>module_available</code>	check whether a python module is available
<code>ensure_directory_exists</code>	creates a folder if it not already exists
<code>preserve_scalars</code>	decorator that makes vectorized methods work with scalars
<code>decorator_arguments</code>	make a decorator usable with and without arguments:
<code>skipUnlessModule</code>	decorator that skips a test when a module is not available
<code>import_class</code>	import a class or module given an identifier
<code>classproperty</code>	decorator that can be used to define read-only properties for classes.
<code>hybridmethod</code>	descriptor that can be used as a decorator to allow calling a method both as a classmethod and an instance method
<code>estimate_computation_speed</code>	estimates the computation speed of a function
<code>hdf_write_attributes</code>	write (JSON-serialized) attributes to a hdf file
<code>number</code>	convert a value into a float or complex number
<code>get_common_dtype</code>	returns a dtype in which all arguments can be represented
<code>number_array</code>	convert an array with arbitrary dtype either to <code>np.double</code> or <code>np.cdouble</code>

**class** `classproperty` (*fget=None, doc=None*)

Bases: `property`

decorator that can be used to define read-only properties for classes.

This is inspired by the implementation of `astropy`, see [astropy.org](https://astropy.org).

---

### Example

The decorator can be used much like the `property` decorator:

```
class Test():

    item: str = 'World'

    @classproperty
    def message(cls):
        return 'Hello ' + cls.item

print(Test.message)
```

**deleter** (*fdel*)

Descriptor to change the deleter on a property.

**getter** (*fget*)

Descriptor to change the getter on a property.

**setter** (*fset*)

Descriptor to change the setter on a property.

**decorator\_arguments** (*decorator: Callable*)  $\rightarrow$  *Callable*

make a decorator usable with and without arguments:

The resulting decorator can be used like `@decorator` or `@decorator(*args, **kwargs)`

Inspired by <https://stackoverflow.com/a/14412901/932593>

**Parameters** **decorator** – the decorator that needs to be modified

**Returns** the decorated function

**ensure\_directory\_exists** (*folder*: *Union[str, pathlib.Path]*)

creates a folder if it not already exists

**Parameters** **folder** (*str*) – path of the new folder

**estimate\_computation\_speed** (*func*: *Callable*, \**args*, \*\**kwargs*) → *float*

estimates the computation speed of a function

**Parameters** **func** (*callable*) – The function to call

**Returns** the number of times the function can be calculated in one second. The inverse is thus the runtime in seconds per function call

**Return type** *float*

**get\_common\_dtype** (\**args*)

returns a dtype in which all arguments can be represented

**Parameters** \***args** – All items (arrays, scalars, etc) to be checked

Returns: numpy.cdouble if any entry is complex, otherwise np.double

**hdf\_write\_attributes** (*hdf\_path*, *attributes*: *Optional[Dict[str, Any]]* = *None*, *raise\_serialization\_error*: *bool* = *False*) → *None*

write (JSON-serialized) attributes to a hdf file

**Parameters**

- **hdf\_path** – Path to a group or dataset in an open HDF file
- **attributes** (*dict*) – Dictionary with values written as attributes
- **raise\_serialization\_error** (*bool*) – Flag indicating whether serialization errors are raised or silently ignored

**class hybridmethod** (*fclass*, *finstance*=*None*, *doc*=*None*)

Bases: *object*

descriptor that can be used as a decorator to allow calling a method both as a classmethod and an instance method

Adapted from <https://stackoverflow.com/a/28238047>

**classmethod** (*fclass*)

**instancemethod** (*finstance*)

**import\_class** (*identifier*: *str*)

import a class or module given an identifier

**Parameters** **identifier** (*str*) – The identifier can be a module or a class. For instance, calling the function with the string *identifier* == *'numpy.linalg.norm'* is roughly equivalent to running *from numpy.linalg import norm* and would return a reference to *norm*.

**module\_available** (*module\_name*: *str*) → *bool*

check whether a python module is available

**Parameters** **module\_name** (*str*) – The name of the module

**Returns** *True* if the module can be imported and *False* otherwise

**number** (*value: Union[int, float, complex, str]*) → Number  
convert a value into a float or complex number

**Parameters** **value** (*Number or str*) – The value which needs to be converted

**Result:** Number: A complex number or a float if the imaginary part vanishes

**number\_array** (*data: Union[int, float, complex, numpy.ndarray, Sequence[NumberOrArray], Sequence[Sequence[Any]]], dtype=None, copy: bool = True*) → `numpy.ndarray`  
convert an array with arbitrary dtype either to `np.double` or `np.cdouble`

**Parameters**

- **data** (`ndarray`) – The data that needs to be converted to a float array. This can also be any iterable of numbers.
- **dtype** (*numpy dtype*) – The data type of the field. All the numpy dtypes are supported. If omitted, it will be determined from *data* automatically.
- **copy** (*bool*) – Whether the data must be copied (in which case the original array is left untouched). Note that data will always be copied when changing the dtype.

**Returns** An array with the correct dtype

**Return type** `ndarray`

**preserve\_scalars** (*method: TFunc*) → TFunc  
decorator that makes vectorized methods work with scalars

This decorator allows to call functions that are written to work on numpy arrays to also accept python scalars, like *int* and *float*. Essentially, this wrapper turns them into an array and unboxes the result.

**Parameters** **method** – The method being decorated

**Returns** The decorated method

**skipUnlessModule** (*module\_names: Union[Sequence[str], str]*) → `Callable[[TFunc], TFunc]`  
decorator that skips a test when a module is not available

**Parameters** **module\_names** (*str*) – The name of the required module(s)

**Returns** A function, so this can be used as a decorator

## 4.6.8 `pde.tools.numba` module

Helper functions for just-in-time compilation with numba

**convert\_scalar** (*arr*)  
helper function that turns 0d-arrays into scalars

This helps to avoid the bug discussed in <https://github.com/numba/numba/issues/6000>

**flat\_idx** (*arr, i*)  
helper function allowing indexing of scalars as if they arrays

**get\_common\_numba\_dtype** (*\*args*)  
returns a numba numerical type in which all arrays can be represented

**Parameters** **\*args** – All items to be tested

Returns: `numba.complex128` if any entry is complex, otherwise `numba.double`

**jit** (*function*: TFunc, *signature*=None, *parallel*: bool = False, *\*\*kwargs*) → TFunc  
 apply nb.jit with predefined arguments

#### Parameters

- **function** – The function which is jitted
- **signature** – Signature of the function to compile
- **parallel** (bool) – Allow parallel compilation of the function
- **\*\*kwargs** – Additional arguments to *nb.jit*

**Returns** Function that will be compiled using numba

**jit\_allocate\_out** (*func*: Callable, *parallel*: bool = False, *out\_shape*: Optional[Tuple[int, ...]] = None, *num\_args*: int = 1, *\*\*kwargs*) → Callable

Decorator that compiles a function with allocating an output array.

This decorator compiles a function that takes the arguments *arr* and *out*. The point of this decorator is to make the *out* array optional by supplying an empty array of the same shape as *arr* if necessary. This is implemented efficiently by using `numba.generated_jit()`.

#### Parameters

- **func** – The function to be compiled
- **parallel** (bool) – Determines whether the function is jitted with `parallel=True`.
- **out\_shape** (tuple) – Determines the shape of the *out* array. If omitted, the same shape as the input array is used.
- **num\_args** (int, optional) – Determines the number of input arguments of the function.
- **\*\*kwargs** – Additional arguments used in `numba.jit()`

**Returns** The decorated function

**make\_array\_constructor** (*arr*: numpy.ndarray) → Callable[[], numpy.ndarray]

returns an array within a jitted function using basic information

**Parameters** **arr** (ndarray) – The array that should be accessible within jit

**Warning:** A reference to the array needs to be retained outside the numba code to prevent garbage collection from removing the array

**numba\_dict** (*data*: Optional[Dict[str, Any]] = None) → Optional[numba.typed.typeddict.Dict]

converts a python dictionary to a numba typed dictionary

**numba\_environment** () → Dict[str, Any]

return information about the numba setup used

**Returns** (dict) information about the numba setup

## 4.6.9 pde.tools.output module

Python functions for handling output

<code>get_progress_bar_class</code>	returns a class that behaves as progress bar.
<code>display_progress</code>	displays a progress bar when iterating
<code>in_jupyter_notebook</code>	checks whether we are in a jupyter notebook
<code>BasicOutput</code>	class that writes text line to stdout
<code>JupyterOutput</code>	class that writes text lines as html in a jupyter cell

**class** `BasicOutput` (*stream*=<\_io.TextIOWrapper name='<stdout>' mode='w' encoding='UTF-8'>)

Bases: `pde.tools.output.OutputBase`

class that writes text line to stdout

**Parameters** *stream* – The stream where the lines are written

**show** ()

shows the actual text

**class** `JupyterOutput` (*header*: *str* = "", *footer*: *str* = "")

Bases: `pde.tools.output.OutputBase`

class that writes text lines as html in a jupyter cell

**Parameters**

- **header** (*str*) – The html code written before all lines
- **footer** (*str*) – The html code written after all lines

**show** ()

shows the actual html in a jupyter cell

**class** `OutputBase`

Bases: `object`

base class for output management

**abstract** **show** ()

**class** `SimpleProgress` (*iterable*=None, \**args*, \*\**kwargs*)

Bases: `object`

indicates progress by printing dots to stderr

**close** (\**args*, \*\**kwargs*)

**refresh** (\**args*, \*\**kwargs*)

**set\_description** (*msg*: *str*, *refresh*: *bool* = True, \**args*, \*\**kwargs*)

**display\_progress** (*iterator*, *total*=None, *enabled*=True, \*\**kwargs*)

displays a progress bar when iterating

**Parameters**

- **iterator** (*iter*) – The iterator
- **total** (*int*) – Total number of steps
- **enabled** (*bool*) – Flag determining whether the progress is display
- **\*\*kwargs** – All extra arguments are forwarded to the progress bar class

**Returns** A class that behaves as the original iterator, but shows the progress alongside iteration.

**get\_progress\_bar\_class** () → `Type[SimpleProgress]`  
returns a class that behaves as progress bar.

This either uses classes from the optional *tqdm* package or a simple version that writes dots to stderr, if the class is not available.

**in\_jupyter\_notebook** () → `bool`  
checks whether we are in a jupyter notebook

## 4.6.10 pde.tools.parameters module

Infrastructure for managing classes with parameters

One aim is to allow easy management of inheritance of parameters.

<code>Parameter</code>	class representing a single parameter
<code>DeprecatedParameter</code>	a parameter that can still be used normally but is deprecated
<code>HideParameter</code>	a helper class that allows hiding parameters of the parent classes
<code>Parameterized</code>	a mixin that manages the parameters of a class
<code>get_all_parameters</code>	get a dictionary with all parameters of all registered classes

**class DeprecatedParameter** (*name: str, default\_value=None, cls=<class 'object'>, description: str = "", hidden: bool = False, extra: typing.Optional[typing.Dict[str, typing.Any]] = None*)

Bases: `pde.tools.parameters.Parameter`

a parameter that can still be used normally but is deprecated

initialize a parameter

### Parameters

- **name** (*str*) – The name of the parameter
- **default\_value** – The default value
- **cls** – The type of the parameter, which is used for conversion
- **description** (*str*) – A string describing the impact of this parameter. This description appears in the parameter help
- **hidden** (*bool*) – Whether the parameter is hidden in the description summary
- **extra** (*dict*) – Extra arguments that are stored with the parameter

**class HideParameter** (*name: str*)

Bases: `object`

a helper class that allows hiding parameters of the parent classes

**Parameters** **name** (*str*) – The name of the parameter

**class Parameter** (*name: str, default\_value=None, cls=<class 'object'>, description: str = "", hidden: bool = False, extra: typing.Optional[typing.Dict[str, typing.Any]] = None*)

Bases: `object`

class representing a single parameter

initialize a parameter

#### Parameters

- **name** (*str*) – The name of the parameter
- **default\_value** – The default value
- **cls** – The type of the parameter, which is used for conversion
- **description** (*str*) – A string describing the impact of this parameter. This description appears in the parameter help
- **hidden** (*bool*) – Whether the parameter is hidden in the description summary
- **extra** (*dict*) – Extra arguments that are stored with the parameter

**convert** (*value=None*)

converts a *value* into the correct type for this parameter. If *value* is not given, the default value is converted.

Note that this does not make a copy of the values, which could lead to unexpected effects where the default value is changed by an instance.

**Parameters** *value* – The value to convert

**Returns** The converted value, which is of type *self.cls*

**class** **Parameterized** (*parameters: Optional[Dict[str, Any]] = None*)

Bases: `object`

a mixin that manages the parameters of a class

initialize the parameters of the object

**Parameters** *parameters* (*dict*) – A dictionary of parameters to change the defaults. The allowed parameters can be obtained from `get_parameters()` or displayed by calling `show_parameters()`.

**get\_parameter\_default** (*name*)

return the default value for the parameter with *name*

**Parameters** *name* (*str*) – The parameter name

**classmethod** **get\_parameters** (*include\_hidden: bool = False, include\_deprecated: bool = False, sort: bool = True*) → `Dict[str, Parameter]`

return a dictionary of parameters that the class supports

#### Parameters

- **include\_hidden** (*bool*) – Include hidden parameters
- **include\_deprecated** (*bool*) – Include deprecated parameters
- **sort** (*bool*) – Return ordered dictionary with sorted keys

**Returns** a dictionary of instance of `Parameter` with their names as keys.

**Return type** `dict`

**parameters\_default**: `Sequence[Union[pde.tools.parameters.Parameter, pde.tools.parameters.HideParameter]] = []`

**show\_parameters** (*description: Optional[bool] = None, sort: bool = False, show\_hidden: bool = False, show\_deprecated: bool = False*)

show all parameters in human readable format

#### Parameters

- **description** (*bool*) – Flag determining whether the parameter description is shown. The default is to show the description only when we are in a jupyter notebook environment.
- **sort** (*bool*) – Flag determining whether the parameters are sorted
- **show\_hidden** (*bool*) – Flag determining whether hidden parameters are shown
- **show\_deprecated** (*bool*) – Flag determining whether deprecated parameters are shown
- **default\_value** (*bool*) – Flag determining whether the default values or the current values are shown

All flags default to *False*.

**get\_all\_parameters** (*data: str = 'name'*) → *Dict[str, Any]*

get a dictionary with all parameters of all registered classes

**Parameters** *data* (*str*) – Determines what data is returned. Possible values are ‘name’, ‘value’, or ‘description’, to return the respective information about the parameters.

**sphinx\_display\_parameters** (*app, what, name, obj, options, lines*)

helper function to display parameters in sphinx documentation

---

### Example

This function should be connected to the ‘autodoc-process-docstring’ event like so:

```
app.connect('autodoc-process-docstring', sphinx_display_parameters)
```

---

## 4.6.11 pde.tools.parse\_duration module

Parsing time durations from strings

This module provides a function that parses time durations from strings. It has been copied from the django software, which comes with the following notes:

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**parse\_duration** (*value: str*) → `datetime.timedelta`

Parse a duration string and return a `datetime.timedelta`.

**Parameters** **value** (*str*) – A time duration given as text. The preferred format for durations is ‘%d %H:%M:%S.%f’. This function also supports ISO 8601 representation and PostgreSQL’s day-time interval format.

**Returns** An instance representing the duration.

**Return type** `datetime.timedelta`

## 4.6.12 `pde.tools.plotting` module

Tools for plotting and controlling plot output using context managers

<code>add_scaled_colorbar</code>	add a vertical color bar to an image plot
<code>disable_interactive</code>	context manager disabling the interactive mode of matplotlib
<code>plot_on_axes</code>	decorator for a plot method or function that uses a single axes
<code>plot_on_figure</code>	decorator for a plot method or function that fills an entire figure
<code>PlotReference</code>	contains all information to update a plot element
<code>BasicPlottingContext</code>	basic plotting using just matplotlib
<code>JupyterPlottingContext</code>	plotting in a jupyter widget using the <i>inline</i> backend
<code>get_plotting_context</code>	returns a suitable plotting context
<code>napari_add_layers</code>	adds layers to a <code>napari</code> viewer

**class** `BasicPlottingContext` (*fig\_or\_ax=None, title: str = None, show: bool = True*)

Bases: `pde.tools.plotting.PlottingContextBase`

basic plotting using just matplotlib

### Parameters

- **fig\_or\_ax** – If axes are given, they are used. If a figure is given, it is set as active.
- **title** (*str*) – The shown in the plot
- **show** (*bool*) – Flag determining whether plots are actually shown

**class** `JupyterPlottingContext` (*title: str = None, show: bool = True*)

Bases: `pde.tools.plotting.PlottingContextBase`

plotting in a jupyter widget using the *inline* backend

### Parameters

- **title** (*str*) – The shown in the plot
- **show** (*bool*) – Flag determining whether plots are actually shown

**close** ()

close the plot

**supports\_update:** `bool = False`

flag indicating whether the context supports that plots can be updated with out redrawing the entire plot. The jupyter backend (*inline*) requires replotting of the entire figure, so an update is not supported.

**class PlotReference** (*ax, element: Any, parameters: Optional[Dict[str, Any]] = None*)

Bases: `object`

contains all information to update a plot element

#### Parameters

- **ax** (`matplotlib.axes.Axes`) – The axes of the element
- **element** (`matplotlib.artist.Artist`) – The actual element
- **parameters** (*dict*) – Parameters to recreate the plot element

**ax**

**element**

**parameters**

**class PlottingContextBase** (*title: str = None, show: bool = True*)

Bases: `object`

base class of the plotting contexts

---

#### Example

The context wraps calls to the `matplotlib.pyplot` interface:

```
context = PlottingContext()
with context:
    plt.plot(...)
    plt.xlabel(...)
```

---

#### Parameters

- **title** (*str*) – The shown in the plot
- **show** (*bool*) – Flag determining whether plots are actually shown

**close()**

close the plot

**supports\_update: bool = True**

flag indicating whether the context supports that plots can be updated with out redrawing the entire plot

**add\_scaled\_colorbar** (*axes\_image: matplotlib.cm.ScalarMappable, ax=None, aspect: float = 20, pad\_fraction: float = 0.5, label: str = "", \*\*kwargs*)

add a vertical color bar to an image plot

The height of the colorbar is now adjusted to the plot, so that the width determined by *aspect* is now given relative to the height. Moreover, the gap between the colorbar and the plot is now given in units of the fraction of the width by *pad\_fraction*.

Inspired by <https://stackoverflow.com/a/33505522/932593>

#### Parameters

- **axes\_image** (`matplotlib.cm.ScalarMappable`) – Mappable object, e.g., returned from `matplotlib.pyplot.imshow()`
- **ax** (`matplotlib.axes.Axes`) – The current figure axes from which space is taken for the colorbar. If omitted, the axes in which the *axes\_image* is shown is taken.

- **aspect** (*float*) – The target aspect ratio of the colorbar
- **pad\_fraction** (*float*) – Width of the gap between colorbar and image
- **label** (*str*) – Set a label for the colorbar
- **\*\*kwargs** – Additional parameters are passed to colorbar call

**Returns** The resulting Colorbar object

**Return type** `Colorbar`

**disable\_interactive()**

context manager disabling the interactive mode of matplotlib

This context manager restores the previous state after it is done. Details of the interactive mode are described in `matplotlib.interactive()`.

**get\_plotting\_context** (*context=None, title: str = None, show: bool = True*) → *PlottingContextBase*  
returns a suitable plotting context

**Parameters**

- **context** – An instance of *PlottingContextBase* or an instance of `matplotlib.axes.Axes` or `matplotlib.figure.Figure` to determine where the plotting will happen. If omitted, the context is determined automatically.
- **title** (*str*) – The title shown in the plot
- **show** (*bool*) – Determines whether the plot is shown while the simulation is running. If *False*, the files are created in the background.

**Returns** The plotting context

**Return type** *PlottingContextBase*

**in\_ipython()** → *bool*

try to detect whether we are in an ipython shell, e.g., a jupyter notebook

**napari\_add\_layers** (*viewer: napari.viewer.Viewer, layers\_data: Dict[str, dict]*)  
adds layers to a *napari* viewer

**Parameters**

- **viewer** (*napari.viewer.Viewer*) – The *napari* application
- **layers\_data** (*dict*) – Data for all layers that will be added.

**napari\_viewer** (*grid: GridBase, run: bool = None, close: bool = False, \*\*kwargs*) →  
*Generator[napari.viewer.Viewer, None, None]*

creates an *napari* viewer for interactive plotting

**Parameters**

- **grid** (*pde.grids.base.GridBase*) – The grid defining the space
- **run** (*bool*) – Whether to run the event loop of *napari*.
- **close** (*bool*) – Whether to close the viewer immediately (e.g. for testing)
- **\*\*kwargs** – Extra arguments are passed to *napari.Viewer*

**class nested\_plotting\_check**

Bases: *object*

context manager that checks whether it is the root plotting call

---

**Example**

The context manager can be used in plotting calls to check for nested plotting calls:

```

with nested_plotting_check() as is_outermost_plot_call:
    make_plot(...) # could potentially call other plotting methods
    if is_outermost_plot_call:
        plt.show()

```

---

**plot\_on\_axes** (*wrapped=None, update\_method=None*)  
decorator for a plot method or function that uses a single axes

This decorator adds typical options for creating plots that fill a single axes. These options are available via keyword arguments. To avoid redundancy in describing these options in the docstring, the placeholder *{PLOT\_ARGS}* can be added to the docstring of the wrapped function or method and will be replaced by the appropriate text. Note that the decorator can be used on both functions and methods.

---

**Example**

The following example illustrates how this decorator can be used to implement plotting for a given class. In particular, supplying the *update\_method* will allow efficient dynamical plotting:

```

class State:
    def __init__(self):
        self.data = np.arange(8)

    def _update_plot(self, reference):
        reference.element.set_ydata(self.data)

    @plot_on_axes(update_method='_update_plot')
    def plot(self, ax):
        line, = ax.plot(np.arange(8), self.data)
        return PlotReference(ax, line)

@plot_on_axes
def make_plot(ax):
    ax.plot(...)

```

---

When *update\_method* is absent, the method can still be used for plotting, but dynamic updating, e.g., by `pde.trackers.PlotTracker`, is not possible.

---

**Parameters**

- **wrapped** (*callable*) – Function to be wrapped
- **update\_method** (*callable or str*) – Method to call to update the plot. The argument of the new method will be the result of the initial call of the wrapped method.

**plot\_on\_figure** (*wrapped=None, update\_method=None*)  
decorator for a plot method or function that fills an entire figure

This decorator adds typical options for creating plots that fill an entire figure. This decorator adds typical options for creating plots that fill a single axes. These options are available via keyword arguments. To avoid redundancy in describing these options in the docstring, the placeholder *{PLOT\_ARGS}* can be added to the docstring of the

wrapped function or method and will be replaced by the appropriate text. Note that the decorator can be used on both functions and methods.

### Example

The following example illustrates how this decorator can be used to implement plotting for a given class. In particular, supplying the `update_method` will allow efficient dynamical plotting:

```
class State:
    def __init__(self):
        self.data = np.random.random((2, 8))

    def _update_plot(self, reference):
        ref1, ref2 = reference
        ref1.element.set_ydata(self.data[0])
        ref2.element.set_ydata(self.data[1])

    @plot_on_figure(update_method='_update_plot')
    def plot(self, fig):
        ax1, ax2 = fig.subplots(1, 2)
        l1, = ax1.plot(np.arange(8), self.data[0])
        l2, = ax2.plot(np.arange(8), self.data[1])
        return [PlotReference(ax1, l1), PlotReference(ax2, l2)]

@plot_on_figure
def make_plot(fig):
    ...
```

When `update_method` is not supplied, the method can still be used for plotting, but dynamic updating, e.g., by `pde.trackers.PlotTracker`, is not possible.

### Parameters

- **wrapped** (*callable*) – Function to be wrapped
- **update\_method** (*callable or str*) – Method to call to update the plot. The argument of the new method will be the result of the initial call of the wrapped method.

## 4.6.13 pde.tools.spectral module

Functions making use of spectral decompositions

<code>make_colored_noise</code>	Return a function creating an array of random values that obey
---------------------------------	--

**make\_colored\_noise** (*shape: Tuple[int, ...], dx=1.0, exponent: float = 0, scale: float = 1, rng: Optional[numpy.random.\_generator.Generator] = None*) → `Callable[[], numpy.ndarray]`  
 Return a function creating an array of random values that obey

$$\langle c(\mathbf{k})c(\mathbf{k}') \rangle = \Gamma^2 |\mathbf{k}|^\nu \delta(\mathbf{k} - \mathbf{k}')$$

in spectral space on a Cartesian grid. The special case  $\nu = 0$  corresponds to white noise.

### Parameters

- **shape** (*tuple of ints*) – Number of supports points in each spatial dimension. The number of the list defines the spatial dimension.
- **dx** (*float or list of floats*) – Discretization along each dimension. A uniform discretization in each direction can be indicated by a single number.
- **exponent** – Exponent  $\nu$  of the power spectrum
- **scale** – Scaling factor  $\Gamma$  determining noise strength
- **rng** (*Generator*) – Random number generator (default: `default_rng()`)

**Returns** a function returning a random realization

**Return type** callable

#### 4.6.14 `pde.tools.spherical` module

Module collecting functions for handling spherical geometry

The coordinate systems use the following convention for polar coordinates  $(r, \phi)$ , where  $r$  is the radial coordinate and  $\phi$  is the polar angle:

$$\begin{cases} x = r \cos(\phi) \\ y = r \sin(\phi) \end{cases} \quad \text{for } r \in [0, \infty] \text{ and } \phi \in [0, 2\pi)$$

Similarly, for spherical coordinates  $(r, \theta, \phi)$ , where  $r$  is the radial coordinate,  $\theta$  is the azimuthal angle, and  $\phi$  is the polar angle, we use

$$\begin{cases} x = r \sin(\theta) \cos(\phi) \\ y = r \sin(\theta) \sin(\phi) \\ z = r \cos(\theta) \end{cases} \quad \text{for } r \in [0, \infty], \theta \in [0, \pi], \text{ and } \phi \in [0, 2\pi)$$

The module also provides functions for handling spherical harmonics. These spherical harmonics are described by the degree  $l$  and the order  $m$  or, alternatively, by the mode  $k$ . The relation between these values is

$$k = l(l + 1) + m$$

and

$$\begin{aligned} l &= \text{floor}(\sqrt{k}) \\ m &= k - l(l + 1) \end{aligned}$$

We will use these indices interchangeably, although the mode  $k$  is preferred internally. Note that we also consider axisymmetric spherical harmonics, where the order is always zero and the degree  $l$  and the mode  $k$  are thus identical.

<code>radius_from_volume</code>	Return the radius of a sphere with a given volume
<code>volume_from_radius</code>	Return the volume of a sphere with a given radius
<code>surface_from_radius</code>	Return the surface area of a sphere with a given radius
<code>spherical_index_k</code>	returns the mode $k$ from the degree $degree$ and order $order$
<code>spherical_index_lm</code>	returns the degree $l$ and the order $m$ from the mode $k$
<code>spherical_index_count</code>	return the number of modes for all indices $\leq l$
<code>spherical_index_count_optimal</code>	checks whether the modes captures all orders for maximal degree
<code>spherical_harmonic_symmetric</code>	axisymmetric spherical harmonics with degree $degree$ , so $m=0$ .
<code>spherical_harmonic_real</code>	real spherical harmonics of degree $l$ and order $m$
<code>spherical_harmonic_real_k</code>	real spherical harmonics described by mode $k$

**class** `PointsOnSphere` (*points*)

Bases: `object`

class representing points on an n-dimensional unit sphere

**Parameters** `points` (`ndarray`) – The list of points on the unit sphere

**get\_area\_weights** (*balance\_axes*: `bool` = `True`)

return the weight of each point associated with the unit cell size

**Parameters** `balance_axes` (`bool`) – Flag determining whether the weights should be chosen such that the weighted average of all points is the zero vector

**Returns** The weight associated with each point

**Return type** `ndarray`

**get\_distance\_matrix** ()

calculate the (spherical) distances between each point

**Returns** the distance of each point to each other

**Return type** `ndarray`

**get\_mean\_separation** () → `float`

float: calculates the mean distance to the nearest neighbor

**classmethod** `make_uniform` (*dim*: `int`, *num\_points*: `int` = `None`)

create uniformly distributed points on a sphere

**Parameters**

- `dim` (`int`) – The dimension of space
- `num_points` (`int`, *optional*) – The number of points to generate. Note that for one-dimensional spheres (intervals), only exactly two points can be generated

**write\_to\_xyz** (*path*: `str`, *comment*: `str` = `"`, *symbol*: `str` = `'S'`)

write the point coordinates to a xyz file

**Parameters**

- `path` (`str`) – location of the file where data is written
- `comment` (`str`, *optional*) – comment that is written to the second line
- `symbol` (`str`, *optional*) – denotes the symbol used for the atoms

**get\_spherical\_polygon\_area** (*vertices*: `numpy.ndarray`, *radius*: `float` = `1`) → `float`

Calculate the surface area of a polygon on the surface of a sphere. Based on equation provided here: <http://mathworld.wolfram.com/LHuilliersTheorem.html> Decompose into triangles, calculate excess for each

Adapted from <https://github.com/tylerjereddy/spherical-SA-docker-demo> Licensed under MIT License (see copy in root of this project)

**Parameters**

- `vertices` (`ndarray`) – List of vertices (using Cartesian coordinates) that describe the corners of the polygon. The vertices need to be oriented.
- `radius` (`float`) – Radius of the sphere

**haversine\_distance** (*point1*: `numpy.ndarray`, *point2*: `numpy.ndarray`) → `numpy.ndarray`

Calculate the haversine-based distance between two points on the surface of a sphere. Should be more accurate than the arc cosine strategy. See, for example: [https://en.wikipedia.org/wiki/Haversine\\_formula](https://en.wikipedia.org/wiki/Haversine_formula)

Adapted from <https://github.com/tylerjereddy/spherical-SA-docker-demo> Licensed under MIT License (see copy in root of this project)

#### Parameters

- **point1** (`ndarray`) – First point(s) on the sphere (given in Cartesian coordinates)
- **point2** (`ndarray`) – Second point on the sphere Second point(s) on the sphere (given in Cartesian coordinates)

**Returns** The distances between the points

**Return type** `ndarray`

**make\_radius\_from\_volume\_compiled** (*dim: int*) → `Callable[[TNumArr], TNumArr]`

Return a function calculating the radius of a sphere with a given volume

**Parameters** **dim** (*int*) – Dimension of the space

**Returns** A function that takes a volume and returns the radius

**Return type** function

**make\_surface\_from\_radius\_compiled** (*dim: int*) → `Callable[[TNumArr], TNumArr]`

Return a function calculating the surface area of a sphere

**Parameters** **dim** (*int*) – Dimension of the space

**Returns** A function that takes a radius and returns the surface area

**Return type** function

**make\_volume\_from\_radius\_compiled** (*dim: int*) → `Callable[[TNumArr], TNumArr]`

Return a function calculating the volume of a sphere with a given radius

**Parameters** **dim** (*int*) – Dimension of the space

**Returns** A function that takes a radius and returns the volume

**Return type** function

**points\_cartesian\_to\_spherical** (*points: numpy.ndarray*) → `numpy.ndarray`

Convert points from Cartesian to spherical coordinates

**Parameters** **points** (`ndarray`) – Points in Cartesian coordinates

**Returns** Points ( $r$ ,  $\theta$ ,  $\varphi$ ) in spherical coordinates

**Return type** `ndarray`

**points\_spherical\_to\_cartesian** (*points: numpy.ndarray*) → `numpy.ndarray`

Convert points from spherical to Cartesian coordinates

**Parameters** **points** (`ndarray`) – Points in spherical coordinates ( $r$ ,  $\theta$ ,  $\varphi$ )

**Returns** Points in Cartesian coordinates

**Return type** `ndarray`

**radius\_from\_surface** (*surface: TNumArr, dim: int*) → `TNumArr`

Return the radius of a sphere with a given surface area

#### Parameters

- **surface** (float or `ndarray`) – Surface area of the sphere
- **dim** (*int*) – Dimension of the space

**Returns** Radius of the sphere

**Return type** float or `ndarray`

**radius\_from\_volume** (*volume: TNumArr, dim: int*)  $\rightarrow$  TNumArr

Return the radius of a sphere with a given volume

**Parameters**

- **volume** (float or `ndarray`) – Volume of the sphere
- **dim** (*int*) – Dimension of the space

**Returns** Radius of the sphere

**Return type** float or `ndarray`

**spherical\_harmonic\_real** (*degree: int, order: int,  $\theta$ : float,  $\varphi$ : float*)  $\rightarrow$  float

real spherical harmonics of degree  $l$  and order  $m$

**Parameters**

- **degree** (*int*) – Degree  $l$  of the spherical harmonics
- **order** (*int*) – Order  $m$  of the spherical harmonics
- **$\theta$**  (*float*) – Azimuthal angle (in  $[0, \pi]$ ) at which the spherical harmonics is evaluated.
- **$\varphi$**  (*float*) – Polar angle (in  $[0, 2\pi]$ ) at which the spherical harmonics is evaluated.

**Returns** The value of the spherical harmonics

**Return type** float

**spherical\_harmonic\_real\_k** (*k: int,  $\theta$ : float,  $\varphi$ : float*)  $\rightarrow$  float

real spherical harmonics described by mode  $k$

**Parameters**

- **k** (*int*) – Combined index determining the degree and order of the spherical harmonics
- **$\theta$**  (*float*) – Azimuthal angle (in  $[0, \pi]$ ) at which the spherical harmonics is evaluated.
- **$\varphi$**  (*float*) – Polar angle (in  $[0, 2\pi]$ ) at which the spherical harmonics is evaluated.

**Returns** The value of the spherical harmonics

**Return type** float

**spherical\_harmonic\_symmetric** (*degree: int,  $\theta$ : float*)  $\rightarrow$  float

axisymmetric spherical harmonics with degree *degree*, so  $m=0$ .

**Parameters**

- **degree** (*int*) – Degree of the spherical harmonics
- **$\theta$**  (*float*) – Azimuthal angle at which the spherical harmonics is evaluated (in  $[0, \pi]$ )

**Returns** The value of the spherical harmonics

**Return type** float

**spherical\_index\_count** (*l: int*)  $\rightarrow$  int

return the number of modes for all indices  $\leq l$

The returned value is one less than the maximal mode  $k$  required.

**Parameters** **l** (*int*) – Maximal degree of the spherical harmonics

**Returns** The number of modes

**Return type** int

**spherical\_index\_count\_optimal** (*k\_count*: *int*) → *bool*  
 checks whether the modes captures all orders for maximal degree

**Parameters** *k\_count* (*int*) – The number of modes considered

**spherical\_index\_k** (*degree*: *int*, *order*: *int* = 0) → *int*  
 returns the mode *k* from the degree *degree* and order *order*

**Parameters**

- **degree** (*int*) – Degree of the spherical harmonics
- **order** (*int*) – Order of the spherical harmonics

**Raises** **ValueError** – if *order* < -*degree* or *order* > *degree*

**Returns** a combined index *k*

**Return type** *int*

**spherical\_index\_lm** (*k*: *int*) → *Tuple*[*int*, *int*]  
 returns the degree *l* and the order *m* from the mode *k*

**Parameters** *k* (*int*) – The combined index for the spherical harmonics

**Returns** The degree *l* and order *m* of the spherical harmonics associated with the combined index

**Return type** *tuple*

**surface\_from\_radius** (*radius*: *TNumArr*, *dim*: *int*) → *TNumArr*  
 Return the surface area of a sphere with a given radius

**Parameters**

- **radius** (float or *ndarray*) – Radius of the sphere
- **dim** (*int*) – Dimension of the space

**Returns** Surface area of the sphere

**Return type** float or *ndarray*

**volume\_from\_radius** (*radius*: *TNumArr*, *dim*: *int*) → *TNumArr*  
 Return the volume of a sphere with a given radius

**Parameters**

- **radius** (float or *ndarray*) – Radius of the sphere
- **dim** (*int*) – Dimension of the space

**Returns** Volume of the sphere

**Return type** float or *ndarray*

## 4.6.15 pde.tools.typing module

Provides support for mypy type checking of the package

## 4.7 pde.trackers package

Classes for tracking simulation results in controlled intervals

Trackers are classes that periodically receive the state of the simulation to analyze, store, or output it. The trackers defined in this module are:

<i>CallbackTracker</i>	Tracker calling a function periodically
<i>ProgressTracker</i>	Tracker showing the progress of the simulation
<i>PrintTracker</i>	Tracker printing data to a stream (default: stdout)
<i>PlotTracker</i>	Tracker plotting data on screen, to files, or writes a movie
<i>LivePlotTracker</i>	PlotTracker with defaults for live plotting
<i>DataTracker</i>	Tracker storing custom data obtained by calling a function
<i>SteadyStateTracker</i>	Tracker interrupting the simulation once steady state is reached
<i>RuntimeTracker</i>	Tracker interrupting the simulation once a duration has passed
<i>ConsistencyTracker</i>	Tracker interrupting the simulation when the state is not finite
<i>InteractivePlotTracker</i>	Tracker showing the state interactively in napari

Some trackers can also be referenced by name for convenience when using them in simulations. The list of supported names is returned by `get_named_trackers()`.

Multiple trackers can be collected in a *TrackerCollection*, which provides methods for handling them efficiently. Moreover, custom trackers can be implemented by deriving from *TrackerBase*. Note that trackers generally receive a view into the current state, implying that they can adjust the state by modifying it in-place. Moreover, trackers can interrupt the simulation by raising the special exception *StopIteration*.

For each tracker, the interval at which it is called can be decided using one of the following classes:

<i>ConstantIntervals</i>	class representing equidistantly spaced time intervals
<i>LogarithmicIntervals</i>	class representing logarithmically spaced time intervals
<i>RealtimeIntervals</i>	class representing time intervals spaced equidistantly in real time

### 4.7.1 pde.trackers.base module

Base classes for trackers

**exception FinishedSimulation**

Bases: *StopIteration*

exception for signaling that simulation finished successfully

**class TrackerBase** (*interval: Union[ConstantIntervals, float, int, str] = 1*)

Bases: *object*

base class for implementing trackers

**Parameters** **interval** – Determines how often the tracker interrupts the simulation. Simple numbers are interpreted as durations measured in the simulation time variable. Alternatively, a string using the format ‘hh:mm:ss’ can be used to give durations in real time. Finally, instances of the classes defined in *intervals* can be given for more control.

**finalize** (*info*: *Optional*[*Dict*[*str*, *Any*]] = *None*) → *None*

finalize the tracker, supplying additional information

**Parameters** *info* (*dict*) – Extra information from the simulation

**classmethod from\_data** (*data*: *Union*[*TrackerBase*, *str*], *\*\*kwargs*) → *TrackerBase*

create tracker class from given data

**Parameters** *data* (*str* or *TrackerBase*) – Data describing the tracker

**Returns** An instance representing the tracker

**Return type** *TrackerBase*

**abstract handle** (*field*: *FieldBase*, *t*: *float*) → *None*

handle data supplied to this tracker

**Parameters**

- **field** (*FieldBase*) – The current state of the simulation
- **t** (*float*) – The associated time

**initialize** (*field*: *FieldBase*, *info*: *Optional*[*Dict*[*str*, *Any*]] = *None*) → *float*

initialize the tracker with information about the simulation

**Parameters**

- **field** (*FieldBase*) – An example of the data that will be analyzed by the tracker
- **info** (*dict*) – Extra information from the simulation

**Returns** The first time the tracker needs to handle data

**Return type** *float*

**class TrackerCollection** (*trackers*: *Optional*[*List*[*TrackerBase*]] = *None*)

Bases: *object*

List of trackers providing methods to handle them efficiently

**trackers**

List of the trackers in the collection

**Type** *list*

**Parameters** *trackers* – List of trackers that are to be handled.

**finalize** (*info*: *Optional*[*Dict*[*str*, *Any*]] = *None*) → *None*

finalize the tracker, supplying additional information

**Parameters** *info* (*dict*) – Extra information from the simulation

**classmethod from\_data** (*data*: *Optional*[*Union*[*Sequence*[*Union*[*TrackerBase*, *str*]], *TrackerBase*, *str*]], *\*\*kwargs*) → *TrackerCollection*

create tracker collection from given data

**Parameters** *data* – Data describing the tracker collection

**Returns** An instance representing the tracker collection

**Return type** *TrackerCollection*

**handle** (*state*: *FieldBase*, *t*: *float*, *atol*: *float* = *1e-08*) → *float*

handle all trackers

**Parameters**

- **state** (`FieldBase`) – The current state of the simulation
- **t** (`float`) – The associated time
- **atol** (`float`) – An absolute tolerance that is used to determine whether a tracker should be called now or whether the simulation should be carried on more timesteps. This is basically used to predict the next time to decide which one is closer.

**Returns** The next time the simulation needs to be interrupted to handle a tracker.

**Return type** `float`

**initialize** (`field`: `FieldBase`, `info`: `Optional[Dict[str, Any]] = None`) → `float`  
initialize the tracker with information about the simulation

**Parameters**

- **field** (`FieldBase`) – An example of the data that will be analyzed by the tracker
- **info** (`dict`) – Extra information from the simulation

**Returns** The first time the tracker needs to handle data

**Return type** `float`

**time\_next\_action**: `float`  
The time of the next interrupt of the simulation

**Type** `float`

**tracker\_action\_times**: `List[float]`  
Times at which the trackers need to be handled next

**Type** `list`

**get\_named\_trackers** () → `Dict[str, Type[TrackerBase]]`  
returns all named trackers

**Returns** a mapping of names to the actual tracker classes.

**Return type** `dict`

## 4.7.2 `pde.trackers.interactive` module

Special module for defining an interactive tracker that uses `napari` to display fields

**class InteractivePlotTracker** (`interval`: `Union[ConstantIntervals, float, int, str] = '0:01'`, `close`: `bool` = `True`, `show_time`: `bool` = `False`)

Bases: `pde.trackers.base.TrackerBase`

Tracker showing the state interactively in `napari`

---

**Note:** The interactive tracker uses the python `multiprocessing` module to run `napari` externally. The multiprocessing module has limitations on some platforms, which requires some care when writing your own programs. In particular, the main method needs to be safe-guarded so that the main module can be imported again after spawning a new process. An established pattern that works is to introduce a function `main` in your code, which you call using the following pattern

```
def main():  
    # here goes your main code
```

(continues on next page)

(continued from previous page)

```
if __name__ == "__main__":
    main()
```

The last two lines ensure that the *main* function is only called when the module is run initially and not again when it is re-imported.

### Parameters

- **interval** – Determines how often the tracker interrupts the simulation. Simple numbers are interpreted as durations measured in the simulation time variable. Alternatively, a string using the format ‘hh:mm:ss’ can be used to give durations in real time. Finally, instances of the classes defined in *intervals* can be given for more control.
- **close** (*bool*) – Flag indicating whether the napari window is closed automatically at the end of the simulation. If *False*, the tracker blocks when *finalize* is called until the user closes napari manually.
- **show\_time** (*bool*) – Whether to indicate the time

**finalize** (*info*: *Optional*[*Dict*[*str*, *Any*]] = *None*) → *None*  
finalize the tracker, supplying additional information

**Parameters** *info* (*dict*) – Extra information from the simulation

**handle** (*state*: *FieldBase*, *t*: *float*) → *None*  
handle data supplied to this tracker

### Parameters

- **state** (*FieldBase*) – The current state of the simulation
- **t** (*float*) – The associated time

**initialize** (*state*: *FieldBase*, *info*: *Optional*[*Dict*[*str*, *Any*]] = *None*) → *float*  
initialize the tracker with information about the simulation

### Parameters

- **state** (*FieldBase*) – An example of the data that will be analyzed by the tracker
- **info** (*dict*) – Extra information from the simulation

**Returns** The first time the tracker needs to handle data

**Return type** *float*

**name** = 'interactive'

**class NapariViewer** (*state*: *FieldBase*, *t\_initial*: *float* = *None*)  
Bases: *object*

allows viewing and updating data in a separate napari process

### Parameters

- **state** (*pde.fields.base.FieldBase*) – The initial state to be shown
- **t\_initial** (*float*) – The initial time. If *None*, no time will be shown.

**close** (*force*: *bool* = *True*)  
closes the napari process

**Parameters** **force** (*bool*) – Whether to force closing of the napari program. If this is *False*, this method blocks until the user closes napari manually.

**update** (*state*: *FieldBase*, *t*: *float*)  
update the state in the napari viewer

**Parameters**

- **state** (*pde.fields.base.FieldBase*) – The new state
- **t** (*float*) – Current time

**napari\_process** (*data\_channel*: *multiprocessing.context.BaseContext.Queue*, *initial\_data*: *Dict[str, Dict[str, Any]]*, *t\_initial*: *float = None*, *viewer\_args*: *Optional[Dict[str, Any]] = None*)  
*multiprocessing.Process* running *napari*

**Parameters**

- **data\_channel** (*multiprocessing.Queue*) – queue instance to receive data to view
- **initial\_data** (*dict*) – Initial data to be shown by napari. The layers are named according to the keys in the dictionary. The associated value needs to be a tuple, where the first item is a string indicating the type of the layer and the second carries the associated data
- **t\_initial** (*float*) – Initial time
- **viewer\_args** (*dict*) – Additional arguments passed to the napari viewer

### 4.7.3 pde.trackers.intervals module

Module defining classes for time intervals for trackers

The provided interval classes are:

<i>ConstantIntervals</i>	class representing equidistantly spaced time intervals
<i>LogarithmicIntervals</i>	class representing logarithmically spaced time intervals
<i>RealtimeIntervals</i>	class representing time intervals spaced equidistantly in real time

**class ConstantIntervals** (*dt*: *float = 1*, *t\_start*: *float = None*)

Bases: *object*

class representing equidistantly spaced time intervals

**Parameters**

- **dt** (*float*) – The duration between subsequent intervals. This is measured in simulation time units.
- **t\_start** (*float*, *optional*) – The time after which the tracker becomes active. If omitted, the tracker starts recording right away. This argument can be used for an initial equilibration period during which no data is recorded.

**copy** ()  
return a copy of this instance

**next** (*t*: *float*) → *float*  
computes the next time point based on the current time *t*

**Parameters** **t** (*float*) – The current time point of the simulation

**IntervalType**

alias of `pde.trackers.intervals.ConstantIntervals`

**class** `LogarithmicIntervals` (*dt\_initial*: `float` = 1, *factor*: `float` = 1, *t\_start*: `float` = None)

Bases: `pde.trackers.intervals.ConstantIntervals`

class representing logarithmically spaced time intervals

**Parameters**

- **dt\_initial** (`float`) – The initial duration between subsequent intervals. This is measured in simulation time units.
- **factor** (`float`) – The factor by which the time between intervals is increased every time. Values larger than one lead to time intervals that are increasingly further apart.
- **t\_start** (`float`, *optional*) – The time after which the tracker becomes active. If omitted, the tracker starts recording right away. This argument can be used for an initial equilibration period during which no data is recorded.

**next** (*t*: `float`) → `float`

computes the next time point based on the current time *t*

**Parameters** *t* (`float`) – The current time point of the simulation

**class** `RealtimeIntervals` (*duration*: `Union`[`float`, `str`], *dt\_initial*: `float` = 0.01)

Bases: `pde.trackers.intervals.ConstantIntervals`

class representing time intervals spaced equidistantly in real time

This spacing is only achieved approximately and depends on the initial value set by *dt\_initial* and the actual variation in computation speed.

**Parameters**

- **duration** (`float` or `str`) – The duration (in realtime seconds) that the intervals should be spaced apart. The duration can also be given as a string, which is then parsed using the function `parse_duration()`.
- **dt\_initial** (`float`) – The initial duration between subsequent intervals. This is measured in simulation time units.

**next** (*t*: `float`) → `float`

computes the next time point based on the current time *t*

**Parameters** *t* (`float`) – The current time point of the simulation

**get\_interval** (*interval*: `Union`[`ConstantIntervals`, `float`, `int`, `str`]) → `ConstantIntervals`

create `IntervalType` from various data formats

If *interval* is of type `IntervalType` it is simply returned

## 4.7.4 pde.trackers.trackers module

Module defining classes for tracking results from simulations.

The trackers defined in this module are:

<code>CallbackTracker</code>	Tracker calling a function periodically
<code>ProgressTracker</code>	Tracker showing the progress of the simulation
<code>PrintTracker</code>	Tracker printing data to a stream (default: stdout)

continues on next page

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<code>PlotTracker</code>	Tracker plotting data on screen, to files, or writes a movie
<code>LivePlotTracker</code>	<code>PlotTracker</code> with defaults for live plotting
<code>DataTracker</code>	Tracker storing custom data obtained by calling a function
<code>SteadyStateTracker</code>	Tracker interrupting the simulation once steady state is reached
<code>RuntimeTracker</code>	Tracker interrupting the simulation once a duration has passed
<code>ConsistencyTracker</code>	Tracker interrupting the simulation when the state is not finite
<code>MaterialConservationTracker</code>	Tracking interrupting the simulation when material conservation is broken

**class** `CallbackTracker` (*func*: `Callable`, *interval*: `Union[ConstantIntervals, float, int, str]` = 1)

Bases: `pde.trackers.base.TrackerBase`

Tracker calling a function periodically

#### Parameters

- **func** – The function to call periodically. The function signature should be *(state)* or *(state, time)*, where *state* contains the current state as an instance of `FieldBase` and *time* is a float value indicating the current time. Note that only a view of the state is supplied, implying that a copy needs to be made if the data should be stored. The function can thus adjust the state by modifying it in-place and it can even interrupt the simulation by raising the special exception `StopIteration`.
- **interval** – Determines how often the tracker interrupts the simulation. Simple numbers are interpreted as durations measured in the simulation time variable. Alternatively, a string using the format ‘hh:mm:ss’ can be used to give durations in real time. Finally, instances of the classes defined in `intervals` can be given for more control.

**handle** (*field*: `FieldBase`, *t*: `float`) → `None`

handle data supplied to this tracker

#### Parameters

- **field** (`FieldBase`) – The current state of the simulation
- **t** (`float`) – The associated time

**class** `ConsistencyTracker` (*interval*: `Optional[Union[ConstantIntervals, float, int, str]]` = `None`)

Bases: `pde.trackers.base.TrackerBase`

Tracker interrupting the simulation when the state is not finite

**Parameters** **interval** – Determines how often the tracker interrupts the simulation. Simple numbers are interpreted as durations measured in the simulation time variable. Alternatively, a string using the format ‘hh:mm:ss’ can be used to give durations in real time. Finally, instances of the classes defined in `intervals` can be given for more control. The default value `None` checks for consistency approximately every (real) second.

**handle** (*field*: `FieldBase`, *t*: `float`) → `None`

handle data supplied to this tracker

#### Parameters

- **field** (`FieldBase`) – The current state of the simulation
- **t** (`float`) – The associated time

**name** = ‘consistency’

**class DataTracker** (*func: Callable, interval: Union[ConstantIntervals, float, int, str] = 1, filename: str = None*)  
 Bases: `pde.trackers.trackers.CallbackTracker`

Tracker storing custom data obtained by calling a function

**times**

The time points at which the data is stored

Type `list`

**data**

The actually stored data, which is a list of the objects returned by the callback function.

Type `list`

#### Parameters

- **func** – The function to call periodically. The function signature should be *(state)* or *(state, time)*, where *state* contains the current state as an instance of `FieldBase` and *time* is a float value indicating the current time. Note that only a view of the state is supplied, implying that a copy needs to be made if the data should be stored. Typical return values of the function are either a single number, a numpy array, a list of number, or a dictionary to return multiple numbers with assigned labels.
- **interval** – Determines how often the tracker interrupts the simulation. Simple numbers are interpreted as durations measured in the simulation time variable. Alternatively, a string using the format ‘hh:mm:ss’ can be used to give durations in real time. Finally, instances of the classes defined in `intervals` can be given for more control.
- **filename** (*str*) – A path to a file to which the data is written at the end of the tracking. The data format will be determined by the extension of the filename. ‘pickle’ indicates a python pickle file storing a tuple (*self.times*, *self.data*), whereas any other data format requires pandas.

**property dataframe:** `pandas.DataFrame`

the data in a dataframe

If *func* returns a dictionary, the keys are used as column names. Otherwise, the returned data is enumerated starting with ‘0’. In any case the time point at which the data was recorded is stored in the column ‘time’.

Type `pandas.DataFrame`

**finalize** (*info: Optional[Dict[str, Any]] = None*) → `None`

finalize the tracker, supplying additional information

Parameters **info** (*dict*) – Extra information from the simulation

**handle** (*field: FieldBase, t: float*) → `None`

handle data supplied to this tracker

#### Parameters

- **field** (`FieldBase`) – The current state of the simulation
- **t** (`float`) – The associated time

**to\_file** (*filename: str, \*\*kwargs*)

store data in a file

The extension of the filename determines what format is being used. For instance, ‘pickle’ indicates a python pickle file storing a tuple (*self.times*, *self.data*), whereas any other data format requires pandas. Supported formats include ‘csv’, ‘json’.

### Parameters

- **filename** (*str*) – Path where the data is stored
- **\*\*kwargs** – Additional parameters may be supported for some formats

```
class LivePlotTracker (interval: Union[ConstantIntervals, float, int, str] = '0:03', *, show: bool = True,
                        max_fps: float = 2, **kwargs)
```

Bases: `pde.trackers.trackers.PlotTracker`

PlotTracker with defaults for live plotting

The only difference to `PlotTracker` are the changed default values, where output is by default shown on screen and the *interval* is set something more suitable for interactive plotting. In particular, this tracker can be enabled by simply listing 'plot' as a tracker.

### Parameters

- **interval** – Determines how often the tracker interrupts the simulation. Simple numbers are interpreted as durations measured in the simulation time variable. Alternatively, a string using the format 'hh:mm:ss' can be used to give durations in real time. Finally, instances of the classes defined in *intervals* can be given for more control.
- **title** (*str*) – Text to show in the title. The current time point will be appended to this text, so include a space for optimal results.
- **output\_file** (*str*, *optional*) – Specifies a single image file, which is updated periodically, so that the progress can be monitored (e.g. on a compute cluster)
- **output\_folder** (*str*, *optional*) – Specifies a folder to which all images are written. The files will have names with increasing numbers.
- **movie\_file** (*str*, *optional*) – Specifies a filename to which a movie of all the frames is written after the simulation.
- **show** (*bool*, *optional*) – Determines whether the plot is shown while the simulation is running. If *False*, the files are created in the background. This option can slow down a simulation severely.
- **max\_fps** (*float*) – Determines the maximal rate (frames per second) at which the plots are updated. Some plots are skipped if the tracker receives data at a higher rate. A larger value (e.g., *np.inf*) can be used to ensure every frame is drawn, which might penalizes the overall performance.
- **plot\_args** (*dict*) – Extra arguments supplied to the plot call. For example, this can be used to specify axes ranges when a single panel is shown. For instance, the value `{ 'ax_style': { 'ylim': (0, 1) } }` enforces the y-axis to lie between 0 and 1.

**name** = 'plot'

```
class MaterialConservationTracker (interval: Union[ConstantIntervals, float, int, str] = 1, atol: float =
                                   0.0001, rtol: float = 0.0001)
```

Bases: `pde.trackers.base.TrackerBase`

Tracking interrupting the simulation when material conservation is broken

### Parameters

- **interval** – Determines how often the tracker interrupts the simulation. Simple numbers are interpreted as durations measured in the simulation time variable. Alternatively, a string using the format 'hh:mm:ss' can be used to give durations in real time. Finally, instances of the classes defined in *intervals* can be given for more control.
- **atol** (*float*) – Absolute tolerance for amount deviations

- **rtol** (*float*) – Relative tolerance for amount deviations

**handle** (*field*: *FieldBase*, *t*: *float*) → *None*  
 handle data supplied to this tracker

#### Parameters

- **field** (*FieldBase*) – The current state of the simulation
- **t** (*float*) – The associated time

**initialize** (*field*: *FieldBase*, *info*: *Optional[Dict[str, Any]]* = *None*) → *float*

#### Parameters

- **field** (*FieldBase*) – An example of the data that will be analyzed by the tracker
- **info** (*dict*) – Extra information from the simulation

**Returns** The first time the tracker needs to handle data

**Return type** *float*

**name** = 'material\_conservation'

```
class PlotTracker (interval: Union[ConstantIntervals, float, int, str] = 1, *, title: Union[str, Callable] = 'Time:
{time:g}', output_file: str = None, movie: Union[str, pathlib.Path, Movie] = None, show: bool
= None, max_fps: float = inf, plot_args: Dict[str, Any] = None)
```

Bases: *pde.trackers.base.TrackerBase*

Tracker plotting data on screen, to files, or writes a movie

This tracker can be used to create movies from simulations or to simply update a single image file on the fly (i.e. to monitor simulations running on a cluster). The default values of this tracker are chosen with regular output to a file in mind.

#### Parameters

- **interval** – Determines how often the tracker interrupts the simulation. Simple numbers are interpreted as durations measured in the simulation time variable. Alternatively, a string using the format 'hh:mm:ss' can be used to give durations in real time. Finally, instances of the classes defined in *intervals* can be given for more control.
- **title** (*str* or *callable*) – Title text of the figure. If this is a string, it is shown with a potential placeholder named *time* being replaced by the current simulation time. Conversely, if *title* is a function, it is called with the current state and the time as arguments. This function is expected to return a string.
- **output\_file** (*str*, *optional*) – Specifies a single image file, which is updated periodically, so that the progress can be monitored (e.g. on a compute cluster)
- **movie** (*str* or *Movie*) – Create a movie. If a filename is given, all frames are written to this file in the format deduced from the extension after the simulation ran. If a *Movie* is supplied, frames are appended to the instance.
- **show** (*bool*, *optional*) – Determines whether the plot is shown while the simulation is running. If *False*, the files are created in the background. This option can slow down a simulation severely. For the default value of *None*, the images are only shown if neither *output\_file* nor *movie* is set.
- **max\_fps** (*float*) – Determines the maximal rate (frames per second) at which the plots are updated in real time during the simulation. Some plots are skipped if the tracker receives

data at a higher rate. A larger value (e.g., `np.inf`) can be used to ensure every frame is drawn, which might penalizes the overall performance.

- **plot\_args** (*dict*) – Extra arguments supplied to the plot call. For example, this can be used to specify axes ranges when a single panel is shown. For instance, the value `{'ax_style': {'ylim': (0, 1)}}` enforces the y-axis to lie between 0 and 1.

---

**Note:** If an instance of `Movie` is given as the `movie` argument, it can happen that the movie is not written to the file when the simulation ends. This is because, the movie could still be extended by appending frames. To write the movie to a file call its `save()` method. Beside adding frames before and after the simulation, an explicit movie object can also be used to adjust the output, e.g., by setting the `dpi` argument or the `frame_rate`.

---

**finalize** (*info*: *Optional*[*Dict*[*str*, *Any*]] = *None*) → *None*

finalize the tracker, supplying additional information

**Parameters** **info** (*dict*) – Extra information from the simulation

**handle** (*state*: *FieldBase*, *t*: *float*) → *None*

handle data supplied to this tracker

**Parameters**

- **state** (*FieldBase*) – The current state of the simulation
- **t** (*float*) – The associated time

**initialize** (*state*: *FieldBase*, *info*: *Optional*[*Dict*[*str*, *Any*]] = *None*) → *float*

initialize the tracker with information about the simulation

**Parameters**

- **state** (*FieldBase*) – An example of the data that will be analyzed by the tracker
- **info** (*dict*) – Extra information from the simulation

**Returns** The first time the tracker needs to handle data

**Return type** *float*

**class PrintTracker** (*interval*: *typing.Union*[*ConstantIntervals*, *float*, *int*, *str*] = 1, *stream*: *typing.IO*[*str*] = *<\_io.TextIOWrapper name='<stdout>' mode='w' encoding='UTF-8'>*)

Bases: `pde.trackers.base.TrackerBase`

Tracker printing data to a stream (default: stdout)

**Parameters**

- **interval** – Determines how often the tracker interrupts the simulation. Simple numbers are interpreted as durations measured in the simulation time variable. Alternatively, a string using the format 'hh:mm:ss' can be used to give durations in real time. Finally, instances of the classes defined in `intervals` can be given for more control.
- **stream** – The stream used for printing

**handle** (*field*: *FieldBase*, *t*: *float*) → *None*

handle data supplied to this tracker

**Parameters**

- **field** (*FieldBase*) – The current state of the simulation
- **t** (*float*) – The associated time

**name** = 'print'

```
class ProgressTracker (interval: Optional[Union[ConstantIntervals, float, int, str]] = None, ndigits: int = 5,  
                      leave: bool = True)
```

Bases: `pde.trackers.base.TrackerBase`

Tracker showing the progress of the simulation

#### Parameters

- **interval** – Determines how often the tracker interrupts the simulation. Simple numbers are interpreted as durations measured in the simulation time variable. Alternatively, a string using the format ‘hh:mm:ss’ can be used to give durations in real time. Finally, instances of the classes defined in `intervals` can be given for more control. The default value `None` updates the progress bar approximately every (real) second.
- **ndigits** (`int`) – The number of digits after the decimal point that are shown maximally.
- **leave** (`bool`) – Whether to leave the progress bar after the simulation has finished (default: `True`)

```
finalize (info: Optional[Dict[str, Any]] = None) → None  
finalize the tracker, supplying additional information
```

**Parameters** **info** (`dict`) – Extra information from the simulation

```
handle (field: FieldBase, t: float) → None  
handle data supplied to this tracker
```

#### Parameters

- **field** (`FieldBase`) – The current state of the simulation
- **t** (`float`) – The associated time

```
initialize (field: FieldBase, info: Optional[Dict[str, Any]] = None) → float  
initialize the tracker with information about the simulation
```

#### Parameters

- **field** (`FieldBase`) – An example of the data that will be analyzed by the tracker
- **info** (`dict`) – Extra information from the simulation

**Returns** The first time the tracker needs to handle data

**Return type** `float`

```
name = 'progress'
```

```
class RuntimeTracker (max_runtime: Union[int, float, str], interval: Union[ConstantIntervals, float, int, str] =  
                      1)
```

Bases: `pde.trackers.base.TrackerBase`

Tracker interrupting the simulation once a duration has passed

#### Parameters

- **max\_runtime** (`float` or `str`) – The maximal runtime of the simulation. If the runtime is exceeded, the simulation is interrupted. Values can be either given as a number (interpreted as seconds) or as a string, which is then parsed using the function `parse_duration()`.
- **interval** – Determines how often the tracker interrupts the simulation. Simple numbers are interpreted as durations measured in the simulation time variable. Alternatively, a string using the format ‘hh:mm:ss’ can be used to give durations in real time. Finally, instances of the classes defined in `intervals` can be given for more control.

**handle** (*field*: `FieldBase`, *t*: `float`)  $\rightarrow$  `None`  
handle data supplied to this tracker

**Parameters**

- **field** (`FieldBase`) – The current state of the simulation
- **t** (`float`) – The associated time

**initialize** (*field*: `FieldBase`, *info*: `Optional[Dict[str, Any]] = None`)  $\rightarrow$  `float`

**Parameters**

- **field** (`FieldBase`) – An example of the data that will be analyzed by the tracker
- **info** (`dict`) – Extra information from the simulation

**Returns** The first time the tracker needs to handle data

**Return type** `float`

**class SteadyStateTracker** (*interval*: `Optional[Union[ConstantIntervals, float, int, str]] = None`, *atol*: `float = 1e-08`, *rtol*: `float = 1e-05`, *progress*: `bool = False`)

Bases: `pde.trackers.base.TrackerBase`

Tracker interrupting the simulation once steady state is reached

Steady state is obtained when the state does not change anymore. This is the case when the derivative is close to zero. Concretely, the current state *cur* is compared to the state *prev* at the previous time step. Convergence is assumed when `abs(prev - cur) <= dt * (atol + rtol * cur)` for all points in the state. Here, *dt* denotes the time that elapsed between the two states that are compared.

**Parameters**

- **interval** – Determines how often the tracker interrupts the simulation. Simple numbers are interpreted as durations measured in the simulation time variable. Alternatively, a string using the format ‘hh:mm:ss’ can be used to give durations in real time. Finally, instances of the classes defined in `intervals` can be given for more control. The default value *None* checks for the steady state approximately every (real) second.
- **atol** (`float`) – Absolute tolerance that must be reached to abort the simulation
- **rtol** (`float`) – Relative tolerance that must be reached to abort the simulation
- **progress** (`bool`) – Flag indicating whether the progress towards convergence is shown graphically during the simulation

**handle** (*field*: `FieldBase`, *t*: `float`)  $\rightarrow$  `None`  
handle data supplied to this tracker

**Parameters**

- **field** (`FieldBase`) – The current state of the simulation
- **t** (`float`) – The associated time

**name** = ‘`steady_state`’

**progress\_bar\_format** = ‘`Convergence: {percentage:3.0f}% | {bar} | [{elapsed}<{remaining}]`’

determines the format of the progress bar shown when *progress* = *True*

## 4.8 pde.visualization package

Functions and classes for visualizing simulations.

<code>movies</code>	Functions for creating movies of simulation results
<code>plotting</code>	Functions and classes for plotting simulation data

### 4.8.1 pde.visualization.movies module

Functions for creating movies of simulation results

<code>Movie</code>	Class for creating movies from matplotlib figures using ffmpeg
<code>movie_scalar</code>	produce a movie for a simulation of a scalar field
<code>movie_multiple</code>	produce a movie for a simulation with n components
<code>movie</code>	produce a movie by simply plotting each frame

**class** `Movie` (*filename*: *str*, *framerate*: *float* = 30, *dpi*: *float* = None, *\*\*kwargs*)

Bases: `object`

Class for creating movies from matplotlib figures using ffmpeg

**Note:** Internally, this class uses `matplotlib.animation.FFMpegWriter`. Note that the *ffmpeg* program needs to be installed in a system path, so that *matplotlib* can find it.

**Warning:** The movie is only fully written after the `save()` method has been called. To aid with this, it is best practice to use a contextmanager:

```
with Movie("output.mp4") as movie:
    movie.add_figure()
```

#### Parameters

- **filename** (*str*) – The filename where the movie is stored. The suffix of this path also determines the default movie codec.
- **framerate** (*float*) – The number of frames per second, which determines how fast the movie will appear to run.
- **dpi** (*float*) – The resolution of the resulting movie
- **\*\*kwargs** – Additional parameters are used to initialize `matplotlib.animation.FFMpegWriter`. Here, we can for instance set the bit rate of the resulting video using the *bitrate* parameter.

**add\_figure** (*fig*=None)

adds the figure *fig* as a frame to the current movie

**Parameters** **fig** (Figure) – The plot figure that is added to the movie

**classmethod** `is_available()` → *bool*

check whether the movie infrastructure is available

**Returns** True if movies can be created

**Return type** bool

**save** ()

convert the recorded images to a movie using ffmpeg

**movie** (storage: [StorageBase](#), filename: *str*, \*, progress: *bool* = True, dpi: *float* = 150, show\_time: *bool* = True, plot\_args: *Optional*[*Dict*[*str*, *Any*]] = None, movie\_args: *Optional*[*Dict*[*str*, *Any*]] = None) → None  
produce a movie by simply plotting each frame

#### Parameters

- **storage** ([StorageBase](#)) – The storage instance that contains all the data for the movie
- **filename** (*str*) – The filename to which the movie is written. The extension determines the format used.
- **progress** (*bool*) – Flag determining whether the progress of making the movie is shown.
- **dpi** (*float*) – Resolution of the movie
- **show\_time** (*bool*) – Whether to show the simulation time in the movie
- **plot\_args** (*dict*) – Additional arguments for the function plotting the state
- **movie\_args** (*dict*) – Additional arguments for [Movie](#). For example, this can be used to set the resolution (*dpi*), the framerate (*framerate*), and the bitrate (*bitrate*).

**movie\_multiple** (storage: [StorageBase](#), filename: *str*, quantities=None, scale: *Union*[*str*, *float*, *Tuple*[*float*, *float*]] = 'automatic', progress: *bool* = True) → None

produce a movie for a simulation with n components

#### Parameters

- **storage** ([StorageBase](#)) – The storage instance that contains all the data for the movie
- **filename** (*str*) – The filename to which the movie is written. The extension determines the format used.
- **quantities** – A 2d list of quantities that are shown in a rectangular arrangement. If *quantities* is a simple list, the panels will be rendered as a single row. Each panel is defined by a dictionary, where the mandatory item 'source' defines what is being shown. Here, an integer specifies the component that is extracted from the field while a function is evaluate with the full state as an input and the result is shown. Additional items in the dictionary can be 'title' (setting the title of the panel), 'scale' (defining the color range shown; these are typically two numbers defining the lower and upper bound, but if only one is given the range [0, scale] is assumed), and 'cmap' (defining the colormap being used).
- **scale** (*str*, *float*, *tuple of float*) – Flag determining how the range of the color scale is determined. In the simplest case a tuple of numbers marks the lower and upper end of the scalar values that will be shown. If only a single number is supplied, the range starts at zero and ends at the given number. Additionally, the special value 'automatic' determines the range from the range of scalar values.
- **progress** (*bool*) – Flag determining whether the progress of making the movie is shown.

**movie\_scalar** (storage: [StorageBase](#), filename: *str*, scale: *Union*[*str*, *float*, *Tuple*[*float*, *float*]] = 'automatic', extras: *Optional*[*Dict*[*str*, *Any*]] = None, progress: *bool* = True, tight: *bool* = False, show: *bool* = True) → None

produce a movie for a simulation of a scalar field

#### Parameters

- **storage** (*StorageBase*) – The storage instance that contains all the data for the movie
- **filename** (*str*) – The filename to which the movie is written. The extension determines the format used.
- **scale** (*str, float, tuple of float*) – Flag determining how the range of the color scale is determined. In the simplest case a tuple of numbers marks the lower and upper end of the scalar values that will be shown. If only a single number is supplied, the range starts at zero and ends at the given number. Additionally, the special value ‘automatic’ determines the range from the range of scalar values.
- **extras** (*dict, optional*) – Additional functions that are evaluated and shown for each time step. The key of the dictionary is used as a panel title.
- **progress** (*bool*) – Flag determining whether the progress of making the movie is shown.
- **tight** (*bool*) – Whether to call `matplotlib.pyplot.tight_layout()`. This affects the layout of all plot elements.
- **show** (*bool*) – Flag determining whether images are shown during making the movie

## 4.8.2 pde.visualization.plotting module

Functions and classes for plotting simulation data

<code>ScalarFieldPlot</code>	class managing compound plots of scalar fields
<code>plot_magnitudes</code>	plot spatially averaged quantities as a function of time
<code>plot_kymograph</code>	plots a single kymograph from stored data
<code>plot_kymographs</code>	plots kymographs for all fields stored in <i>storage</i>
<code>plot_interactive</code>	plots stored data interactively using the <code>napari</code> viewer

**class** `ScalarFieldPlot` (*fields: FieldBase, quantities=None, scale: Union[str, float, Tuple[float, float]] = 'automatic', fig=None, title: str = None, tight: bool = False, show: bool = True*)

Bases: `object`

class managing compound plots of scalar fields

### Parameters

- **fields** (*FieldBase*) – Collection of fields
- **quantities** – A 2d list of quantities that are shown in a rectangular arrangement. If *quantities* is a simple list, the panels will be rendered as a single row. Each panel is defined by a dictionary, where the mandatory item ‘source’ defines what is being shown. Here, an integer specifies the component that is extracted from the field while a function is evaluate with the full state as an input and the result is shown. Additional items in the dictionary can be ‘title’ (setting the title of the panel), ‘scale’ (defining the color range shown; these are typically two numbers defining the lower and upper bound, but if only one is given the range [0, scale] is assumed), and ‘cmap’ (defining the colormap being used).
- **scale** (*str, float, tuple of float*) – Flag determining how the range of the color scale is determined. In the simplest case a tuple of numbers marks the lower and upper end of the scalar values that will be shown. If only a single number is supplied, the range starts at zero and ends at the given number. Additionally, the special value ‘automatic’ determines the range from the range of scalar values.
- **(fig)** (*class:matplotlib.figure.Figure*): Figure to be used for plotting. If ‘None’, a new figure is created.

- **title** (*str*) – Title of the plot.
- **tight** (*bool*) – Whether to call `matplotlib.pyplot.tight_layout()`. This affects the layout of all plot elements.
- **show** (*bool*) – Flag determining whether to show a plot. If *False*, the plot is kept in the background, which can be useful if it only needs to be written to a file.

**classmethod from\_storage** (*storage*: *StorageBase*, *quantities*=*None*, *scale*: *Union*[*str*, *float*, *Tuple*[*float*, *float*]] = 'automatic', *tight*: *bool* = *False*, *show*: *bool* = *True*) → *ScalarFieldPlot*

create *ScalarFieldPlot* from storage

#### Parameters

- **storage** (*StorageBase*) – Instance of the storage class that contains the data
- **quantities** – A 2d list of quantities that are shown in a rectangular arrangement. If *quantities* is a simple list, the panels will be rendered as a single row. Each panel is defined by a dictionary, where the mandatory item 'source' defines what is being shown. Here, an integer specifies the component that is extracted from the field while a function is evaluate with the full state as an input and the result is shown. Additional items in the dictionary can be 'title' (setting the title of the panel), 'scale' (defining the color range shown; these are typically two numbers defining the lower and upper bound, but if only one is given the range [0, scale] is assumed), and 'cmap' (defining the colormap being used).
- **scale** (*str*, *float*, *tuple of float*) – Flag determining how the range of the color scale is determined. In the simplest case a tuple of numbers marks the lower and upper end of the scalar values that will be shown. If only a single number is supplied, the range starts at zero and ends at the given number. Additionally, the special value 'automatic' determines the range from the range of scalar values.
- **tight** (*bool*) – Whether to call `matplotlib.pyplot.tight_layout()`. This affects the layout of all plot elements.
- **show** (*bool*) – Flag determining whether to show a plot. If *False*, the plot is kept in the background.

**Returns** *ScalarFieldPlot*

**make\_movie** (*storage*: *StorageBase*, *filename*: *str*, *progress*: *bool* = *True*) → *None*  
make a movie from the data stored in storage

#### Parameters

- **storage** (*StorageBase*) – The storage instance that contains all the data for the movie
- **filename** (*str*) – The filename to which the movie is written. The extension determines the format used.
- **progress** (*bool*) – Flag determining whether the progress of making the movie is shown.

**savefig** (*path*: *str*, *\*\*kwargs*)  
save plot to file

#### Parameters

- **path** (*str*) – The path to the file where the image is written. The file extension determines the image format
- **\*\*kwargs** – Additional arguments are forwarded to `matplotlib.figure.Figure.savefig()`.

**update** (*fields*: [FieldBase](#), *title*: *str* = *None*) → *None*

update the plot with the given fields

#### Parameters

- **fields** – The field or field collection of which the defined quantities are shown.
- **title**(*str*, *optional*) – The title of this view. If *None*, the current title is not changed.

**extract\_field** (*fields*: [FieldBase](#), *source*: [Union](#)[*None*, *int*, *Callable*] = *None*, *check\_rank*: *int* = *None*) → [DataFieldBase](#)

Extracts a single field from a possible collection.

#### Parameters

- **fields** ([FieldBase](#)) – The field from which data is extracted
- **source** (*int* or *callable*, *optional*) – Determines how a field is extracted from *fields*. If *None*, *fields* is passed as is, assuming it is already a scalar field. This works for the simple, standard case where only a single [ScalarField](#) is treated. Alternatively, *source* can be an integer, indicating which field is extracted from an instance of [FieldCollection](#). Lastly, *source* can be a function that takes *fields* as an argument and returns the desired field.
- **check\_rank** (*int*, *optional*) – Can be given to check whether the extracted field has the correct rank (0 = [ScalarField](#), 1 = [VectorField](#), ...).

**Returns** The extracted field

**Return type** [DataFieldBase](#)

**plot\_interactive** (*storage*: [StorageBase](#), *time\_scaling*: *str* = 'exact', *viewer\_args*: [Optional](#)[[Dict](#)[*str*, *Any*]] = *None*, *\*\*kwargs*)

plots stored data interactively using the [napari](#) viewer

#### Parameters

- **storage** ([StorageBase](#)) – The storage instance that contains all the data
- **time\_scaling** (*str*) – Defines how the time axis is scaled. Possible options are “exact” (the actual time points are used), or “scaled” (the axis is scaled so that it has similar dimension to the spatial axes). Note that the spatial axes will never be scaled.
- **viewer\_args** (*dict*) – Arguments passed to [napari.viewer.Viewer](#) to affect the viewer.
- **\*\*kwargs** – Extra arguments passed to the plotting function

**plot\_kymograph** (*storage*: [StorageBase](#), *field\_index*: *int* = *None*, *scalar*: *str* = 'auto', *extract*: *str* = 'auto', *colorbar*: *bool* = *True*, *transpose*: *bool* = *False*, *\*args*, *title*: *str* = *None*, *filename*: *str* = *None*, *action*: *str* = 'auto', *ax\_style*: [Optional](#)[[Dict](#)[*str*, *Any*]] = *None*, *fig\_style*: [Optional](#)[[Dict](#)[*str*, *Any*]] = *None*, *ax*=*None*, *\*\*kwargs*) → [PlotReference](#)

plots a single kymograph from stored data

The kymograph shows line data stacked along time. Consequently, the resulting image shows space along the horizontal axis and time along the vertical axis.

#### Parameters

- **storage** ([StorageBase](#)) – The storage instance that contains all the data
- **field\_index** (*int*) – An index to choose a single field out of many in a collection stored in *storage*. This option should not be used if only a single field is stored in a collection.
- **scalar** (*str*) – The method for extracting scalars as described in [DataFieldBase.to\\_scalar\(\)](#).

- **extract** (*str*) – The method used for extracting the line data. See the docstring of the grid method `get_line_data` to find supported values.
- **colorbar** (*bool*) – Whether to show a colorbar or not
- **transpose** (*bool*) – Determines whether the transpose of the data should be plotted
- **title** (*str*) – Title of the plot. If omitted, the title might be chosen automatically.
- **filename** (*str*, *optional*) – If given, the plot is written to the specified file.
- **action** (*str*) – Decides what to do with the final figure. If the argument is set to `show`, `matplotlib.pyplot.show()` will be called to show the plot. If the value is `none`, the figure will be created, but not necessarily shown. The value `close` closes the figure, after saving it to a file when `filename` is given. The default value `auto` implies that the plot is shown if it is not a nested plot call.
- **ax\_style** (*dict*) – Dictionary with properties that will be changed on the axis after the plot has been drawn by calling `matplotlib.pyplot.setp()`. A special item in this dictionary is `use_offset`, which is a flag that can be used to control whether offsets are shown along the axes of the plot.
- **fig\_style** (*dict*) – Dictionary with properties that will be changed on the figure after the plot has been drawn by calling `matplotlib.pyplot.setp()`. For instance, using `fig_style={'dpi': 200}` increases the resolution of the figure.
- **ax** (`matplotlib.axes.Axes`) – Figure axes to be used for plotting. The special value “create” creates a new figure, while “reuse” attempts to reuse an existing figure, which is the default.
- **\*\*kwargs** – Additional keyword arguments are passed to `matplotlib.pyplot.imshow()`.

**Returns** The reference to the plot

**Return type** `PlotReference`

**plot\_kymographs** (*storage*: `StorageBase`, *scalar*: *str* = 'auto', *extract*: *str* = 'auto', *colorbar*: *bool* = `True`, *transpose*: *bool* = `False`, *resize\_fig*: *bool* = `True`, *\*args*, *title*: *str* = `None`, *constrained\_layout*: *bool* = `True`, *filename*: *str* = `None`, *action*: *str* = 'auto', *fig\_style*: *Optional*[*Dict*[*str*, *Any*]] = `None`, *fig*=`None`, *\*\*kwargs*) → *List*[`PlotReference`]

plots kymographs for all fields stored in *storage*

The kymograph shows line data stacked along time. Consequently, the resulting image shows space along the horizontal axis and time along the vertical axis.

#### Parameters

- **storage** (`StorageBase`) – The storage instance that contains all the data
- **scalar** (*str*) – The method for extracting scalars as described in `DataFieldBase.to_scalar()`.
- **extract** (*str*) – The method used for extracting the line data. See the docstring of the grid method `get_line_data` to find supported values.
- **colorbar** (*bool*) – Whether to show a colorbar or not
- **transpose** (*bool*) – Determines whether the transpose of the data should be plotted
- **resize\_fig** (*bool*) – Whether to resize the figure to adjust to the number of panels
- **title** (*str*) – Title of the plot. If omitted, the title might be chosen automatically. This is shown above all panels.

- **constrained\_layout** (*bool*) – Whether to use *constrained\_layout* in `matplotlib.pyplot.figure()` call to create a figure. This affects the layout of all plot elements. Generally, spacing might be better with this flag enabled, but it can also lead to problems when plotting multiple plots successively, e.g., when creating a movie.
- **filename** (*str*, *optional*) – If given, the figure is written to the specified file.
- **action** (*str*) – Decides what to do with the final figure. If the argument is set to *show*, `matplotlib.pyplot.show()` will be called to show the plot. If the value is *none*, the figure will be created, but not necessarily shown. The value *close* closes the figure, after saving it to a file when *filename* is given. The default value *auto* implies that the plot is shown if it is not a nested plot call.
- **fig\_style** (*dict*) – Dictionary with properties that will be changed on the figure after the plot has been drawn by calling `matplotlib.pyplot.setp()`. For instance, using `fig_style={'dpi': 200}` increases the resolution of the figure.
- **fig** (`matplotlib.figure.Figure`) – Figure that is used for plotting. If omitted, a new figure is created.
- **\*\*kwargs** – Additional keyword arguments are passed to the calls to `matplotlib.pyplot.imshow()`.

**Returns** The references to all plots

**Return type** list of *PlotReference*

**plot\_magnitudes** (*storage*: *StorageBase*, *quantities*=*None*, *\*args*, *title*: *str* = *None*, *filename*: *str* = *None*, *action*: *str* = 'auto', *ax\_style*: *Optional[Dict[str, Any]]* = *None*, *fig\_style*: *Optional[Dict[str, Any]]* = *None*, *ax*=*None*, *\*\*kwargs*) → *PlotReference*

plot spatially averaged quantities as a function of time

For scalar fields, the default is to plot the average value while the averaged norm is plotted for vector fields.

#### Parameters

- **storage** – Instance of *StorageBase* that contains the simulation data that will be plotted
- **quantities** – A 2d list of quantities that are shown in a rectangular arrangement. If *quantities* is a simple list, the panels will be rendered as a single row. Each panel is defined by a dictionary, where the mandatory item 'source' defines what is being shown. Here, an integer specifies the component that is extracted from the field while a function is evaluate with the full state as an input and the result is shown. Additional items in the dictionary can be 'title' (setting the title of the panel), 'scale' (defining the color range shown; these are typically two numbers defining the lower and upper bound, but if only one is given the range [0, scale] is assumed), and 'cmap' (defining the colormap being used).
- **title** (*str*) – Title of the plot. If omitted, the title might be chosen automatically.
- **filename** (*str*, *optional*) – If given, the plot is written to the specified file.
- **action** (*str*) – Decides what to do with the final figure. If the argument is set to *show*, `matplotlib.pyplot.show()` will be called to show the plot. If the value is *none*, the figure will be created, but not necessarily shown. The value *close* closes the figure, after saving it to a file when *filename* is given. The default value *auto* implies that the plot is shown if it is not a nested plot call.
- **ax\_style** (*dict*) – Dictionary with properties that will be changed on the axis after the plot has been drawn by calling `matplotlib.pyplot.setp()`. A special item in this dictionary is *use\_offset*, which is flag that can be used to control whether offset are shown along the axes of the plot.

- **fig\_style** (*dict*) – Dictionary with properties that will be changed on the figure after the plot has been drawn by calling `matplotlib.pyplot.setp()`. For instance, using `fig_style={'dpi': 200}` increases the resolution of the figure.
- **ax** (`matplotlib.axes.Axes`) – Figure axes to be used for plotting. The special value “create” creates a new figure, while “reuse” attempts to reuse an existing figure, which is the default.
- **\*\*kwargs** – All remaining parameters are forwarded to the `ax.plot` method

**Returns** The reference to the plot

**Return type** *PlotReference*

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